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**ANALYSIS OF STALL FLUTTER  
OF A HELICOPTER ROTOR BLADE**

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ANALYSIS OF STALL FLUTTER  
OF A HELICOPTER ROTOR BLADE

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SUMMARY

A study of rotor blade aeroelastic stability was carried out, using an analytic model of a two-dimensional airfoil undergoing dynamic stall and an elastomechanical representation including flapping, flapwise bending and torsional degrees of freedom. Results for a hovering rotor demonstrated that the models used are capable of reproducing both classical and stall flutter. The minimum rotor speed for the occurrence of stall flutter in hover was found to be determined from coupling between torsion and flapping. Instabilities analogous to both classical and stall flutter were found to occur in forward flight. However, the large stall-related torsional oscillations which commonly limit aircraft forward speed appear to be the response to rapid changes in aerodynamic moment which accompany stall and unstall, rather than the result of an aeroelastic instability. The severity of stall-related instabilities and response was found to depend to some extent on linear stability. Increasing linear stability lessens the susceptibility to stall flutter and reduces the magnitude of the torsional response to stall and unstall.

## INTRODUCTION

Aeroelastic stability of a helicopter rotor blade is a multifaceted problem because of the extreme variations of the aerodynamic environment within the flight envelope of the aircraft. In hovering flight, a blade can undergo classical binary flutter (Ref. 1) or stall flutter (Ref. 2). In forward flight, the linear instability experienced by systems with periodically varying parameters can occur (Ref. 3). While these types of instability are not normally encountered with blades of current design, due to the relatively low disc loading and weak coupling of translational and rotational degrees of freedom, they are certainly not precluded from new designs, particularly those intended to extend present performance capabilities. Of immediate concern, however, in both design and operation, is the occurrence of large-amplitude torsional oscillations and excessive control-linkage loads associated with blade stall on the retreating side of the rotor disc at high forward speed or gross weight, effectively limiting aircraft performance. This problem has prompted a number of recent studies of dynamic stall and the effects of stall on blade dynamics (Refs. 4-8).

While stall has been identified as a causal element of the problem, the nonlinearity of the stall process, coupled with the unsteady aerodynamic environment, has precluded an analysis to the depth required to gain a thorough understanding of the mechanisms involved. In particular, it has not been clear whether the blade undergoes a true aeroelastic instability, a simple forced response, or some hybrid phenomenon which takes on the character of one or the other extreme, depending on flight conditions and blade vibrational characteristics.

Stall flutter for axial flight is amenable to analysis by empirical methods similar to those developed for analyzing stall flutter in cascades (Ref. 9). The flutter mechanism for that case has been identified as deriving from the extraction of energy from the free stream by the periodic variation of the aerodynamic moment. Analogous methods applied to the forward-flight problem (Refs. 10 and 11) have been inconclusive, however, the primary difficulty possibly being in applying empirical methods without a clear definition of the underlying mechanism of the problem.

A method was recently developed for analyzing dynamic stall of an airfoil undergoing arbitrary pitching and plunging motions which provides an ideal tool for analyzing the stall problem in forward flight. The method, which is described in detail in Ref. 7, employs models for each of

the basic flow elements contributing to the unsteady stall of a two-dimensional airfoil. Calculations of the loading during transient and sinusoidal pitching motions are in good qualitative agreement with measured loads. Dynamic overshoot, or lift in excess of the maximum static value, as well as unstable moment variation, are in clear evidence in the computed results.

This study was directed to analyzing the aeroelastic stability of a helicopter rotor, particularly as it relates to stall, using the method of Ref. 7 to compute aerodynamic loading. The representation of the elastomechanical system includes flapping and flapwise bending degrees of freedom as well as torsion. A listing of the computer program used to perform the calculations is given in Appendix A.

# SYMBOLS

$b$	blade semichord, m
$\bar{C}_L$	mean lift coefficient, ratio of time average of $l$ to $\rho \Omega^2 R^2 b$
$C_l$	lift coefficient, $C_l = c_l / (\rho U^2 b)$
$C_m \text{ } c/4$	moment coefficient referred to quarterchord, $C_m \text{ } c/4 = m_{c/4} / (2 \rho U^2 b^2)$
$c$	blade chord, m
$f_\theta$	mode shape of first uncoupled torsional mode, unit tip deflection
$f_\phi$	mode shape of first uncoupled flapwise bending mode, unit tip deflection
$h_\beta$	tip deflection due to flapping, semichords
$h_\phi$	tip deflection due to bending, semichords
$h_i$	translational coordinates of 2-D system ( $i = 1, 2$ ), semichords
$I_o$	moment of inertia of 2-D system about pitch axis, kg - m
$I'_\theta$	blade moment of inertia about elastic axis per unit span, kg - m
$k_i$	translational spring stiffnesses of 2-D system ( $i = 1, 2$ ), N/m <sup>2</sup>
$k_\theta$	torsional spring stiffness of 2-D system, N/rad
$l$	lift per unit span at aerodynamic reference radius, N/m
$l_{s_i}$	offsets of springs from pitch axis of 2-D system ( $i = 1, 2$ ), m
$M_b$	total blade mass, kg
$m$	blade mass per unit span, kg/m
$m \text{ } c/4$	aerodynamic moment per unit span at aerodynamic reference radius, N

$m_1$	masses of 2-D system, kg/m
$R$	rotor radius, m
$r_o$	inner radius of blade lifting surface, m
$r_R$	aerodynamic reference radius, m
$U$	instantaneous free-stream speed at aerodynamic reference section, m/sec
$U_o$	reference speed, $U_o = \Omega r_R$ , m/sec
$x_m$	distance aft of elastic axis of blade section mass center, m
$\bar{x}$	distance aft of pitch axis of mass center of $m_1$ , m
$z_\beta$	generalized coordinate of 2-D system, equivalent to $h_\beta$ , semichords
$z_\phi$	generalized coordinate of 2-D system, equivalent to $h_\phi$ , semichords
$\alpha$	angle of attack, deg
$\delta$	flapping hinge offset, m
$\theta_o$	collective pitch angle, deg or rad
$\theta_1$	blade tip torsional deflection, rad
$\tilde{\theta}$	angle of zero restraint of 2-D system torsion spring, rad
$\mu$	advance ratio, ratio of forward speed to $\Omega R$
$\rho$	free-stream density, kg/m <sup>3</sup>
$\tau$	dimensionless time, $\tau = U_o t/b$
$\psi$	blade azimuth angle measured from downwind direction, deg or rad
$\Omega$	rotor rotational speed, rad/sec
$\Omega^*$	dimensionless rotor speed, $\Omega^* = \Omega R/(\omega_{\theta_o} b)$
$\omega_f$	flutter frequency, rad/sec

$\omega_{\theta_0}$  frequency of first uncoupled, nonrotating  
torsion mode, rad/sec

$\omega_{\phi_0}$  frequency of first uncoupled, nonrotating  
flapwise bending mode, rad/sec



## PROBLEM FORMULATION

### Aerodynamic Loading

In the flutter analysis, only leading-edge stall was considered, so the following relates specifically only to that type, even though the basic method can treat trailing-edge stall as well. When the airfoil is not stalled, the flow elements represented are (see Figure 1a): (1) the laminar boundary layer from the stagnation point to separation near the leading-edge, (2) the small leading-edge separation bubble; and, (3) a potential flow, including a vortex wake generated by the variation with time of the circulation about the airfoil. When the airfoil is stalled, as indicated in Figure 1b, the flow elements are: (1) the laminar boundary layer, (2) a dead-air region extending from the separation point to the pressure recovery point; and, (3) a potential flow external to the airfoil and dead-air region, again including a vortex wake. The analytic representations of these elements are described briefly below. Details are given in Ref. 7.

Potential Flow.—Given the airfoil section characteristics and motions, together with the distribution of pressure in the dead-air region if the airfoil is stalled, the flow and pressure over the airfoil must be determined to compute the integrated load and analyze the boundary layer. The problem was formulated by imposing linearized boundary conditions of flow tangency and pressure, using a perturbation velocity potential derived from source and vortex distributions. The resulting coupled set of singular integral equations is solved by casting the singularity distributions in series form and solving for the unknown coefficients by imposing boundary conditions at prescribed points.

Boundary Layer.—Because the relative importance of the individual elements of the boundary layer flow as they affect dynamic stall could not be established in advance, the representation in Ref. 7 was made as general as possible. The method of finite differences for unsteady flows with variable step size in both streamwise and normal directions, was employed, with the error in each finite-difference approximation the order of the square of the step size. It was determined from preliminary calculations performed for this study that, at least for leading-edge stall, results are virtually unaffected by assuming quasi-steady flow in the boundary layer. That assumption was therefore employed for all flutter computations, to take advantage

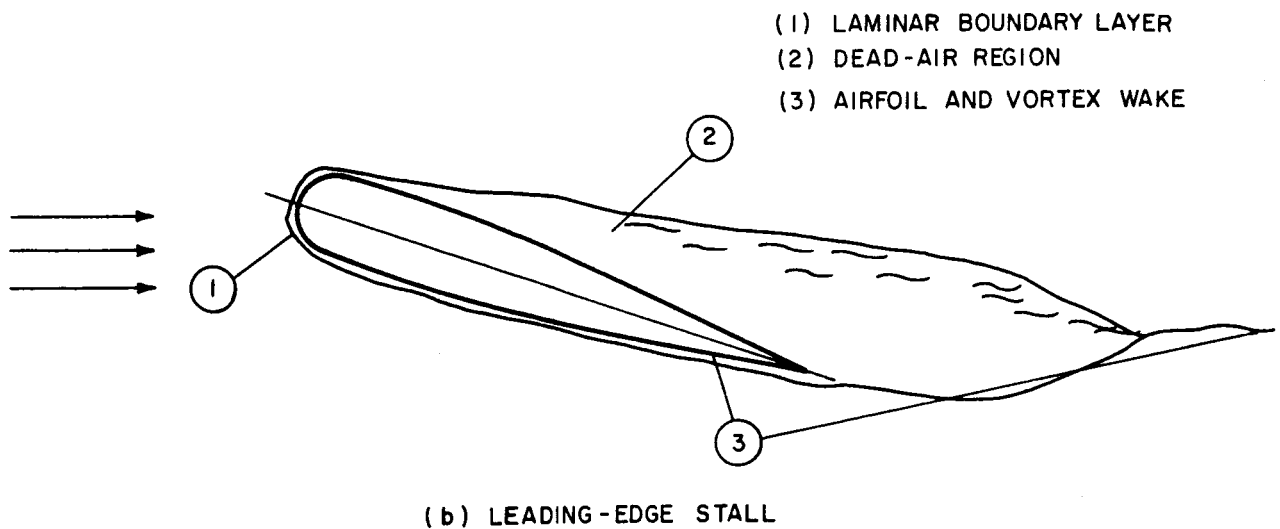
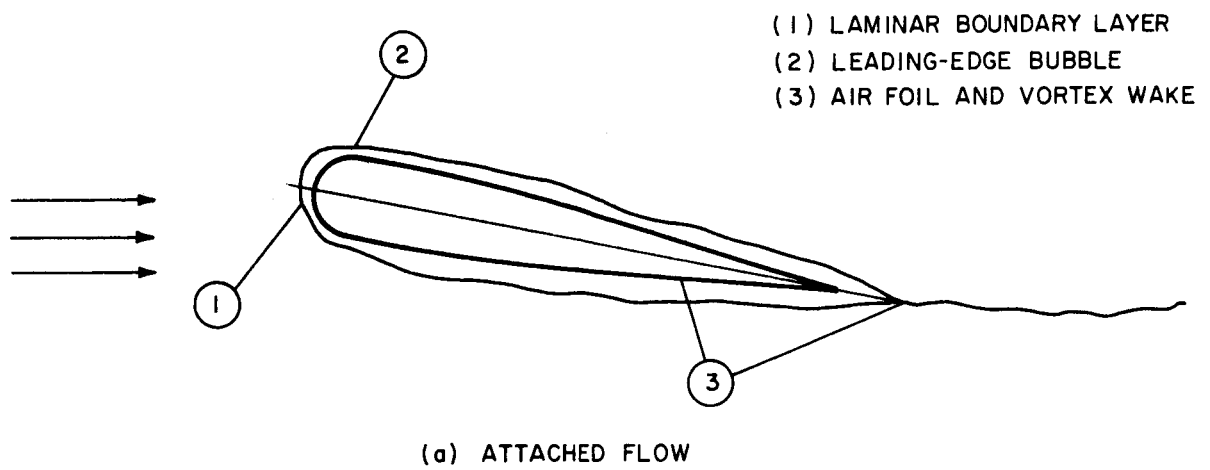


Figure 1 FLOW ELEMENTS

of the resulting substantial savings in computer storage requirements and computing time.

Dead-Air Region.—The function of the model of the dead-air region is to define the streamwise distribution of pressure in that region, given the locations of the separation and recovery points and the pressure at the recovery point. The dead-air region is assumed to consist of a laminar constant-pressure free shear layer from separation to transition, a turbulent constant-pressure mixing region, and a turbulent pressure-recovery region. The laminar shear layer is analyzed by the method of Ref. 12, assuming quasi-steady flow. The turbulent mixing and pressure-recovery regions are analyzed using the steady-flow momentum integral and first moment equations. Profile parameters in these regions are assumed to be universal functions of a dimensionless streamwise coordinate, with those functions derived from an exact viscous-inviscid interaction calculation. Matching of approximate solutions for the mixing and pressure-recovery regions at their interface completes the analysis.

Leading-Edge Bubble.—The leading-edge bubble on an unstalled airfoil is analyzed using the same basic relations employed for the dead-air region. Given the boundary-layer parameters at separation, the length of the bubble and the amount of pressure rise possible, for that length, in the pressure recovery region, are computed. That pressure rise is compared with the rise in pressure in the potential flow over the length of the bubble. If the latter is greater than the former, the bubble is assumed to have burst, and the stall process is initiated.

Loading Calculation Procedure.—Calculations proceed by forward integration in time, using the blade motions derived by integrating the equations of motion of the elastomechanical system. If, at a given instant, the airfoil is not stalled, the potential flow is computed, and the boundary layer and leading-edge bubble are analyzed to check for bubble bursting. If the airfoil is stalled, the pressure distribution in the dead-air region is computed, the potential flow evaluated, and the boundary layer is analyzed to locate the separation point. The last two steps are repeated iteratively until assumed and computed separation points agree. Rate of growth of the dead-air region is determined from an estimate of the rate of fluid entrainment derived from the potential-flow solution. Unstall is determined by first postulating its occurrence and analyzing the leading-edge bubble which would then form to ascertain whether that event did in fact occur.

During unstart, the dead-air region is washed off the airfoil at the free-stream speed.

### Elastomechanical Representation

The equations of motion for a rotor blade with flapping, flapwise bending and torsional degrees of freedom can be written in the form (Ref. 3)

$$\begin{aligned} \frac{d^2 h_\beta}{d\tau^2} + \frac{R}{b} \frac{M_{\beta\theta}}{M_{\beta\beta}} \frac{d^2 \theta_1}{d\tau^2} + \bar{\omega}_\beta^2 h_\beta - \frac{R}{b} \bar{\Omega}^2 \frac{T_{\beta\theta}}{M_{\beta\beta}} \theta_1 \\ = \frac{Rb}{U_o^2} \frac{F_\beta}{M_{\beta\beta}} \end{aligned}$$

$$\begin{aligned} \frac{d^2 h_\phi}{d\tau^2} + \frac{M_{\phi\theta}}{b M_{\phi\phi}} \frac{d^2 \theta_1}{d\tau^2} + \bar{\omega}_\phi^2 h_\phi - \bar{\Omega}^2 \frac{T_{\phi\theta}}{M_{\phi\phi}} \theta_1 \\ = \frac{b}{U_o^2} \frac{F_\phi}{M_{\phi\phi}} \end{aligned}$$

$$\begin{aligned} \frac{d^2 \theta_1}{d\tau^2} + \frac{b}{R} \frac{M_{\beta\theta}}{M_{\theta\theta}} \frac{d^2 h_\beta}{d\tau^2} + \frac{b M_{\phi\theta}}{M_{\theta\theta}} \frac{d^2 h_\phi}{d\tau^2} + \bar{\omega}_\theta^2 \theta_1 \\ - \frac{b}{R} \bar{\Omega}^2 \frac{T_{\beta\theta}}{M_{\theta\theta}} h_\beta - \bar{\Omega}^2 \frac{b T_{\phi\theta}}{M_{\theta\theta}} h_\phi \\ = \frac{b^2}{U_o^2} \frac{F_\theta}{M_{\theta\theta}} \end{aligned}$$

where  $h_\beta$  and  $h_\phi$  are tip displacements due to flapping and bending, respectively, in semichords,  $\theta_1$  is torsional displacement at the blade tip and the frequencies\* are the following functions of rotational speed:

$$\bar{\omega}_\beta^2 = - \bar{\Omega}^2 \frac{T_{\beta\beta}}{M_{\beta\beta}}, \quad \bar{\omega}_\phi^2 = \bar{\omega}_{\phi_0}^2 - \bar{\Omega}^2 \frac{T_{\phi\phi}}{M_{\phi\phi}},$$

$$\bar{\omega}_\theta^2 = \bar{\omega}_{\theta_0}^2 - \bar{\Omega}^2 \frac{T_{\theta\theta}}{M_{\theta\theta}}$$

The inertial and centrifugal-force coefficients are given by

$$M_{\beta\beta} = \int_\delta^R (r + \delta)^2 m dr, \quad M_{\phi\phi} = \int_\delta^R m f_\phi^2 dr,$$

$$M_{\theta\theta} = \int_\delta^R I'_\theta f_\theta^2 dr,$$

$$M_{\beta\theta} = - \int_\delta^R m x_m (r - \delta) f_\theta dr,$$

$$M_{\phi\theta} = - \int_\delta^R m x_m f_\phi f_\theta dr,$$

$$T_{\beta\beta} = - \int_\delta^R r (r - \delta) m dr,$$

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\*Barred quantities are dimensionless frequencies,  $U_0/b$  being reference frequency; e.g.,  $\bar{\Omega} = \Omega b/U_0$ .

$$T_{\phi\phi} = - \int_{\delta}^R f_{\phi}'^2 \left\{ \int_r^R r_1 m(r_1) dr_1 \right\} dr,$$

$$T_{\theta\theta} = - M_{\theta\theta}, \quad T_{\beta\theta} = - M_{\beta\theta},$$

$$T_{\phi\theta} = \int_{\delta}^R (r - \delta) f_{\phi}' f_{\theta} m x_m dr$$

The complexity of the aerodynamic representation precludes evaluation of the generalized forces  $F_{\beta}$ ,  $F_{\phi}$  and  $F_{\theta}$  by the usual strip approximation. It was felt essential, however, to retain both translational degrees of freedom in the investigation of the forward-flight problem, so a simple two-dimensional model of the dynamics could not be used. Therefore, a two-dimensional airfoil suspended in such a way as to have three degrees of freedom was analyzed. Inertial and stiffness parameters were assigned to make the coupled natural frequencies of the two-dimensional system match those of the rotor blade.

The system analyzed is shown schematically in Figure 2. The matching of the two-dimensional system with the blade dynamics proceeds as follows. Three generalized coordinates are first defined to correspond to those of the blade. Clearly, angular displacement  $\theta_1$  should correspond to blade torsional displacement at the blade tip. The counterparts of flapping and bending,  $Z_{\beta}$  and  $Z_{\phi}$ , respectively, are defined by

$$Z_{\beta} = A_1 h_1 + B h_2, \quad Z_{\phi} = A_2 h_1 - B h_2$$

$$\text{where } A_1 = \frac{\bar{\omega}_{\beta}^2 - \bar{\omega}_2^2}{\bar{\omega}_{\phi}^2 - \bar{\omega}_{\beta}^2}, \quad A_2 = \frac{\bar{\omega}_2^2 - \bar{\omega}_{\phi}^2}{\bar{\omega}_{\phi}^2 - \bar{\omega}_{\beta}^2},$$

$$B = \frac{(\bar{\omega}_2^2 - \bar{\omega}_{\phi}^2)(\bar{\omega}_2^2 - \bar{\omega}_{\beta}^2)}{(\bar{\omega}_{\phi}^2 - \bar{\omega}_{\beta}^2) \bar{\omega}_2^2} \quad (1)$$

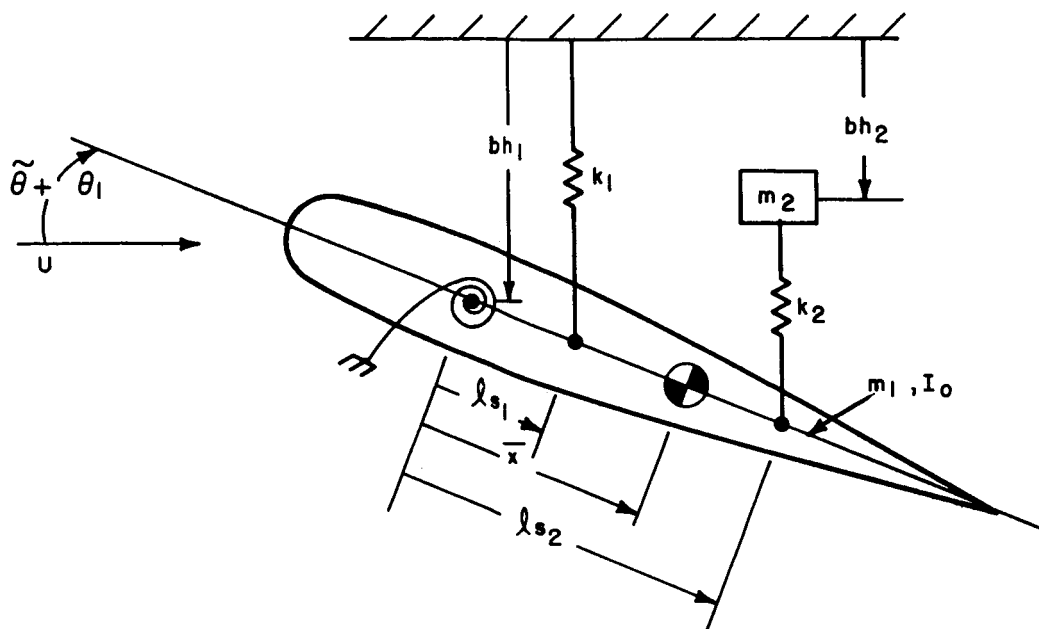


Figure 2 TWO-DIMENSIONAL ELASTOMECHANICAL SYSTEM

$$\text{and } \bar{\omega}_1^2 = (k_1/m_1)(b/U_0)^2, \quad i = 1, 2.$$

With the above definitions,  $Z_\beta + Z_\phi = -h_1$ , to give the correct translational correspondence. It can further be shown that the uncoupled natural frequencies of the two-dimensional system match those of the blade, provided

$$\left( \frac{k_\theta + k_1 l_{s1}^2 + k_2 l_{s2}^2}{I_0} \right) \left( \frac{b}{U_0} \right)^2 = \bar{\omega}_\theta^2$$

while  $\bar{\omega}_1^2$  and  $\bar{\omega}_2^2$  satisfy

$$\bar{\omega}_1^2 \bar{\omega}_2^2 = \bar{\omega}_\phi^2 \bar{\omega}_\beta^2,$$

$$\bar{\omega}_1^2 + (1 + m_2/m_1) \bar{\omega}_2^2 = \bar{\omega}_\phi^2 + \bar{\omega}_\beta^2 \quad (2)$$

By comparing the generalized masses of the two systems, it follows that

$$m_1 b^2/I_0 = -A_1 M_{\beta\beta} b^2/(M_{\theta\theta} R^2)$$

$$A_2/A_1 = M_{\beta\beta} / (M_{\phi\phi} R^2) \equiv \lambda_m$$

The last relation, together with Eqs. (1) and (2), fixes  $m_2/m_1$ :

$$m_2/m_1 = \frac{(1 + \lambda_m)(\bar{\omega}_\phi^4 + \lambda_m \bar{\omega}_\beta^4)}{(\lambda_m \bar{\omega}_\beta^2 + \bar{\omega}_\phi^2)^2} - 1$$

Equating the corresponding coefficients of the characteristic equations of the two systems provides three additional relations, which can be solved for the coupling parameters  $\bar{x}$ ,  $l_{s1}$ ,  $l_{s2}$ . That calculation is outlined in Appendix B.



To complete the matching, quasi-steady approximations to the damping terms of the flapping equations are equated with the result that

$$m_1 R/(-A_1) = 4 \frac{r_R}{R} \frac{M_{\beta\beta}}{R^2 [1 - (r_o/R)^4]}$$

$$U/U_o = 1 + \frac{4}{3} \left[ \frac{1 - (r_o/R)^2}{1 - (r_o/R)^4} \right] \mu \sin \psi$$

where  $\Omega r_R = U_o$ . The aerodynamic reference radius  $r_R$  was selected to be  $.75R$ .

The angle of zero restraint in torsion was varied periodically to approximate the effects of cyclic pitch variation in forward flight, according to the formula

$$\tilde{\theta} = \theta_o [1 - 2 (R/r_R) \mu \sin \psi]$$

This variation gives nominally constant lift.

The equations of motion were solved by integrating analytically, using linear extrapolations to approximate the variation of lift and aerodynamic moment over the interval of integration. This scheme was found to give satisfactory results, provided the time interval of integration is no longer than about one fifth of the period of the coupled mode having the highest natural frequency.

## RESULTS OF COMPUTATIONS

### Configurations Analyzed

Vibrational and aerodynamic characteristics of the blade analyzed were selected to correspond to those of the model rotor blade described in Ref. 2. That blade is untwisted, of constant chord, with offset flapping hinge. Pertinent dimensionless parameters of the model blade are listed in Table 1.

TABLE 1  
BLADE PARAMETERS FOR NOMINAL CONFIGURATION

<u>Parameter</u>	<u>Value</u>
$b/R$	.0435
$\delta/R$	.0543
$r_o/R$	.174
$\omega_{\theta o}/\omega_{\phi o}$	3.69
$\rho R b^2/M_b$	.00431
$x_m/b$	.216
$m R/M_b$	1.055
$I'_{\theta}/M_b R$	$3.51 \times 10^{-4}$

Two elastomechanical configurations in addition to the nominal one were analyzed. One of these had  $\omega_{\theta o}/\omega_{\phi o} = 2.5$ , with all other parameters as listed in Table 1. The third configuration had  $x_m/b = .108$ , with the remaining parameters as listed in Table 1.

The bending mode shape, which was computed by a finite-element method, was found not to vary appreciably over the range of rotational speeds of interest. The mode shape for  $\omega_{\phi o}/\Omega = 1.26$ , which is plotted in Figure 3, was used for all computations. The torsional mode shape for the nonrotating blade, also shown in Figure 3, was used to evaluate torsional inertia parameters.

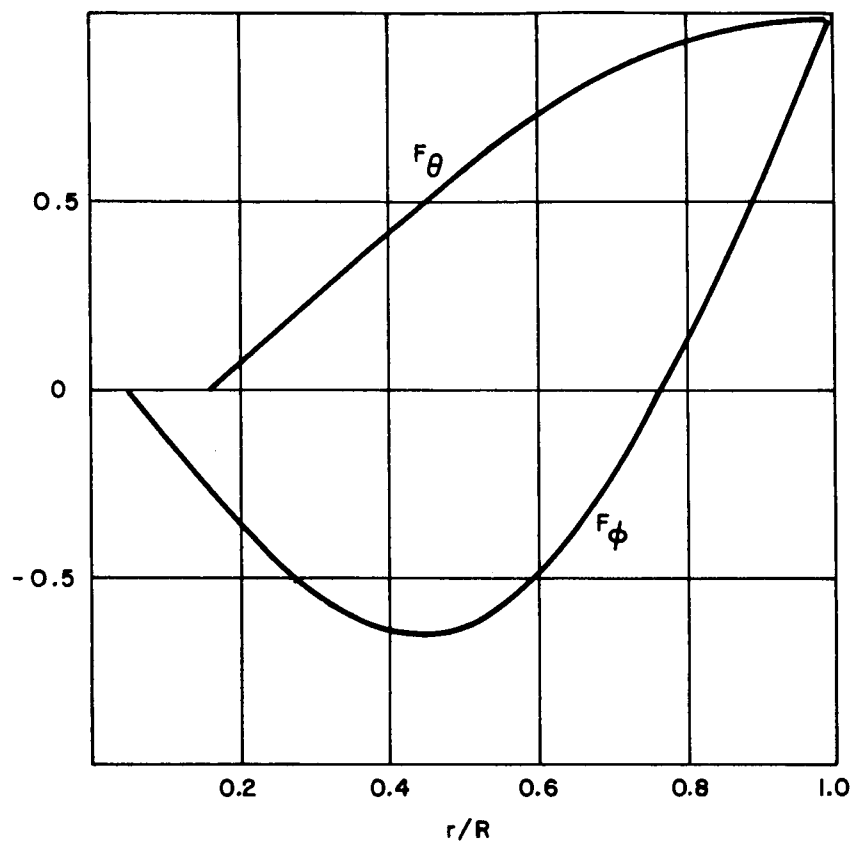


Figure 3 BENDING AND TORSION MODE SHAPES

The test blade had a NACA 23012 section. The variation of static lift and moment coefficients with angle of attack for this section were computed from a series of transient pitch calculations, and are shown in Figure 4, together with the measured section characteristics, from Ref. 13. The aerodynamic model is seen to give nearly the correct maximum lift, but at a slightly lower angle of attack, and, as indicated from the variation of  $C_{m,c}/4$ , the computed center of pressure is somewhat further aft than that of the actual airfoil section below the stall angle.

### Stability in Hover

Initial calculations were performed for hovering flight, with the nominal configuration, to allow a direct comparison with the test results of Ref. 2. First, rotor speed was varied parametrically, with the collective pitch at a value well below the stall incidence. A classical bending-torsion instability was encountered at  $\Omega^* \equiv \Omega R / (\omega_{\theta_0} b) = 5.3$  with  $\omega_f / \omega_{\theta_0} = .803$ . The variation of bending, flapping, and torsional displacements with azimuth angle at flutter onset are shown in Figure 5. By way of comparison, tests (Ref. 2) yielded classical flutter at about  $\Omega^* = 7.1$  with  $\omega_f / \omega_{\theta_0} = .72$ .

It should be noted that since the system stability was analyzed by direct simulation, a precise point of linear instability was not computed. The values of  $\Omega^*$  at onset of a linear instability, both for hover and forward flight, were obtained by successively increasing or decreasing rotor speed, in small steps, until the transient response changed from convergent to divergent, or visa versa. The maximum error in the value of flutter speed, for the results presented here, is estimated to be about three percent.

Susceptibility of the system to stall flutter was investigated next. It was found that a torsional limit cycle, at approximately the highest coupled natural frequency of the system, could be triggered for  $\Omega^*$  as low as 3.4. Computed blade motions for stall flutter at  $\Omega^*$  of 3.5 are shown in Figure 6.

For  $\Omega^*$  below 3.4, a limit cycle could not be set up, regardless of the initial conditions or the collective pitch angle. Severe oscillations involving repeated stall and unstall could be made to occur by imposing a large initial bending deflection. However, the flapping response modulated the torsional response, and caused continuous stall and/or unstall of the blade over a significant portion of

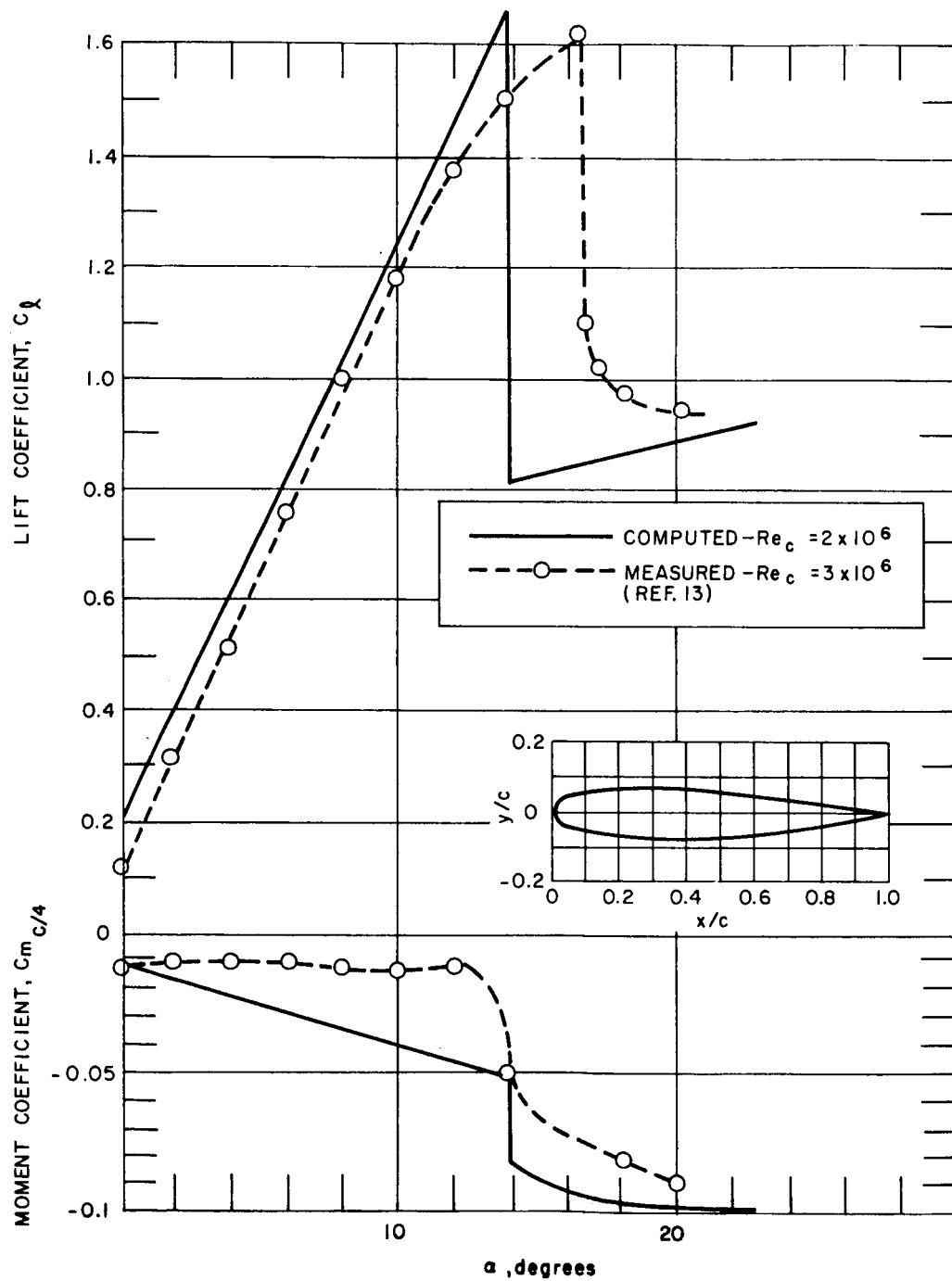


Figure 4 AIRFOIL SECTION CHARACTERISTICS FOR NACA 23012

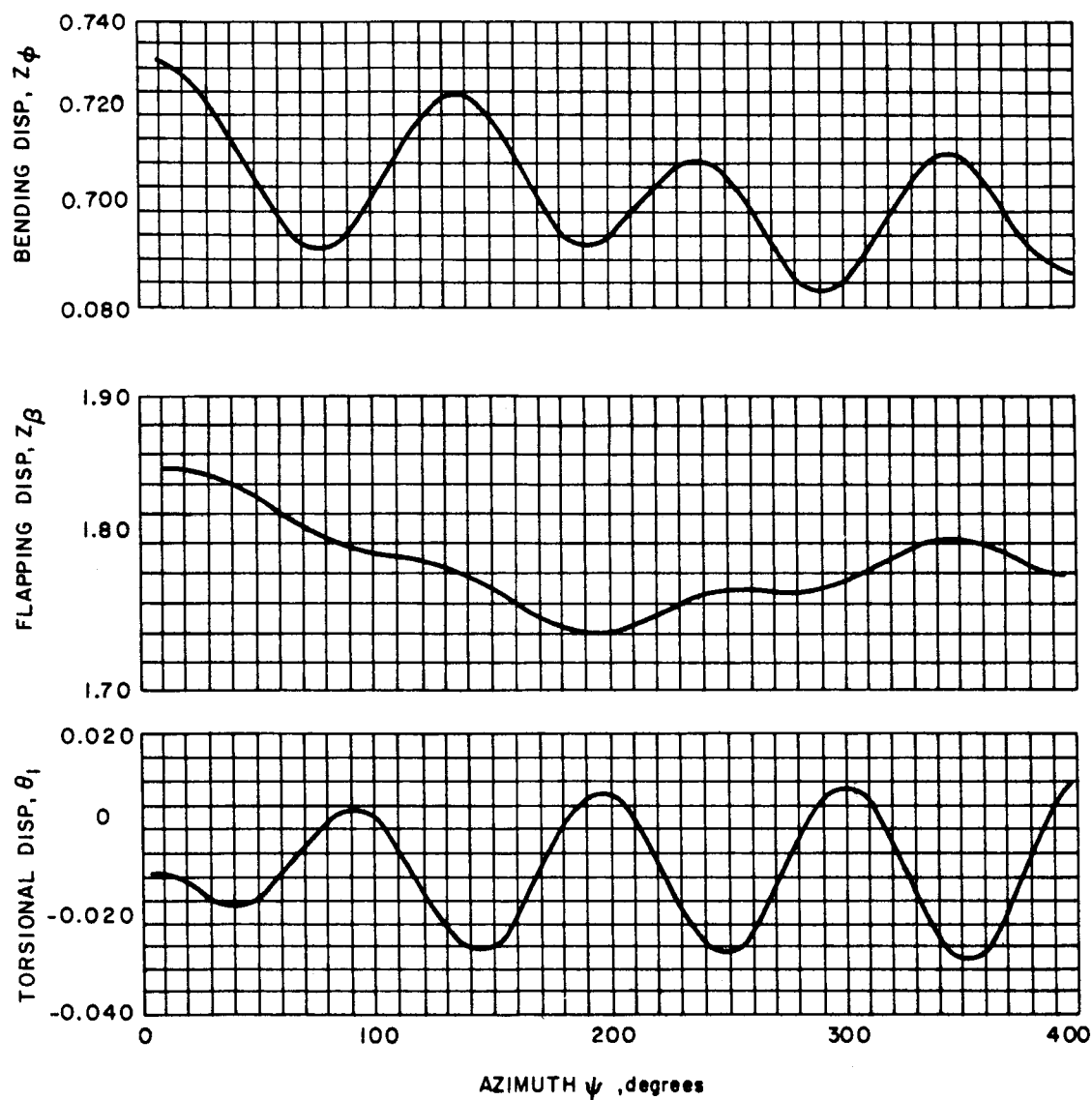


Figure 5 DISPLACEMENT TIME HISTORIES AT CLASSICAL FLUTTER ONSET  
 $\Omega^* = 5.3$ ,  $\theta_0 = 11$  deg,  $\mu = 0$

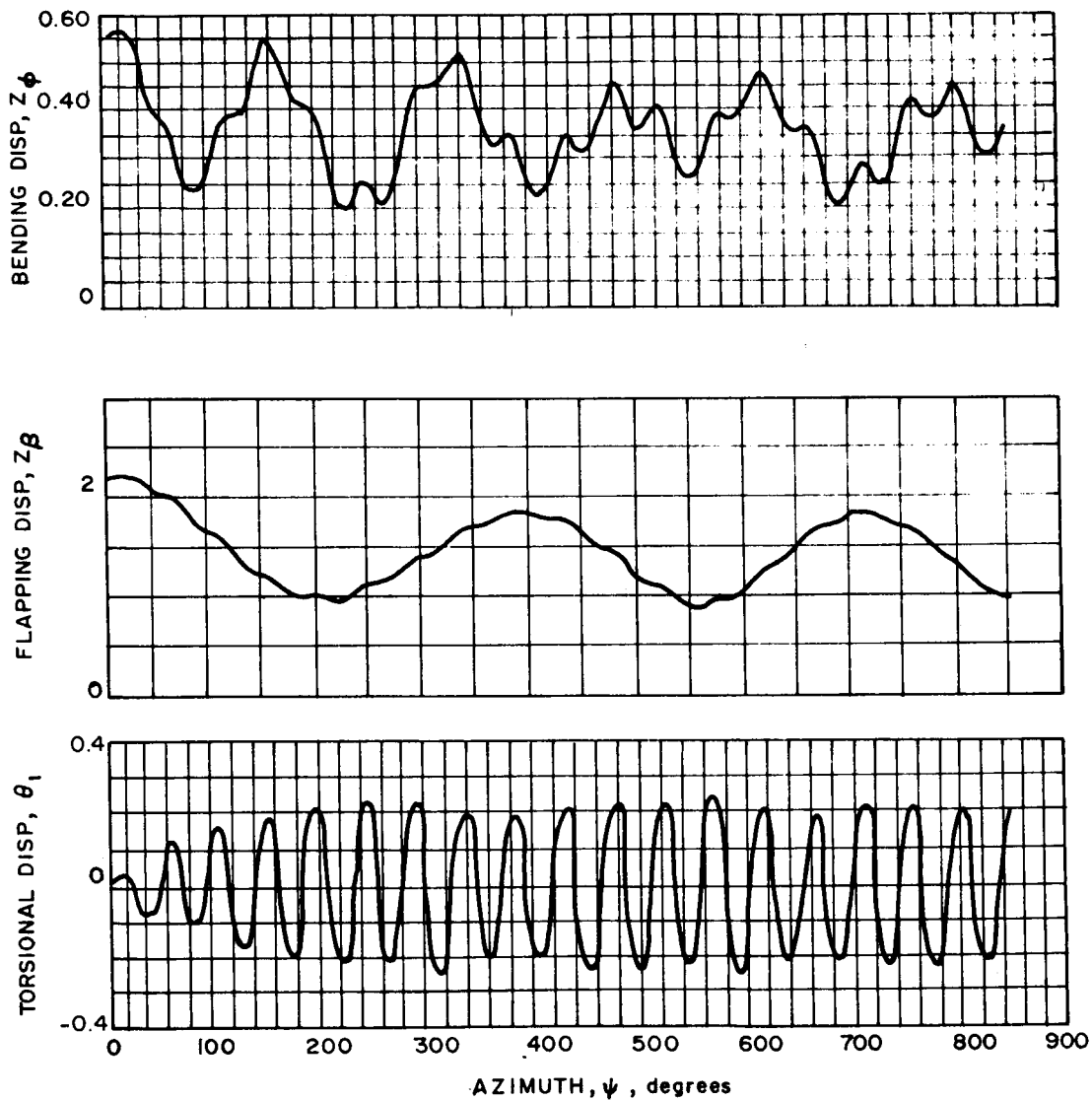


Figure 6 DISPLACEMENT TIME HISTORIES FOR STALL FLUTTER  
 $\Omega^* = 3.5, \theta_0 = 15.0 \text{ deg}, \mu = 0$

a revolution, due to the large plunging rate generated by the flapping motion. An example of this occurrence is shown in Figure 7. Thus, while stall flutter involves only the rotational degree of freedom, the results obtained indicate that the minimum speed for its occurrence is determined by coupling with a translational degree of freedom.

Results for the hovering case are summarized in Figure 8, which compares computed and measured flutter speed and frequency, plotted against collective pitch angle. No upper limit in collective pitch angle for the occurrence of stall flutter was calculated, since that limit would depend strongly on initial conditions, and so would be arbitrary. Quantitative differences between the computed and measured stability boundaries of Figure 8 can be attributed in large part to the use of a two-dimensional aerodynamic model, which cannot precisely reproduce the aerodynamic coupling between the rotational and translational degrees of freedom.

From the basic similarity of the computed and measured stability boundaries and the character of the computed instabilities (Figures 5 and 6) it can be concluded that the aerodynamic and dynamic models formulated are capable of reproducing both classical and stall flutter as experienced by a rotor blade, and so can be employed to investigate the forward-flight problem.

### Stability in Forward Flight

The nominal configuration was analyzed next for an advance ratio of .1. Computations were carried out in the same sequence as for hovering. First, the rotational speed at which classical flutter occurs was determined. Then, stall-related instabilities were investigated.

A linear bending-torsion instability of the Floquet type (Ref. 14) was encountered at  $\Omega^* = 5.2$ . Blade motions as a function of azimuth angle at flutter onset are shown in Figure 9. The torsional and bending displacements are seen to display the aperiodic character typical of this type of instability. The flapping motion is the steady-state response to the cyclic pitch variation.

An instability analogous to stall flutter in hover was found to occur for  $\Omega^*$  as low as about 4.4, with collective pitch angle greater than 12 deg. Blade motions for

$\Omega^* = 4.8$  are shown in Figure 10. The torsional displacement time history, while not strictly periodic, is nonetheless



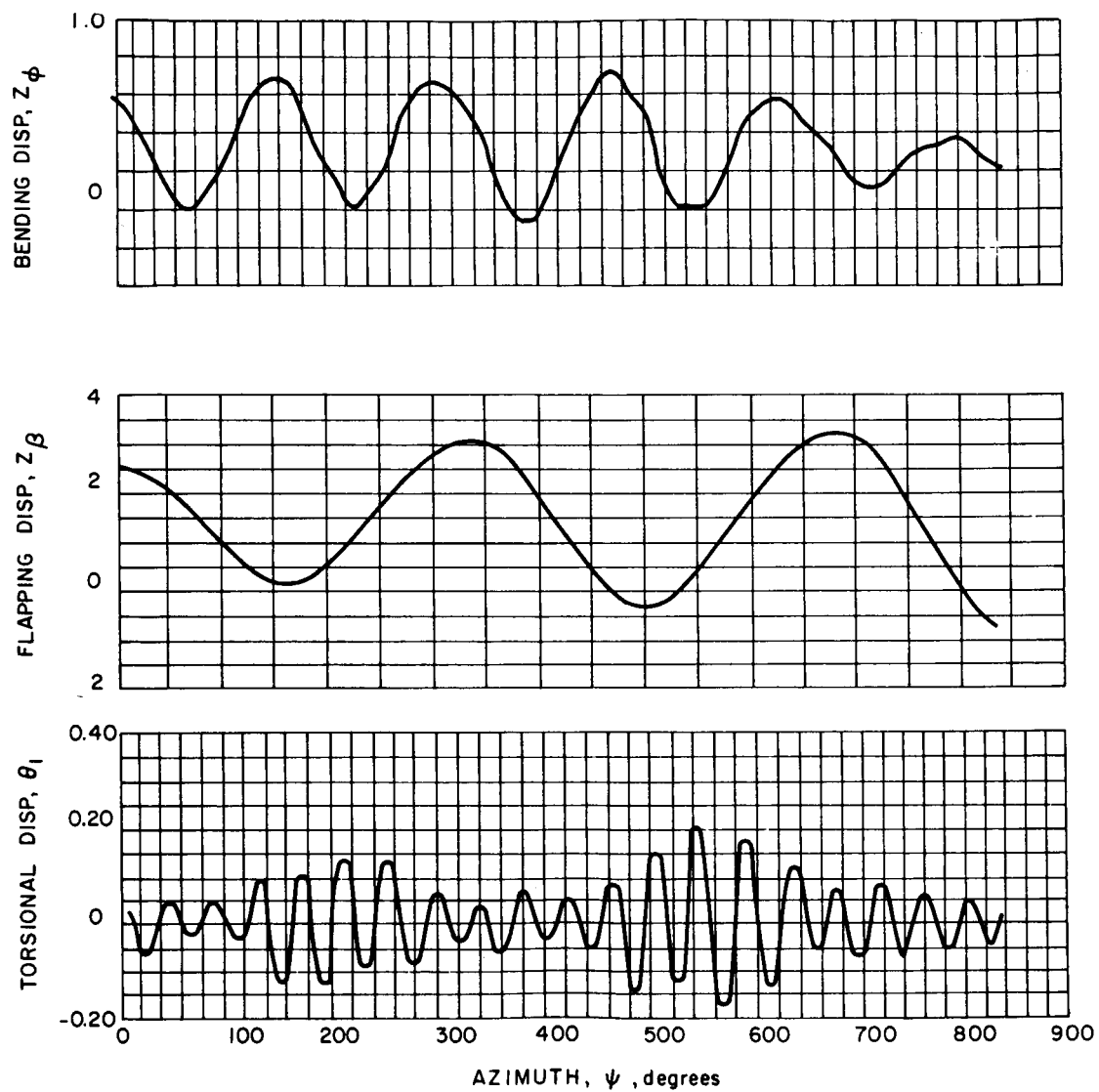


Figure 7 BLADE RESPONSE BELOW STALL FLUTTER BOUNDARY  
 $\Omega^* = 3.1$ ,  $\theta_0 = 15.0$  deg,  $\mu = 0$

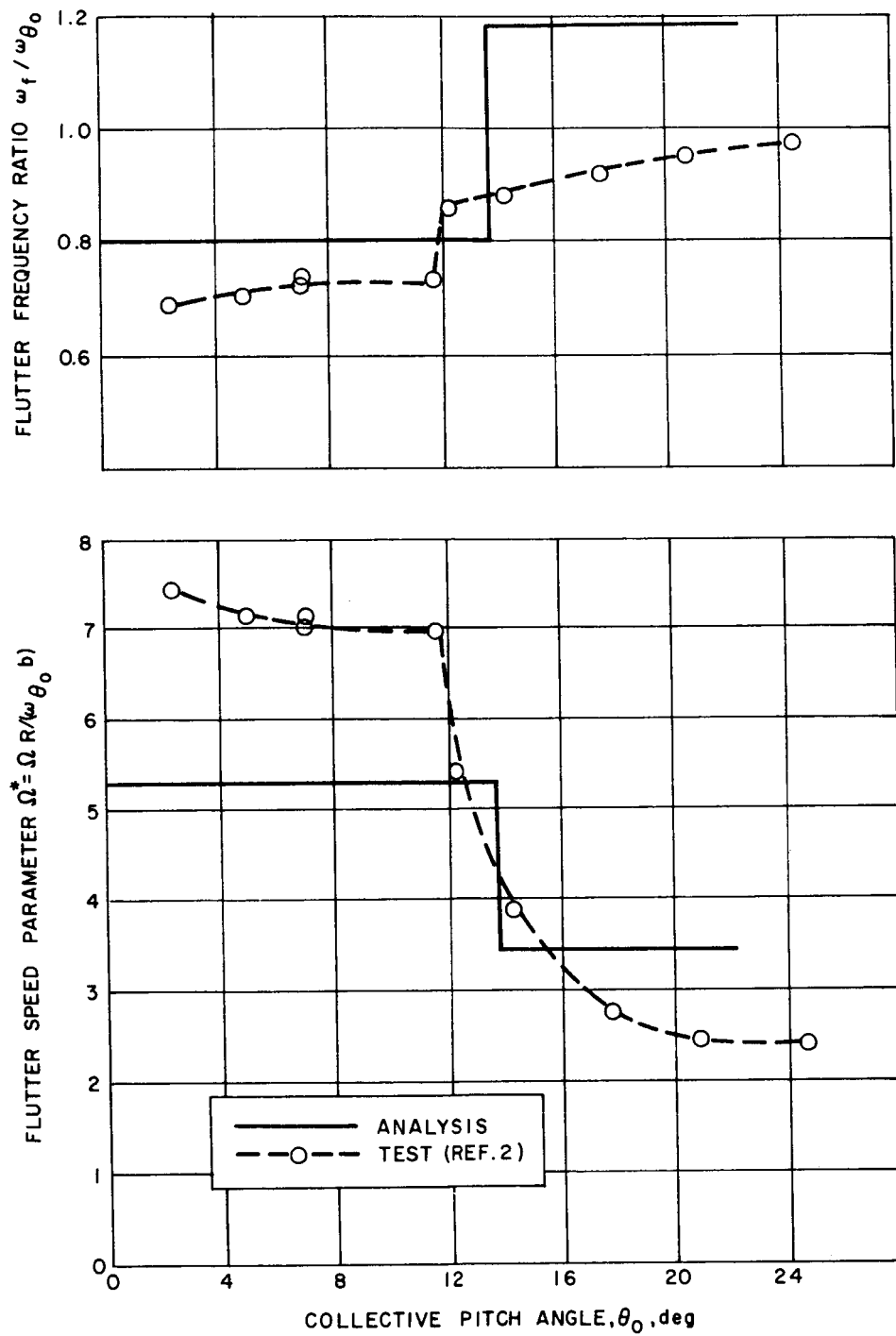


Figure 8 FLUTTER SPEED AND FREQUENCY VARIATION WITH COLLECTIVE PITCH ANGLE FOR A HOVERING ROTOR

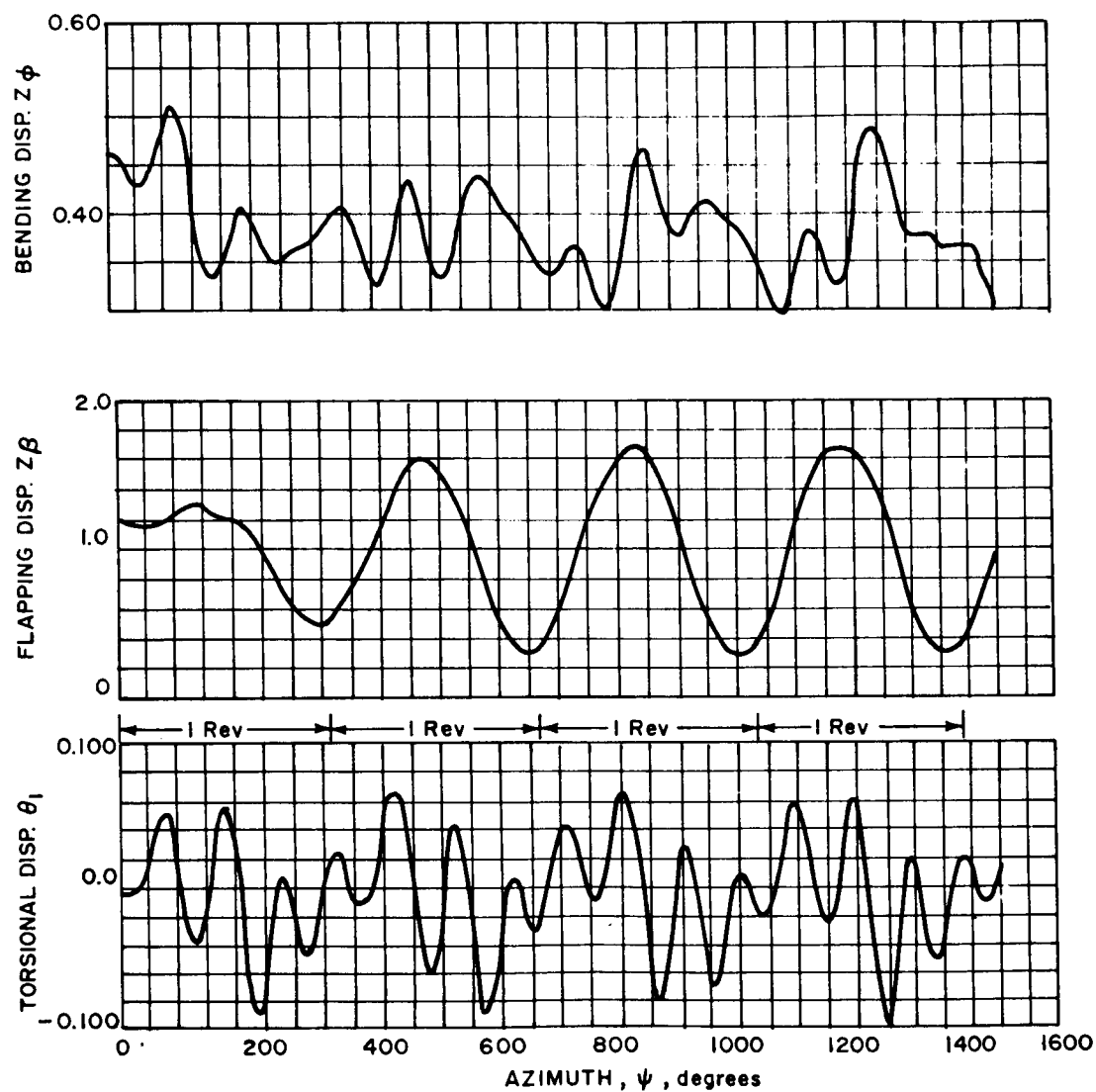


Figure 9 DISPLACEMENT TIME HISTORIES AT LINEAR INSTABILITY ONSET  
 $\Omega^* = 5.2, \theta_0 = 6 \text{ deg}, \mu = 0.1$



brought about by successive stall and unstall. The azimuth positions at which those events occur are marked by (S) and (U), respectively, on the  $\psi$ -scale.

The blade motions for the type of instability shown in Figure 10 are not of the same character as those of particular concern in the limiting of helicopter performance, in that the excessive torsional displacements shown in Figure 10 persist over a complete revolution of the blade. The control load time history, taken from flight test (Ref. 6), shown in Figure 11 illustrates the type of stall-related blade motions usually encountered at a thrust level or forward speed near the upper limit of an aircraft. Large oscillations in the control loads, presumably deriving from blade torsional oscillations, are seen from Figure 11 to persist only between about  $\psi = 270$  deg and  $\psi = 400$  deg, rather than throughout a complete revolution of the blade.

A torsional displacement time history closely resembling the variation of control loads in Figure 11 was obtained for  $\Omega^*$  less than 4.4, for collective pitch angles between 12 and 13 deg. Results for two typical cases are shown in Figures 12 and 13. The occurrences of stall and unstall are indicated on the abscissas. The large oscillations in torsion are clearly related to stall, but their persistence is not the result of successive stalling and unstalling, as would be the case for true stall flutter. The blade appears to be responding to the sudden changes in aerodynamic moment at stall onset and unstall, as can be seen by comparing the variation of moment coefficient shown in Figures 12 and 13 with that of torsional displacement, and noting the azimuth positions at which stall and unstall occur. There is some cyclic stall-unstall within the stall zone evident in the results, particularly at the higher rotor speed ( $\Omega^* = 4.15$ , Figure 13). However, the major contributors to the oscillations appear to be the initial and final pulses associated with stall and unstall upon entering and leaving that zone. There are, in general, two cycles of torsional oscillation of excessive amplitude after the blade unstalls the last time on a given revolution. The response can be regarded as transient, on a localized time scale, or forced, when viewed on a scale of several rotor revolutions. The severity of the response is apparently due in part to the suddenness of load changes at stall and unstall, and partly to the relative lack of aerodynamic damping in pitch, particularly when the blade is not stalled.

If the collective pitch angle is increased, the blade does undergo stall flutter, as seen from the time history plotted in Figure 14. These results are for the same rotor

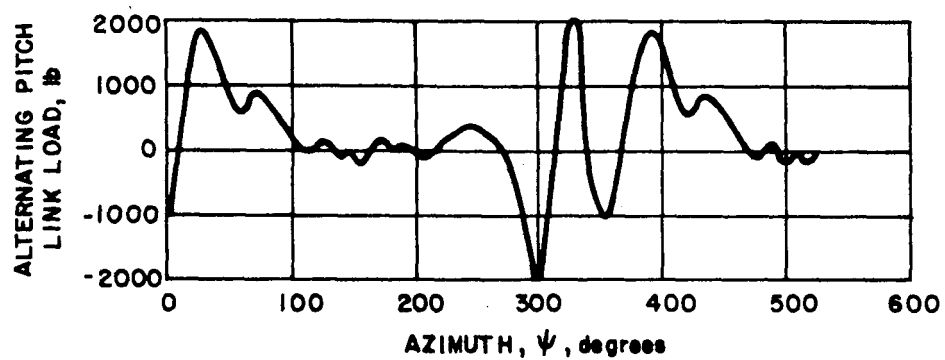


Figure 11 VARIATION OF PITCH LINK LOAD IN FLIGHT  
TEST OF CH-47 AT 123 KNOTS  
(from Ref. 6)

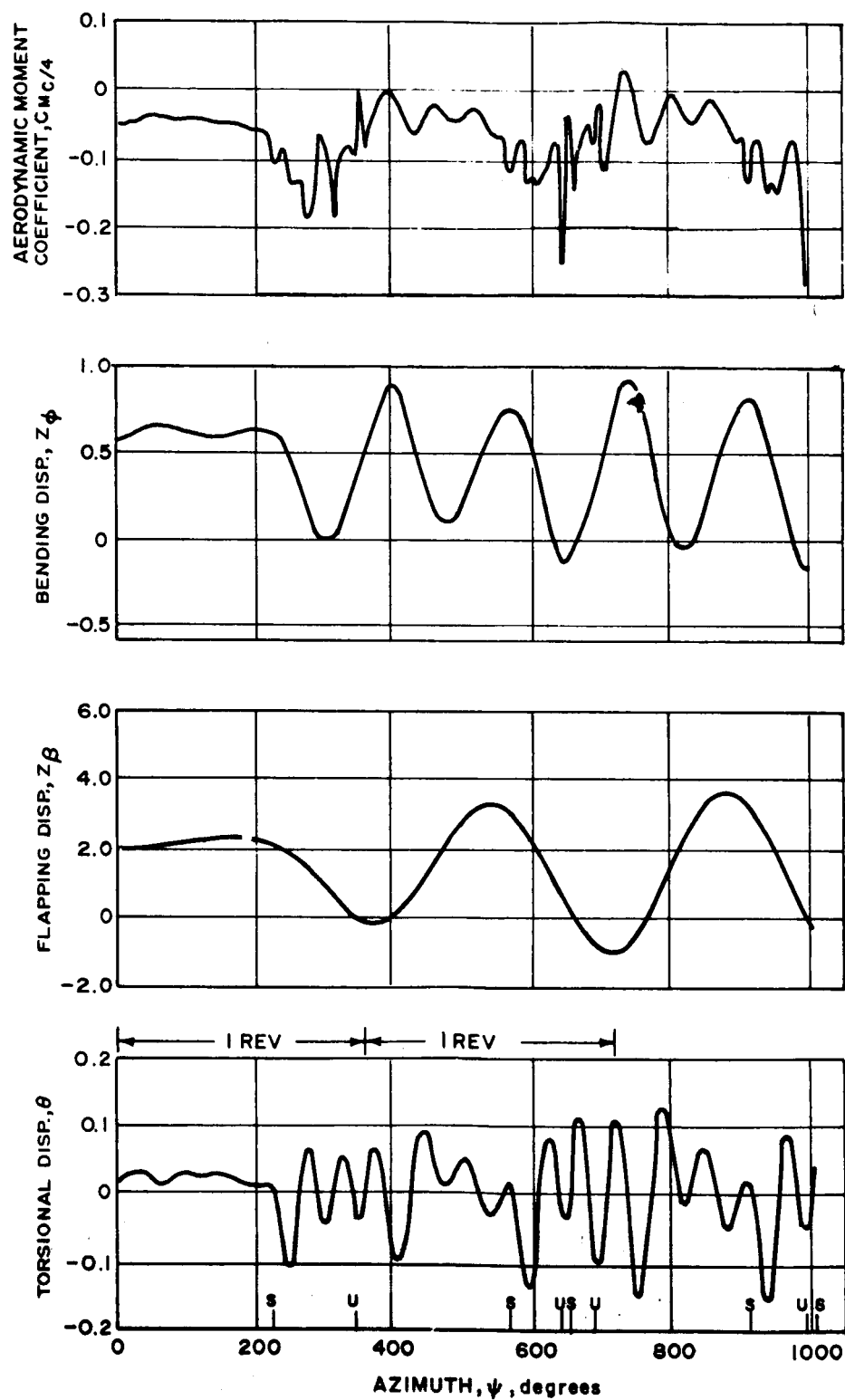


Figure 12 DISPLACEMENT AND MOMENT TIME HISTORIES FOR EXCESSIVE  
TORSIONAL RESPONSE  
 $\Omega^* = 3.89, \theta_0 = 12 \text{ deg}, \mu = 0.1$





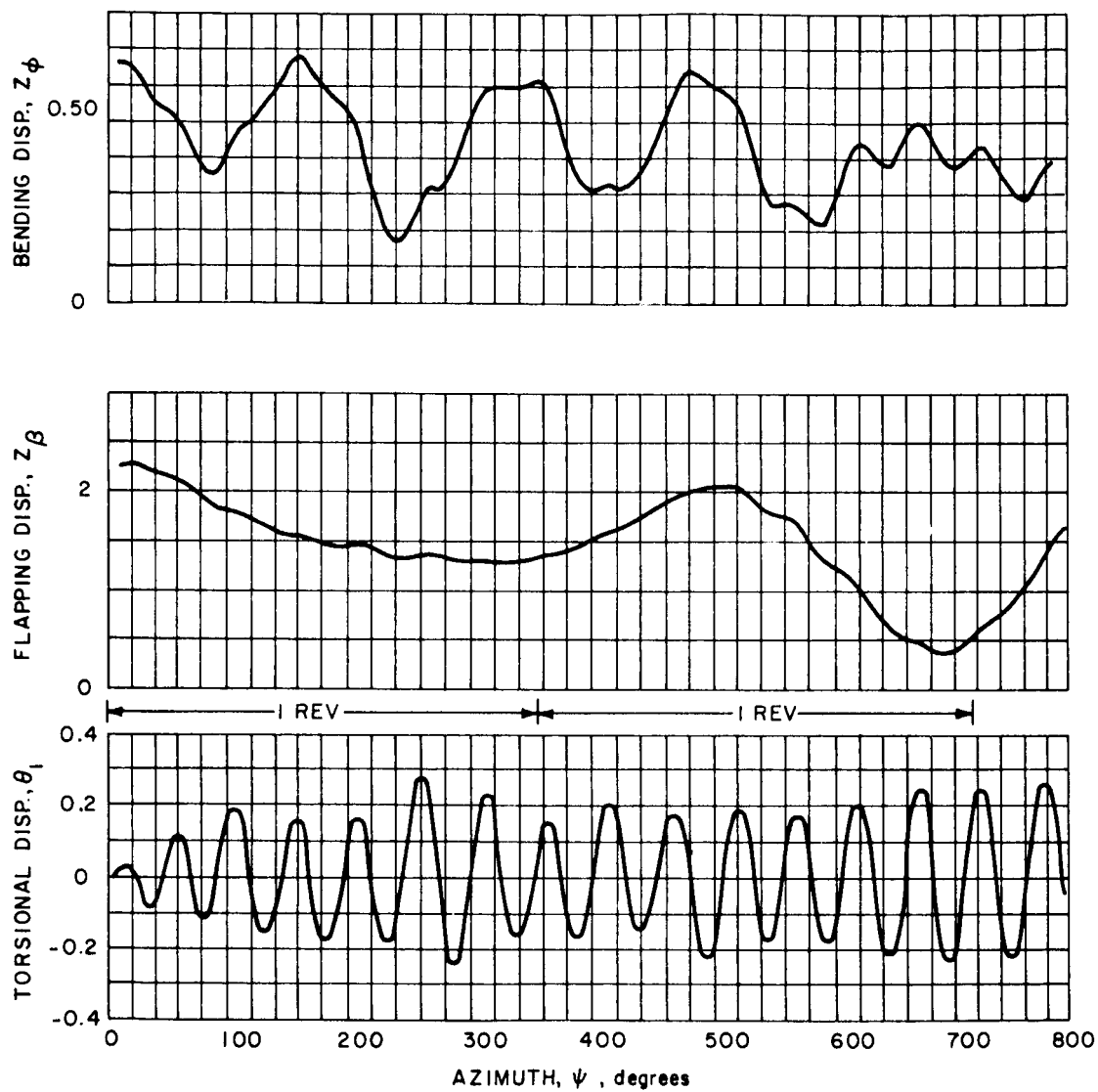


Figure 14 DISPLACEMENT TIME HISTORIES FOR STALL FLUTTER AT LOW ROTOR SPEED  
 $\Omega^* = 3.89$ ,  $\theta_0 = 14.3$  deg,  $\mu = 0.1$

speed as those of Figure 12, but with  $\theta_0$  increased from 12 deg to 14.3 deg. Successive stall and unstall persists over the whole revolution of the blade for this case.

It could be argued that the blade torsional oscillations of Figures 12 and 13 are still a manifestation of stall flutter, even though successive stall and unstall is not taking place, since the aerodynamic moment can undergo unstable variations when the blade remains stalled throughout a cycle (Ref. 4). It may, in fact, be the case that the large deflections do result partly from that effect, so choosing to term them as simply a response may be somewhat misleading. On the other hand, the solutions are distinctly different from what is definitely stall flutter obtained both in hover (Figure 6) and in forward flight (Figures 10 and 14) so that label would seem to be even less appropriate. Further, the persistence of the oscillations after exit from the stall zone is clearly symptomatic of a response, so, for lack of a more precise term, solutions of the type shown in Figures 12 and 13 are identified in what follows as excessive response.

### Linear Stability Boundaries

The value of  $\Omega^*$  at the onset of linear instability was determined for the three configurations considered, for advance ratios of 0, .1, .2, and .3. The effects of advance ratio and torsion-bending frequency ratio on linear stability are shown in Figure 15, where  $\Omega^*$  is plotted against  $\mu$  for two different frequency ratios. Increasing advance ratio is seen to cause some decrease in flutter rotational speed, with most of the decrease occurring between advance ratios of .1 and .2. The substantial decrease in frequency ratio, from 3.69 to 2.5, caused only about a 4 percent reduction in flutter speed over the range of advance ratios considered. The insensitivity to frequency ratio can be attributed to the large chordwise mass imbalance, which produces the same effect in classical binary flutter of a wing (Ref. 15).

The effect of chordwise mass imbalance on linear stability is shown in Figure 16, where  $\Omega^*$  at flutter onset is plotted against  $\mu$  for values of  $x_m$  of .216 and .108 semichords. As one would expect, the reduction in  $x_m$ , and hence in the coupling between bending and torsion, causes a substantial increase in the flutter rotational speed.

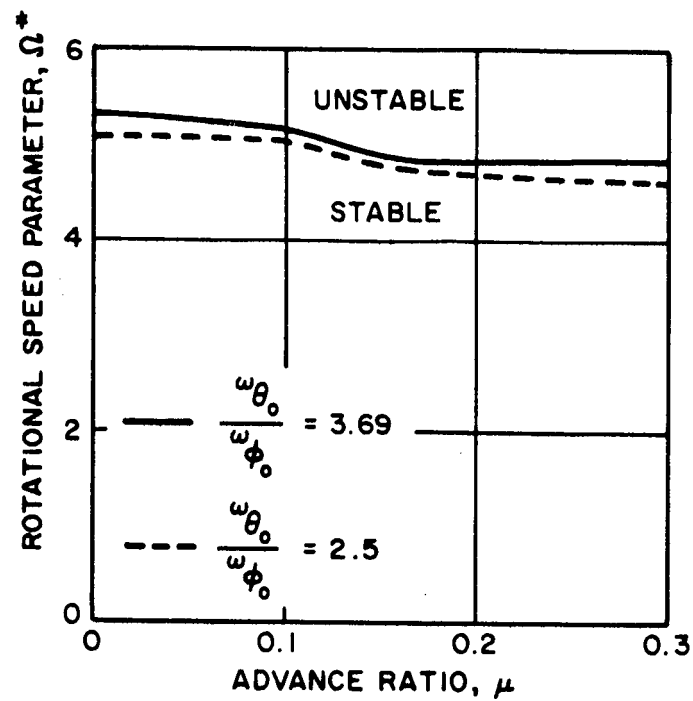


Figure 15 EFFECT OF ADVANCE RATIO AND  
TORSION-BONDING FREQUENCY RATIO  
ON LINEAR STABILITY -  $X_m/b = 0.216$

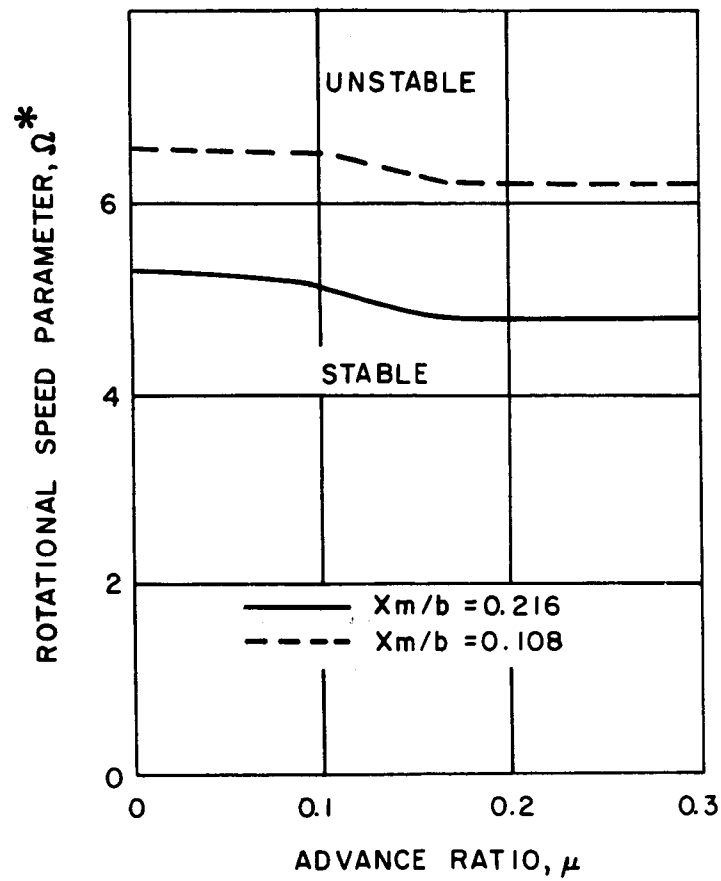


Figure 16 EFFECT OF  $X_m$  ON LINEAR STABILITY -

$$\omega_{\theta_0}/\omega_{\phi_0} = 3.69$$

## Stall Flutter and Response Boundaries

The effect of forward speed on stall-related instabilities for the three configurations was investigated by systematically varying the collective pitch angle and advance ratio, with  $\Omega^*$  equal to 3.89. In order to relate the results to rotor performance, a mean lift coefficient  $\bar{C}_L$  is defined, according to

$$\bar{C}_L = \frac{\bar{l}}{\rho \Omega^2 R^2 b}$$

where  $\bar{l}$  is the time-averaged lift per unit span at the aerodynamic reference radius. This coefficient is, to a good approximation, directly proportional to the thrust coefficient (see Ref. 16). The two-dimensional aerodynamic model does not provide a good measure of  $\bar{C}_L$  when the rotor is partially stalled, so  $\bar{C}_L$  was computed assuming it varies linearly with the collective pitch angle, using the formula

$$\bar{C}_L = a(\mu)(\theta_0 + .0217)$$

The slope  $a$  and zero-lift collective pitch angle of  $-.0217$  rad were obtained from calculations of  $\bar{C}_L$  for the nominal configuration with stall precluded. The variation of  $a$  with  $\mu$  is shown in Figure 17.

The results obtained for the nominal configuration are summarized in Figure 18 as a plot of  $\bar{C}_L$  vs  $\mu$ . As thrust is increased at a given  $\mu$ , the rotor is seen to first encounter a region of excessive response, of the type discussed previously, and then, for  $\mu$  of .2 or less, a region where stall flutter occurs. Increasing advance ratio has the effect of suppressing the tendency for stall flutter. At  $\mu = .2$ , stall flutter occurs at  $\bar{C}_L = .85$ , but a further increase in  $\bar{C}_L$  results in excessive response again. At  $\mu = .3$  a limit-cycle type of oscillation could not be triggered at all. As a result, stall flutter is confined to a region somewhat as indicated by the shaded area in Figure 18.

The suppression of stall flutter at high advance ratio is apparently caused by an effect similar to the one encountered at low rotor speed in hover, whereby the flapping motion prevented a limit cycle from occurring. This can be seen from the blade motions obtained for  $\mu = .3$  and

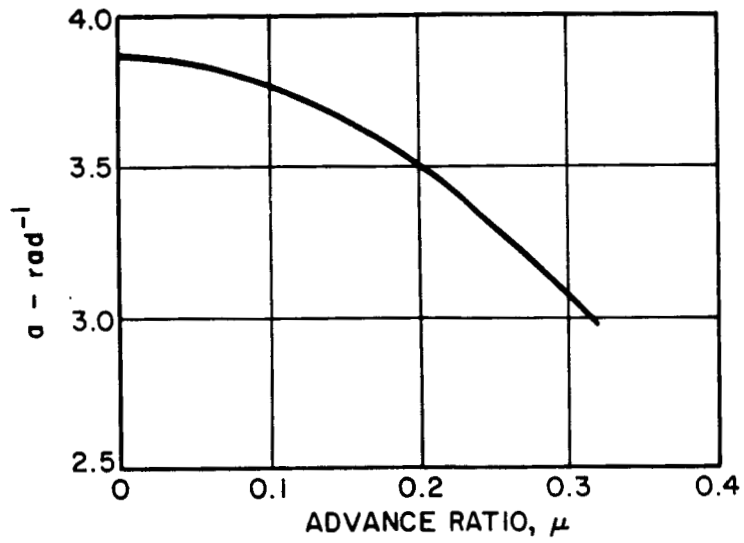


Figure 17 VARIATION OF  $a = d\bar{C}_L / d\theta_0$  WITH ADVANCE RATIO

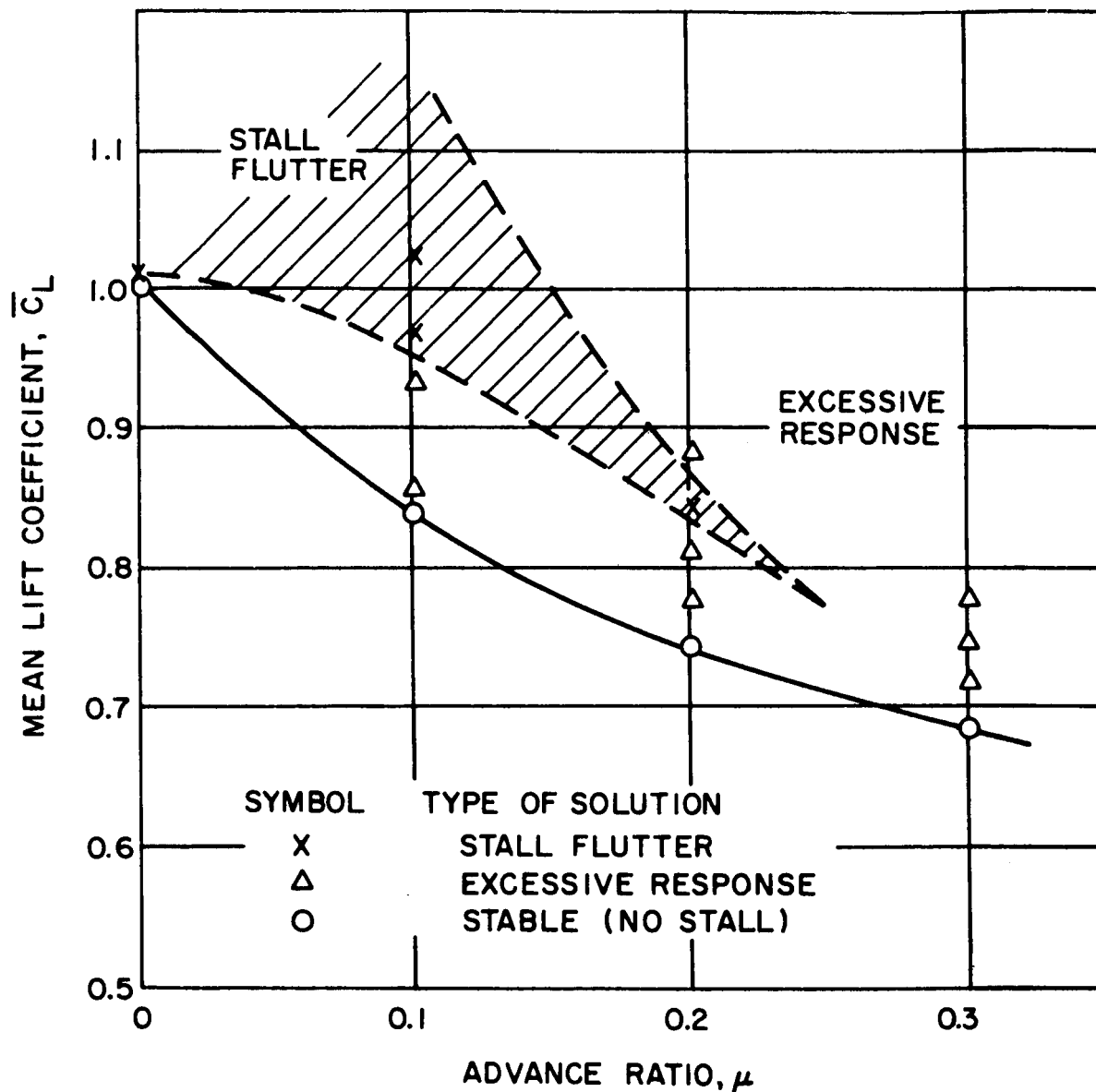


Figure 18 STALL STABILITY BOUNDARIES FOR  $\Omega^* = 3.89$ ,  $\omega_{\theta_0}/\omega_{\theta_0} = 3.69$   
AND  $Xm/b = 0.216$

$\bar{C}_L = .78$ , plotted in Figure 19. On the first revolution, as the blade enters the stall zone on the retreating side, it appears that a limit cycle is being set up, with repeated stall and unstall occurring. However, at about  $\psi = 420$  deg, the flapping motion has built up in response to the large cyclic pitch changes, producing a negative plunging rate sufficient to keep the blade unstalled over the remainder of its passage on the advancing side. Then, when the blade again enters the stall zone, the large positive flap-induced plunging rate precludes unstall until exit from the stall zone at about  $\psi = 670$  deg. As a result, the blade subsequently undergoes excessive torsional response, rather than stall flutter.

The effect of torsion-bending frequency ratio on stall-related instabilities can be seen from Figure 20, where  $\bar{C}_L$  is plotted against  $\mu$  for  $\omega_{\theta_0}/\omega_{\phi_0} = 2.5$ . No instance of excessive torsional response occurred with this configuration for an advance ratio of .2 or less. Instead, limit-cycle type oscillations were set up, with almost no evidence of suppression by the flapping motion, even at relatively high values of  $\bar{C}_L$  with  $\mu = .2$ . At  $\mu = .3$ , however, only excessive response was obtained, similar to the results for  $\omega_{\theta_0}/\omega_{\phi_0} = 3.69$ .

The marked deterioration in stability at the lower frequency ratio is apparently associated with the lessened linear stability of the system. The configuration with  $x_m/b = .108$ , which is more stable, in the linear sense, than the nominal one, exhibited a trend opposite to the one resulting from a decrease in frequency ratio. The results for the smaller mass center offset, shown in Figure 21, are similar to those of the nominal configuration, Figure 18, but the region in which stall flutter occurs is somewhat reduced, there being no occurrence of stall flutter at an advance ratio of .2. Also, the amplitude of the torsional oscillations in the region of excessive response is considerably reduced, as evidenced by comparing the blade motions plotted in Figure 22, which are for  $\mu = .1$ ,  $\bar{C}_L = .95$  and  $x_m/b = .108$ , with those of the nominal configuration plotted in Figure 12.



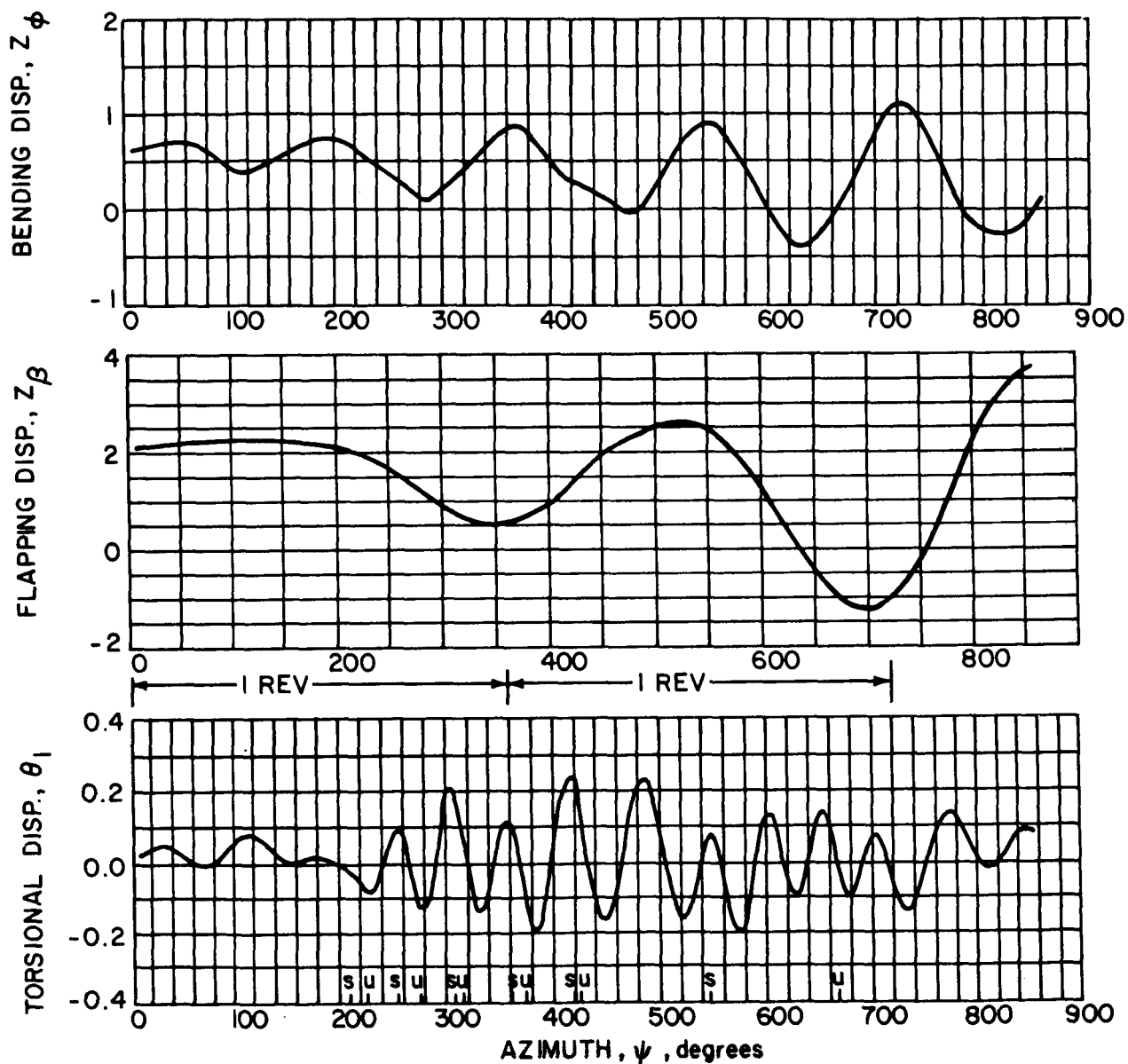


Figure 19 DISPLACEMENT TIME HISTORIES AT HIGH ADVANCE RATIO —  
 $\Omega^* = 3.89$ ,  $\bar{C}_L = 0.78$ ,  $\mu = 0.3$

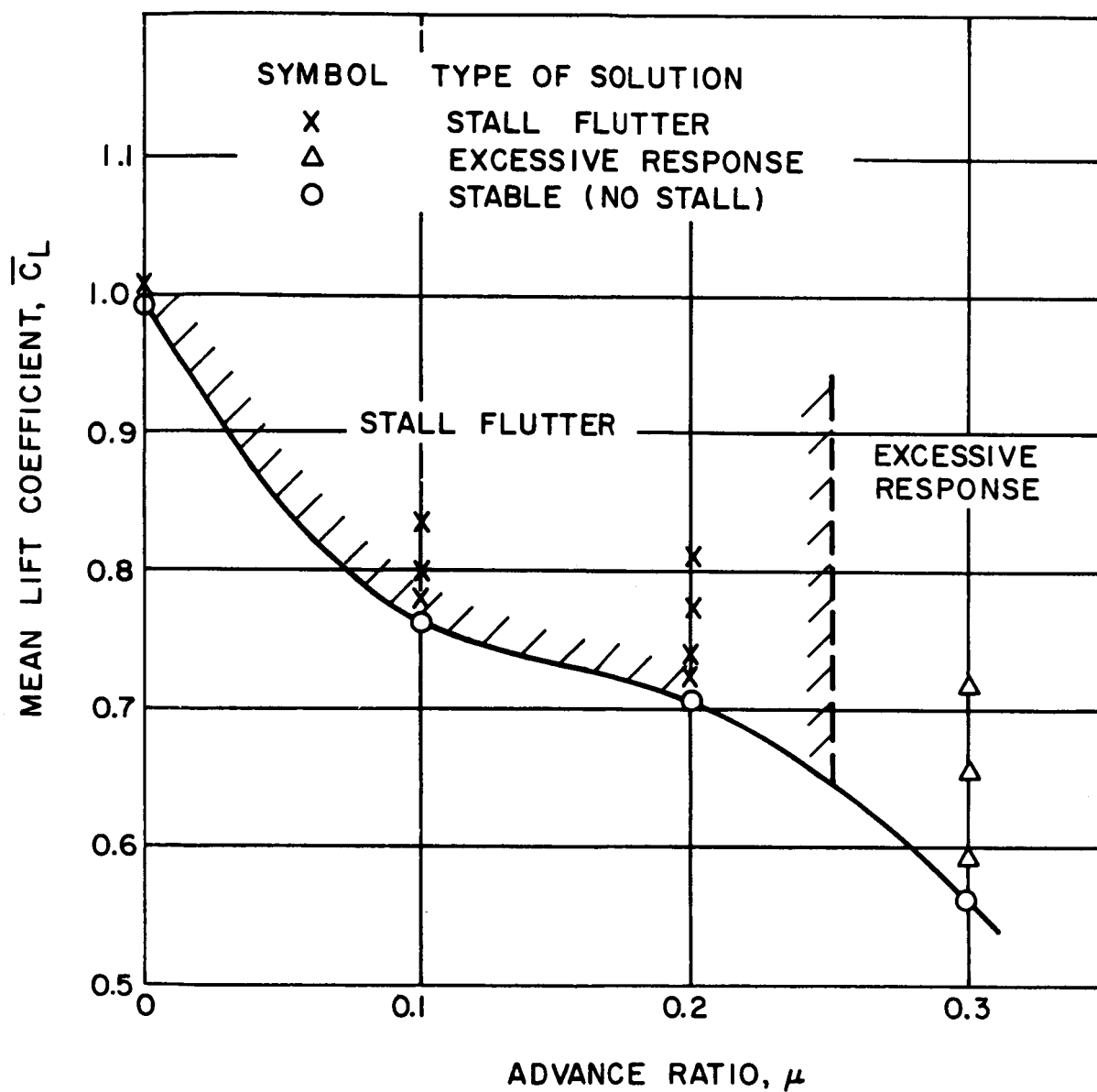


Figure 20 STALL STABILITY BOUNDARIES FOR  $\Omega^* = 3.89$ ,  $\omega_{\theta_0}/\omega_{\phi_0} = 2.5$   
AND  $X_m/b = 0.216$

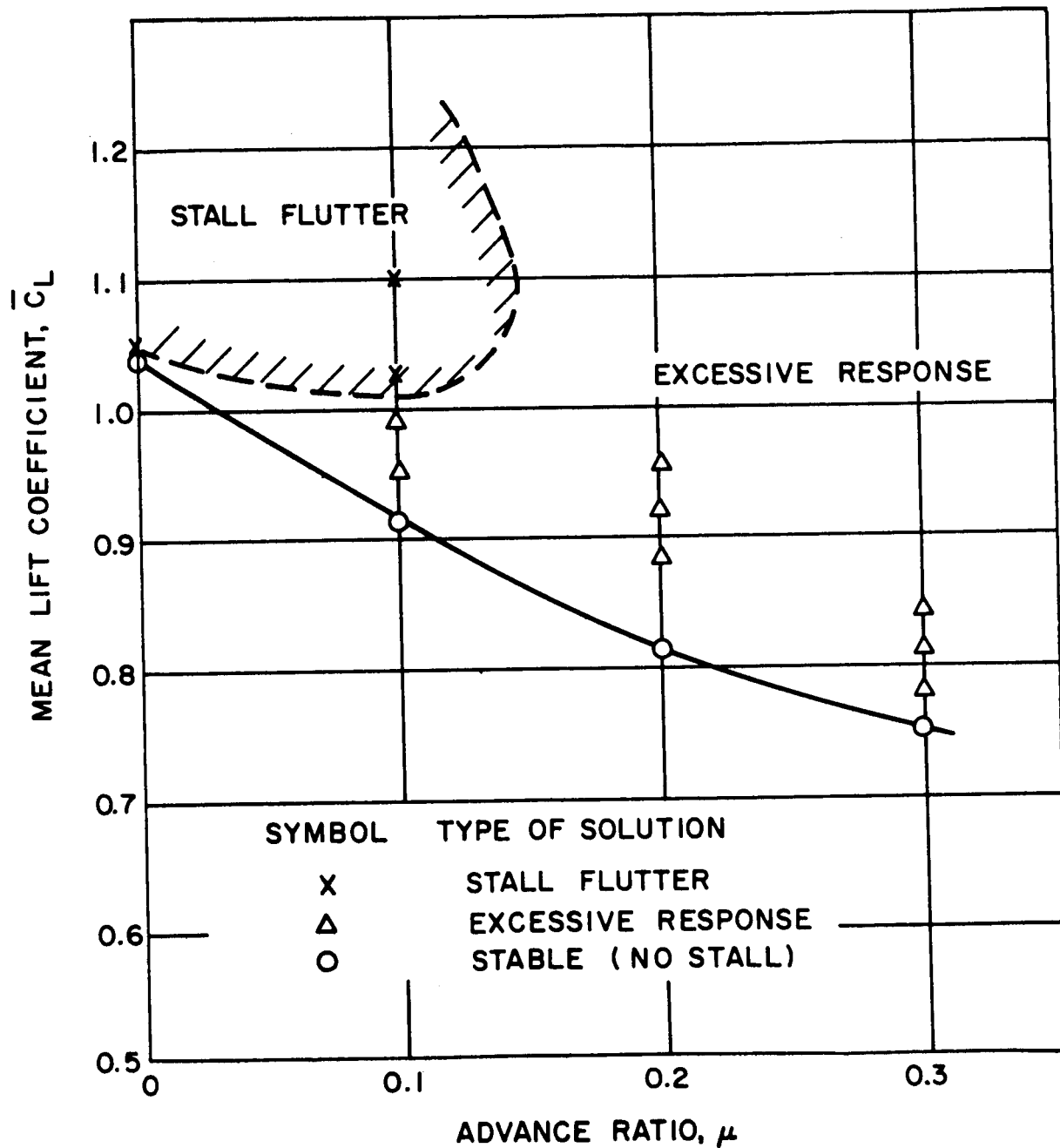


Figure 21 STALL STABILITY BOUNDARIES FOR  $\Omega^* = 3.89$ ,  $\omega_{\theta_0}/\omega_{\phi_0} = 3.69$   
AND  $X_m/b = 0.108$

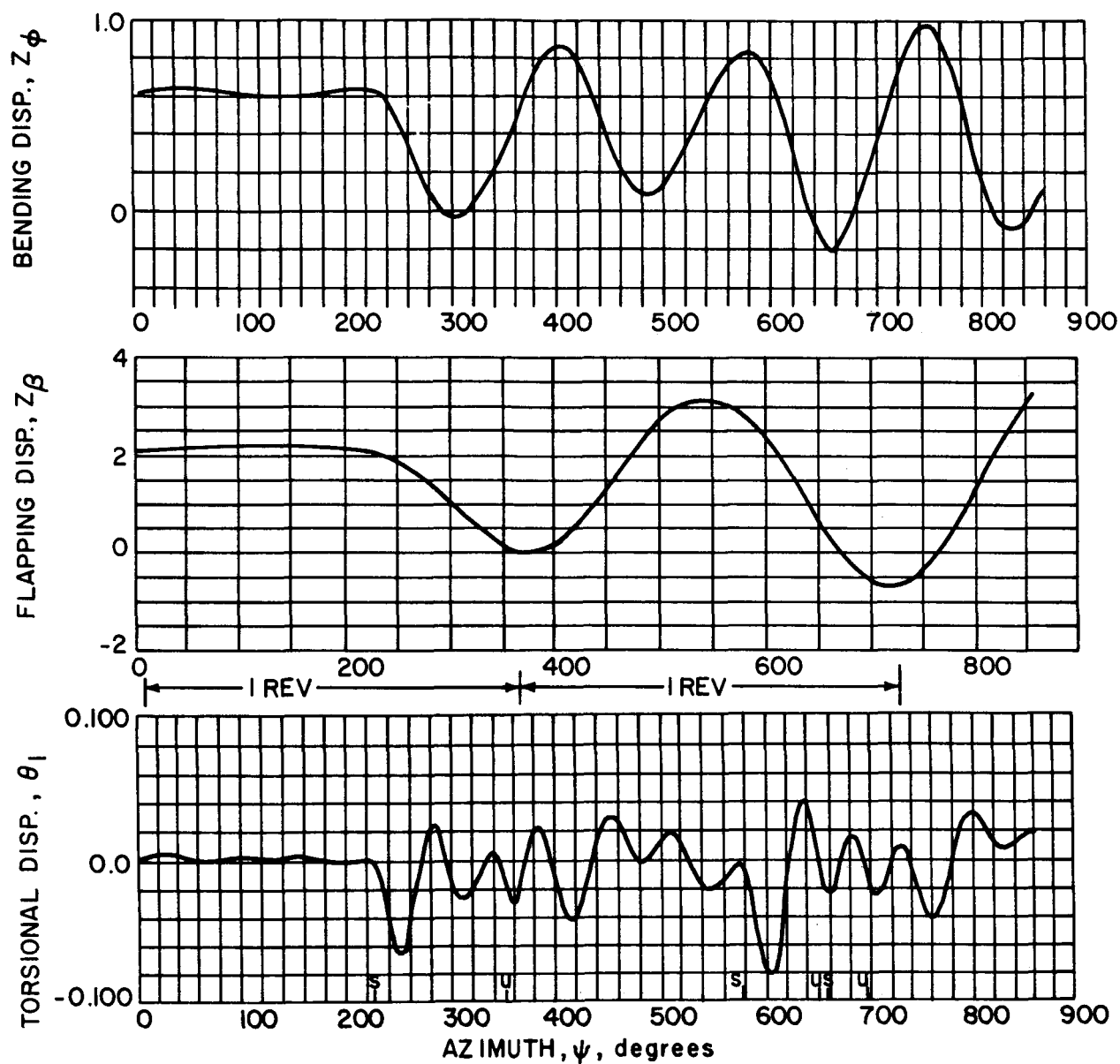


Figure 22 DISPLACEMENT TIME HISTORIES FOR EXCESSIVE TORSIONAL RESPONSE.  
 $\Omega^* = 3.89$ ,  $\bar{C}_L = 0.95$ ,  $\mu = 0.1$ , AND  $X_m/b = 0.108$

## CONCLUSIONS

An analysis has been performed of the aeroelastic stability of a helicopter rotor blade in hovering and forward flight. An analytical model of an airfoil undergoing unsteady stall and an elastomechanical representation including flapping, flapwise bending and torsional degrees of freedom were employed in the study. The following conclusions can be drawn from the results obtained.

1. Analysis of aeroelastic stability for a hovering rotor demonstrated that the aerodynamic and dynamic representations developed are capable of reproducing classical and stall flutter.
2. While stall flutter is an instability involving a single rotational degree of freedom, the minimum rotational speed for its occurrence, in hover, is determined from coupling with a translational degree of freedom.
3. In forward flight, the rotor can undergo a linear instability analogous to classical flutter and a stall-induced flutter which, while not manifested by a strictly periodic limit cycle, has the same basic mechanism for its occurrence as stall flutter of a hovering rotor.
4. The large stall-related torsional oscillations which limit forward speed and thrust are primarily the response to the rapid changes in aerodynamic moment which accompany stall and unstall, rather than the result of an aeroelastic instability.
5. Linear stability is relatively insensitive to advance ratio for advance ratios as large as .3.
6. While excessive response due to stall occurs at high advance ratio, stall flutter is precluded by the large flap-induced plunging rates.

7. The severity of stall-related instabilities and response depends to some extent on linear stability. Increasing linear stability lessens the susceptibility to stall flutter and reduces the magnitude of the torsional response to stall and unstall.

APPENDIX A

PROGRAM LISTING

## APPENDIX A

### PROGRAM LISTING

A listing of the FORTRAN coding of the computer program follows. The program was written in FORTRAN IV for use on an IBM 360/75 computer.



C		MAIN	2
C	PROGRAM TO ANALYZE UNSTEADY AIRFOIL STALL	MAIN	3
C		MAIN	4
	COMMON /BL1/ NTIME, NDIMC, ISTD		
	COMMON /CLCMBL / CLVB, CMVB, CMPAVB		
C		SETUPS17	
	COMMON /INPTVB/ FTVB(64), FPVB(64), FPPRVB(64), DIDRVB(64),	SETUPS18	
A	XMVB(64), DELVB, XMUVB, FOVB, XMUAVB,	SETUPS19	
B	ATOVB, ATCVB, ATSVB, ROVB, RVB(64),	SETUPS20	
C	MVB(64), NVB	SETUPS21	
C		SETUPS22	
	COMMON /INPUTS/ NSBL, NZ, NOFF, NGAM, NSIG,	SETUPS23	
A	NCOT, NCORD, LOWER, MSTOP, MAXT, MOTR,	SETUPS24	
B	NOTBL, INOV, ELSIG, DXI, REB, RDBB,	SETUPS25	
C	FRZ, ARR, AMPLU, FREQU, ALPH1, ALPH2,	SETUPS26	
D	HEAVE, AROT, FREQF, PHIH, NY, RY1,	SETUPS27	
E	DRY, Y(100), TEST, UPRIM, XU(30), YU(30),	SETUPS28	
F	XL(30), YL(30), ER1, ER2, ER3, BDBR,	SETUPS29	
G	RRDBR	SETUPS30	
H	CMPA, CMPAS, BARG, EMI, HVOR, NVOR, SSPA, SVOR, TORF, X1VOR		
I	PLOTOP, PSILOW, PSIUP		
J	NOUT		
	COMMON/ ZZZ/ Z(3)		
C		SETUPS31	
C			
C	DIMENSION USAV(300,100),SCALS(300)	MAIN	5
	DIMENSION USAV(1,1),SCALS(300)	MAIN	5
	DIMENSION CAMBR(24),THICK(24)	MAIN	6
	DIMENSION XGAM(30),XSIG(100),XSIGA(100),XSIGR(100),XC(300),X(300),	MAIN	7
	LSBL(300),XBSIG(100)	MAIN	8
	DIMENSION ACAP(30,3),BCAP(100,3),ASZ(30),AS(30,30),BS(30,30),ASHZ	MAIN	9
	1(100),ASH(30,30),BSH(30,30),AR(30),ARH(100),UE(300,3)	MAIN	10
	DIMENSION ALAM(30),VZIP(30),FPRES(100),GAMAW(1000),XTW(1000)	MAIN	11
	DIMENSION BLAM(30),FLAM(10),XFLAM(10)	MAIN	12
	DIMENSION SCALE(300,2),U(1,1,1),UC(100,3),V(100,2)	MAIN	13
	1, P(200,7)		
C			
C			
C	DOUBLE PRECISION CMAT(60,60),RMAT(130)	MAIN	15
C			
C	DATA IN, MOUT, NF/ 5,6, 24/		
	DATA PI,TIME,UINF,RENEL,USTOP/3.14159,0.,1.,4.75E4,2.8/	MAIN	18
	DATA FLAM /1.75,1.75,1.724,1.527,1.354,1.,.663,.452,.25	MAIN	19
	14,.21/	MAIN	20
	DATA XFLAM /-100.,-11.26,-7.01,-3.48,-1.766,0.,1.888,4.	MAIN	21
	103,6.77,7.19/	MAIN	22
	DATA DEGRES /1.74 53292 51994 330D-2/	SUPPL	38
C			
C			
C	EQUIVALENCE (CMAT(1),USAV(1)),(ASH(1),SCALS(1))	MAIN	16
C			
C			
C			
C	IF ISTD =1 TIME DERIVATIVES NOT USED		

	ISTD= 1	
	RAD = 180. /PI	
	IL= 8888	
	NDIMC= 60	
	CALL SETUPS	MAIN 4
	IF(ISTD .EQ. 1) GO TO 40	
	DO 100 J = 1,300	
	SCALS(J) =0.	
	DO 100 I = 1,100	
100	USAV (J,I) =0	
40	: CONTINUE	
C		
	CALL READIN ( IL,& 60)	
C		MAIN 65
C	NOTE - OFFSETS ARE PUT IN AS LISTED IN THEORY OF WING SECTIONS,	I.E. MAIN 66
C	AS A FRACTION OF TOTAL CHORD, X1 BEING MEASURED FROM THE	MAIN 67
C	LEADING EDGE. BE SURE NF IS AN EVEN NUMBER.	MAIN 68
C		MAIN 69
	TIME=0.	
	NTIME=0	
	NWAKE= 999	
	ISEP=0	
	ISEPY =0	
	IWASH =2	
	UINF =1.	
	L=0	
	INDV=INDV+1	MAIN 59
	WRITE(MOUT,6)	MAIN 72
	PITCH = ALPH1	
	IF(INDV + MOTR .LE. 2) PITCH = PITCH - ALPH2	
	IF(INDV .EQ. 2)	
X	AMPLU = 1.33333* XMJAVB * (1.-ROVB**3) / (1. - ROVB**4)	
	IF( INDV.EQ. 2) FREQU= BDBR/RDDBR	
	IF(INDV .GE. 2) GO TO 343	
	WRITE(MOUT,25) NVOR,SVOR,HVOR,BARG,XIVOR,EMI,TORF,SSPA	MAIN 75
	RY=RY1	MAIN 64
	HVOR=HVOR**2	MAIN 76
	BARG=BARG/6.2832	MAIN 77
343	CALL SECT(XU,YU,XL,YL,NOFF,NF,RDDB,TMDBB,CMDBB,THICK,CAMBR)	MAIN 78
	DO 7875 N=1,NF	MAIN 79
	CAMBR(N)=CAMBR(N)*CMDBB	MAIN 80
7875	THICK(N)=THICK(N)*TMDBB	MAIN 81
	WRITE(MOUT,4)	MAIN 82
	WRITE(MOUT,7) AMPLU,FREQU,ALPH1,ALPH2,HEAVE,AROT,FREQF,RDDB,REB	MAIN 83
	WRITE(MOUT,8)	MAIN 84
	WRITE(MOUT,9) (N,CAMBR(N),THICK(N),N=1,NF)	MAIN 85
	MX=NSBL+NZ-1	MAIN 86
	CALL SCAL(SBL,NSBL,FRZ,ARR,RDDB)	MAIN 87
	CALL CORDX(NSBL,NZ,RDDB,SBL,X,XC)	MAIN 88
	DO 2420 M=1,MX	MAIN 89
	IF(XC(M)-1.) 2420,2419,2419	MAIN 90
2419	MEND=M-1	MAIN 91
	GO TO 2421	MAIN 92
2420	CONTINUE	MAIN 93
2421	MX=MEND	MAIN 94

MXM1=MX-1	MAIN	95
UE(MX+1,1)=1.	MAIN	96
EPSLF=2.*(X(NZ)-X(NZ-1))	MAIN	97
FPSTF=X(MX)-X(MX-1)	MAIN	98
ALTC=8.36F4/SQRT(REB)	MAIN	99
IF(ISTD.EQ.1) GO TO 50		
DO 2422 M=1,MX	MAIN	100
SCALE(M,1)=0.	MAIN	101
SCALE(M,2)=0.	MAIN	102
DO 2422 N=1,NY	MAIN	103
U(M,N,1)=0.	MAIN	104
2422 U(M,N,2)=0.	MAIN	105
5C CONTINUE		
NSIGA=NSIG	MAIN	106
NSIGB=NSIG	MAIN	107
NSIG1=NSIG+1	MAIN	108
MOTR=MOTR+1	MAIN	109
NOTBL=NOTBL+1	MAIN	110
XMAX=1.-ELSIG	MAIN	111
CCNA=.375*PI/DXI	MAIN	112
ANGS=PI/FLOAT(NSIG)	MAIN	113
CALL SETSX(NSIG1,1.1,2.,XSIG,ANGS)	MAIN	114
XSEP=1.1	MAIN	115
DO 2430 N=1,NSIG1	MAIN	116
XSIGB(N)=XSIG(N)	MAIN	117
2430 XSIGA(N)=XSIG(N)	MAIN	118
DO 2431 N=1,NSIG	MAIN	119
DO 2431 NU=1,3	MAIN	120
2431 BCAP(N,NU)=0.	MAIN	121
PINT=2./FLOAT(NCORD)	MAIN	122
NCPI=NCORD+1	MAIN	123
THXI=1.5/DXI	MAIN	124
NGPI=NGAM+1	MAIN	125
NWMI=NWAKE-1	MAIN	126
COUNT=0.	MAIN	127
DO 8456 N=1,NWAKE	MAIN	128
GAMAW(N)=0.	MAIN	129
XIW(N)=1.+COUNT	MAIN	130
8456 COUNT=COUNT+DXI	MAIN	131
ANGLE=PI/FLOAT(NGAM)	MAIN	132
COUNT=0.	MAIN	133
DO 1002 M=1,NGPI	MAIN	134
PHIM=COUNT*ANGLE	MAIN	135
XGAM(M)=COS(PHIM)	MAIN	136
DOUNT=2.	MAIN	137
DO 1001 N=2,NGAM	MAIN	138
AS(M,N)=COS(DOUNT*PHIM)	MAIN	139
1001 DOUNT=DOUNT+1.	MAIN	140
1002 COUNT=COUNT+1.	MAIN	141
CALL WASH(XGAM,NGAM,TIME,ALPH1,ALPH2,HEAVE,AROT,FREQF,PHIH,UINF,CAMAIN	MAIN	142
IMBR,NF,VZIP,1,1)	MAIN	143
DO 8458 M=1,NGPI	MAIN	146
CPAT(M,1)=1.	MAIN	147
TEMP=2.*VZIP(M)	MAIN	148
RPAT(M)=TEMP	MAIN	149

CMAT(M,2)=XGAM(M)	MAIN 150
DO 8457 N=3,NGP1	MAIN 151
8457 CMAT(M,N)=AS(M,N-1)	MAIN 152
8458 CONTINUE	MAIN 153
CALL ALSOL(NGP1,CMAT,RMAT)	MAIN 154
DO 8459 N=1,NGP1	MAIN 155
ACAP(N,1)=RMAT(N)	MAIN 156
ACAP(N,3)=RMAT(N)	MAIN 156
8459 ACAP(N,2)=ACAP(N,1)	MAIN 157
DO 2784 M=1,MX	MAIN 158
SIGN=1.	MAIN 159
IF(M-NZ) 2774,2775,2775	MAIN 160
2774 SIGN=-SIGN	MAIN 161
2775 CALL QECAL(ISEP,NGAM,NSIG,NF,XSIG,ACAP,BCAP,THICK,RCBB,GAMAW(1),U	MAIN 162
INF,XC(M),UF(M,1),SIGN)	MAIN 163
2784 UF(M,2)=UE(M,1)	MAIN 164
DO 1004 M=2,NGAM	MAIN 165
1004 BLAM(M)=(1.125*XGAM(M)+.1875*(1.+XGAM(M))*(1.-3.*XGAM(M))*ALOG((1.	MAIN 166
1+XGAM(M))/((1.-XGAM(M))) )/DXI	MAIN 167
BLAM(NGP1)=-1.125/DXI	MAIN 168
CALL CLCM(NCOT,ISEP,NGAM,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,RC	MAIN 504
LAP,THICK,RDDB,GAMAW,UINF,UDOT,DXI,AROT,CMPA)	MAIN 505
IF (INDV.EQ. 2)	
1CALL SUPPL	MAIN
C	MAIN 169
C INDEXING IN TIME IS CARRIED OUT AT THIS POINT.	MAIN 170
C	MAIN 171
9999 CONTINUE	MAIN 172
CALL ACUCPU( YACU )	
IF( YACU .LT. 35000 ) GO TO 99	
C	MAIN 175
C NOTE - FOR READ-IN CF FCIL MOTIONS, MAKE ALPHA1 = ALPHA,	MAIN 176
C ALPHA2 = ALPHA- $\dot{\alpha}$ , AND HEAVE = H- $\dot{H}$ .	MAIN 177
C	MAIN 178
IF(MCTR.EQ. 2)	
XREAD(IN,2,END=8989) ALPHA1,ALPH2,HEAVE	MAIN 174
158 NITS=1	MAIN 182
TIME=TIME+DXI	MAIN 183
NTIME=NTIME+1	MAIN 184
NWAKE=NTIME+2	MAIN 185
IF(NWAKE-998) 202,201,201	MAIN 186
201 NWAKE=998	MAIN 187
202 IF(MAXT-NTIME) 8989,8800,8800	MAIN 188
8800 SAVFU=UINF	MAIN 189
L= L+1	
P(L,1) = BCBB / RRDBR * TIME * RAD	
PSI360= AMOD( P(L,1) , 360.)	
UINF=1.+AMPLU*SIN(FREQJ*TIME)	MAIN 190
IF(INDV.EQ. 2)	
XCALL SUPPL(UINF)	MAIN
PITCH = ALPHA1	
IF(INDV + MCTR .LE. 2) PITCH = PITCH - ALPH2*COS(FREQF*TIME)	MAIN 475
UDOT=FREQU*AMPLU*COS(FREQU*TIME)	MAIN 191
STEPX=.5*DXI*(UINF+SAVEU)	MAIN 192
DO 1003 J=2,NWAKE	MAIN 193

JC=NWAKE-J+2	MAIN 194
GAMAW(JC)=GAMAW(JC-1)	MAIN 195
1003 XIW(JC)=XIW(JC-1)+STFPX	MAIN 196
IF(ISEP) 2009,2009,2007	MAIN 197
2007 DO 2008 N=1,NSIG	MAIN 198
BCAP(N,3)=BCAP(N,2)	MAIN 199
2008 BCAP(N,2)=BCAP(N,1)	MAIN 200
DO 4433 N=1,NSIG1	MAIN 201
XSIGR(N)=XSIGA(N)	MAIN 202
4433 XSIGA(N)=XSIG(N)	MAIN 203
GO TO 2010	MAIN 204
2009 DEADL=0.	MAIN 205
ELDOT=UINF	MAIN 206
2010 DO 1014 M=1,MX	MAIN 207
UE(M,3)=UE(M,2)	MAIN 208
1014 UE(M,2)=UE(M,1)	MAIN 209
DEADL=DEADL	MAIN 210
ELDI=ELDOT	MAIN 211
ALAM(1)=(1.125+.75*ALOG(STEPX*.5))/DXI	MAIN 212
DO 1005 M=2,NGPI	MAIN 213
1005 ALAM(M)=BLAM(M)+.75*(1.+(1.-XGAM(M))/STEPX)*ALOG((1.+STEPX-XGAM(M)	MAIN 214
1)/(1.-XGAM(M))/DXI	MAIN 215
DO 2006 M=1,NGPI	MAIN 216
ACAP(M,3)=ACAP(M,2)	MAIN 217
2006 ACAP(M,2)=ACAP(M,1)	MAIN 218
AFACT=8.*(ACAP(1,2)+.5*ACAP(2,2))-2.*(ACAP(1,3)+.5*ACAP(2,3))	MAIN 219
ALPHS=VZIP(1)	MAIN 220
CALL WASH(XGAM,NGAM,TIME,ALPH1,ALPH2,HEAVE,AROT,FREQF,PHIH,UINF,CAMAIN	MAIN 221
IMBR,NF,VZIP,MOTR,INDV)	MAIN 222
DO 1006 M=1,NGPI	MAIN 225
ASZ(M)=1.+2.*ALAM(M)	MAIN 226
AS(M,1)=XGAM(M)+ALAM(M)	MAIN 227
SUM=0.	MAIN 228
DO 4343 J=2,NWMI	MAIN 229
4343 SUM=SUM+(GAMAW(J)+(GAMAW(J+1)-GAMAW(J))*(XGAM(M)-XIW(J))/(XIW(J+1)	MAIN 230
1-XIW(J))*ALOG((XIW(J+1)-XGAM(M))/(XIW(J)-XGAM(M)))	MAIN 231
ELX=1.-XGAM(M)	MAIN 232
IF(M-1) 1006,2130,1006	MAIN 233
2130 ELX=1.	MAIN 234
1006 AR(M)=2.*VZIP(M)+ALAM(M)*AFACT/3.+(SUM-GAMAW(2)*(1.-XGAM(M))*ALOG(	MAIN 235
1/(1.+STEPX-XGAM(M))/ELX)/STEPX)/PI	MAIN 236
C	MAIN 237
C THE FOLLOWING CALCULATIONS, THROUGH STATEMENT 4444, ARE PERFORMED	MAIN 238
C ONLY IF THE AIRFOIL IS STALLED. THE AIRFOIL IS DESIGNATED TO BE	MAIN 239
C STALLED IF INTEGER ISEP IS NONZERO.	MAIN 240
C	MAIN 241
IF(ISEP) 3247,4444,3247	MAIN 242
3247 GO TO (3344,3345),IWASH	MAIN 243
3344 XSEP=XSEP+DXI	MAIN 244
IF(XSEP-XMAX) 3248,3347,3347	MAIN 245
3347 IWASH=2	MAIN 246
ISEP=0	MAIN 247
XSEP=1.1	MAIN 248
DO 3015 K=1,3	MAIN 249
DO 3015 N=1,NSIG	MAIN 250

3015	BCAP(N,K)=0.	MAIN	251
	GO TO 4444	MAIN	252
3345	IF(INDT) 3348,3348,3248	MAIN	253
3348	IF(NITS-1) 3248,3349,3248	MAIN	254
3349	IF(INDV.EQ.2) GO TO 6349	MAIN	255
	IF(VZIP(1)-ALPHS) 6349,6348,6348	MAIN	256
6348	NITS=2	MAIN	257
	GO TO 3248	MAIN	258
6349	CALL UNPOP(NGAM,AR,ALAM,AFACT,RMAT,CMAT,XGAM,AS,ACAP,MX,NZ,JE,XSIG	MAIN	259
	1,BCAP,THICK,RDBB,UINF,XC,UE)	MAIN	260
	GO TO 2785	MAIN	261
3248	XATT=XSEP+DEADL+.5*(ELDL+ELDOT)*DXI	MAIN	262
	DEADL=XATT-XSEP	MAIN	263
	DIFF=1.-XATT	MAIN	264
	XTST = XSEP + 3. * EPSLE		
	CALL SETSX(NSIG1,XSEP,XATT,XSIG,ANGS)	MAIN	265
	DO 4434 N=1,NSIG	MAIN	266
4434	XBSIG(N)=.5*(XSIG(N)+XSIG(N+1))	MAIN	267
	DO 3086 M=1,NGPI	MAIN	268
	DO 3086 N=1,NSIG	MAIN	269
3086	BS(M,N)=0.	MAIN	270
	DO 3087 M=1,NGPI	MAIN	271
	IF(XGAM(M)-XSEP) 3088,3088,3089	MAIN	272
3089	IF(XATT-XGAM(M)) 3187,3087,3091	MAIN	273
3091	DO 3092 I=1,NSIG1	MAIN	274
	IF(XGAM(M)-XSIG(I)) 3093,3092,3092	MAIN	275
3093	MARK=I	MAIN	276
	GO TO 3094	MAIN	277
3092	CONTINUE	MAIN	278
3094	WIDES=XSIG(MARK)-XSIG(MARK-1)	MAIN	279
	BS(M,MARK-1)=(XSIG(MARK)-XGAM(M))/WIDES	MAIN	280
	BS(M,MARK)=(XGAM(M)-XSIG(MARK-1))/WIDES	MAIN	281
	BS(M,I)=SQRT((XGAM(M)-XSEP)/(XATT-XGAM(M)))	MAIN	282
3088	IF(DIFF-1.E-6) 3087,3098,3098	MAIN	283
3098	BS(M,I)=BS(M,I)+DIFF**(-1.5)*SQRT(DEADL)*(2.*DIFF+(SQRT((1.-XGAM(M)	MAIN	284
	1))/(XATT-XGAM(M))-1.)*(4.*XGAM(M)-1.-3.*XATT))	MAIN	285
	GO TO 3087	MAIN	286
3187	BS(M,I)=DIFF**(-1.5)*SQRT(DEADL)*(3.+ XATT-4.*XGAM(M))	MAIN	287
3087	CONTINUE	MAIN	288
C		MAIN	289
C	SET-UP OF THE SECOND SET OF EQUATIONS STARTS HERE.	MAIN	290
C		MAIN	291
	DO 4350 K=1,NSIG	MAIN	292
	IF(XBSIG(K)-1.) 4348,4349,4349	MAIN	293
4348	COSK=XBSIG(K)	MAIN	294
	SINK=SQRT(1.-COSK*COSK)	MAIN	295
	THETK=ARCT(COSK)	MAIN	296
	TANT=SIN(.5*THETK)/COS(.5*THETK)	MAIN	297
	ASHZ(K)=TANT+CONA*(1.+COSK)*(1.-3.*COSK)/UINF+THXI*(PI-THETK+SINK+	MAIN	298
	ICONA*(1.+COSK)*SINK**2)/UINF	MAIN	299
	ASH(K,I)=.5*(ASHZ(K)-TANT)+SINK	MAIN	300
	COUNT=1.	MAIN	301
	DO 4355 N=2,NGAM	MAIN	302
	COUNT=COUNT+1.	MAIN	303
4355	ASH(K,N)=SIN(COUNT*THETK)+.75*(SIN((COUNT+1.)*THETK)/(COUNT+1.)-S	MAIN	304

IN((COUNT-1.)*THETK)/(COUNT-1.)/(DXI*UINF)	MAIN 305
GO TO 4350	MAIN 306
4349 ASHZ(K)=0.	MAIN 307
DO 4359 N=1,NGAM	MAIN 308
4359 ASH(K,N)=0.	MAIN 309
4350 CONTINUE	MAIN 310
IF(DIFF-1.E-6) 5005,5006,5006	MAIN 311
5005 PREC=0.	MAIN 312
GO TO 5007	MAIN 313
5006 CALL ATTPR(PREC,XSIG,NSIG,ASZ,AS,AR,CMAT,RMAT,NGAM,NF,ACAP,THICK,RMAIN	MAIN 314
10BB,GAMAW,UINF,UDOT,DXI,BCAP)	MAIN 315
5007 CALL MIXER(FPRES,PREC,UINF,UDOT,THICK,NF,XBSIG,NSIG,INDT,DEL1,THETMAIN	MAIN 316
11,REF,USEP,X4,CPI)	MAIN 317
CPCOT=CPI	MAIN 318
DO 4800 K=1,NSIG	MAIN 319
CORD=XBSIG(K)	MAIN 320
BSH(K,1)=-1.+THXI*BINT(XSEP,XATT,CORD)/UINF	MAIN 321
DO 4808 N=2,NSIG	MAIN 322
4808 BSH(K,N)=FB(XSIG(N-1),XSIG(N),XSIG(N+1),CORD)+FHXI*GB(XSIG(N-1),XSMAIN	MAIN 323
1IG(N),XSIG(N+1),CORD)/UINF	MAIN 324
CALL ESIGI(2,NSIGA,XSIGA,BCAP,CORD,VAL1)	MAIN 325
CALL ESIGI(3,NSIGB,XSIGB,BCAP,CORD,VAL2)	MAIN 326
ARH(K)=FPRES(K)+(2.*VAL1-.5*VAL2)/(DXI*UINF)	MAIN 327
IF(CORD-1.) 5008,4800,4800	MAIN 328
5008 CALL EGAMI(2,NGAM,ACAP,BCAP(1,2),XSIGA(1),XSIGA(NSIGA+1),GAMAW(2),MAIN	MAIN 329
1CORD,VAL1)	MAIN 330
CALL EGAMI(3,NGAM,ACAP,BCAP(1,3),XSIGB(1),XSIGB(NSIGB+1),GAMAW(3),MAIN	MAIN 331
1CORD,VAL2)	MAIN 332
ARH(K)=ARH(K)+(2.*VAL1-.5*VAL2)/(DXI*UINF)+.0625*AFACT*PI*(1.+CORDMAIN	MAIN 333
1)*(1.-3.*CORD+THXI*(1.-CORD*CORD))/(DXI*UINF)	MAIN 334
4800 CONTINUE	MAIN 335
4444 CONTINUE	MAIN 336
C	MAIN 337
C CALCULATIONS FROM THIS POINT ON COMBINE THE	MAIN 338
C CASES OF STALLED AND UNSTALLED AIRFOILS.	MAIN 339
C	MAIN 340
DO 6500 M=1,NGPI	MAIN 341
RMAT(M)=AR(M)	MAIN 342
CMAT(M,1)=ASZ(M)	MAIN 343
DO 6485 N=1,NGAM	MAIN 344
6485 CMAT(M,N+1)=AS(M,N)	MAIN 345
IF(ISEP) 6486,6500,6486	MAIN 346
6486 DO 6499 N=1,NSIG	MAIN 347
NGG=N+NGPI	MAIN 348
6499 CMAT(M,NGG)=BS(M,N)	MAIN 349
6500 CONTINUE	MAIN 350
IF(ISEP) 6502,6501,6502	MAIN 351
6501 NTOT=NGPI	MAIN 352
GO TO 6751	MAIN 353
6502 DO 6750 K=1,NSIG	MAIN 354
KK=K+NGPI	MAIN 355
RMAT(KK)=ARH(K)	MAIN 356
CMAT(KK,1)=ASHZ(K)	MAIN 357
DO 6748 N=1,NGAM	MAIN 358
6748 CMAT(KK,N+1)=ASH(K,N)	MAIN 359

DO 6750 N=1,NSIG	MAIN 360
NGG=N+NGPI	MAIN 361
6750 CMAT(KK,NGG)=RSH(K,N)	MAIN 362
NTOT=NSIG+NGPI	MAIN 363
6751 CALL ALSOL(NTOT,CMAT,RMAT)	MAIN 364
DO 6800 N=1,NGPI	MAIN 365
6800 ACAP(N,1)=RMAT(N)	MAIN 366
IF(ISEP) 6805,6820,6805	MAIN 367
6805 DO 6810 N=1,NSIG	MAIN 368
NGG=N+NGPI	MAIN 369
6810 BCAP(N,1)=RMAT(NGG)	MAIN 370
6820 CONTINUE	MAIN 371
GAMAW(1)=GAMI(ACAP,DXI,PI)	MAIN 372
IF(PSI360 .GE. PSILOW .AND. PSI360 .LE. PSIUP) GO TO 1736	
DO 1785 M=1,MX	MAIN 373
SIGN=1.	MAIN 374
IF(M-NZ) 1780,1785,1785	MAIN 375
1780 SIGN=-SIGN	MAIN 376
1785 CALL QECAL(ISEP,NGAM,NSIG,NF,XSIG,ACAP,BCAP,THICK,RDBB,GAMAW(1),UI	MAIN 377
INF,XC(M),UE(M,1),SIGN)	MAIN 378
2785 DO 8886 I=1,2	MAIN 379
US2=UE(1,1)	MAIN 380
DO 8886 M=1,MXMI	MAIN 381
US1=UE(M,1)	MAIN 382
UE(M,1)=(US1+US2+UE(M+1,1))/3.	MAIN 383
8886 US2=US1	MAIN 384
GO TO (8351,8353),IWASH	MAIN 386
8351 DO 8352 M=1,MX	MAIN 387
8352 SCALS(M)=0.	MAIN 388
GO TO 1786	MAIN 389
8353 CALL YSET(RY1,Y(2),NY,Y)	MAIN 390
RY=RY1	MAIN 391
DO 8354 M=1,MX	MAIN 392
8354 SCALS(M)=0.	MAIN 393
IF(INDV.EQ.2) GO TO 8370	MAIN 395
IF(ISEP.EQ.0.AND.VZIP(1).LT.ALPHS) GO TO 1786	MAIN 396
8370 CALL STAG(MX,NY,MSTOP,MST,DXI,RY,DRY,X,Y,UE,UC,V,USAV,SCALS,ISEP)	MAIN 397
LAMQ=1	MAIN 398
XSEPS=XSEP	MAIN 399
DXX=DXI	MAIN 400
IF(ISEP.EQ.1.AND.ISEPT.EQ.0.AND.NITS.EQ.1) DXX=1.E30	MAIN 401
8367 CALL BLC(X,Y,MST,MEND,NY,RY,DRY,DXX,REB,UPRIM,FLAM,XFLAM,TEST,U,SC	MAIN 402
IALE,UE,UC,V,XSEP,USEP,DISP,THETA,LOWER,LAMQ,MSEP,XC,USAV,SCALS,NIT	MAIN 403
MAIN 403	
1S,NTIME, NOTBL , XTEST, NZ, NOUT)	
IF(XSEP-XMAX) 7736,7735,7735	MAIN 405
7735 IF(ISEP) 1786,1786,7736	MAIN 406
7736 DELI=DISP	MAIN 407
THET1=THETA	MAIN 408
INDT=1-LAMQ	MAIN 409
IF(INDT.EQ.1.AND.NOTBL.EQ.2) GO TO 1786	MAIN 410
WRITE(MOUT,23) XSIG(1),CPCT,XSEP	MAIN 411
IF(INDT) 8462,8462,8463	MAIN 412
8462 IF(ISEP) 8562,8562,8563	MAIN 413
8563 IF(NITS-1) 8562,8562,8562	MAIN 414
8562 IF(ISEPT) 7742,7742,8562	MAIN 415



8562	CALL RU98(DEL1,THET1,RF8,XSEP,USEP,XC5,DCP,DEL5,X,XC,MX,NZ,X5,U5,UMAIN	416
	IF,ALTC,RFNEL,USTOP)	MAIN 417
	USEP=USEP+.002046*USEP**3	MAIN 418
	PDIFF=(USEP-U5)*(IUSEP+U5)	MAIN 419
	WRITE(MOUT,22) PDIFF,DCP	MAIN 420
	IF(DCP-PDIFF) 8263,8366,8366	MAIN 421
8263	ISEPT=0	MAIN 422
	GO TO 8463	MAIN 423
8366	IF(ISEPT) 8368,8368,8369	MAIN 424
8369	IF(ISEPT) 8467,8467,8368	MAIN 425
8467	IWASH=1	MAIN 426
	NITS=2	MAIN 427
	GO TO 3344	MAIN 428
8368	GO TO (8168,1786),NOTBL	MAIN 429
8168	CALL REATT(UC,V,X,Y,MX,NY,RY,DRY,UE,X5,DEL5,MST,REB)	MAIN 430
	LAMQ=0	MAIN 431
	GO TO 8367	MAIN 432
8463	IF(ISEPT) 7741,7741,7742	MAIN 433
7741	ISEPT=1	MAIN 434
	NITS=NITS+1	MAIN 435
	IF(INDT) 7743,7743,7643	MAIN 436
7643	ISEPT=1	MAIN 437
	DXSEP=1.-XSEP	MAIN 438
	XSEP=.6*XSEP+.4	MAIN 439
	CALL CPC(ISEPT,NGAM,NF,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,	MAIN 440
	1THICK,RDRB,GAMAW,UINF,UDOT,1.,XSEP,DXI,CP1)	MAIN 441
	GO TO 3248	MAIN 442
7742	CALL ELDER(BCAP,XSIG,NSIG,UINF,ELDOT,SIGSUM,YMX)	MAIN 443
	IF(ISEPT.EQ.1.AND.ISEPT.EQ.0.AND.NITS.EQ.1) GO TO 9210	MAIN 444
	IF(XSEP+.5) 7841,7842,7842	MAIN 445
7841	EPS=EPSLE	MAIN 446
	GO TO 7843	MAIN 447
7842	EPS=EPSTE	MAIN 448
7843	DXSEP=ABS(XSEP-XSEPS)	MAIN 449
	IF(DXSEP-EPS) 7834,7834,9210	MAIN 450
7834	IF(XSEP-XMAX) 1786,1786,7835	MAIN 451
7835	ISEPT=0	MAIN 452
	ISEPT=0	MAIN 453
	DO 7836 K=1,3	MAIN 454
	DO 7836 N=1,NSIG	MAIN 455
7836	BCAP(N,K)=0.	MAIN 456
	GO TO 1786	MAIN 457
9210	NITS=NITS+1	MAIN 458
	IF(NITS.EQ.2.AND.INDT.EQ.0) XSEPS=XSEP	MAIN 459
	IF(NITS-4) 9211,9211,1786	MAIN 460
9211	IF(XSEP-XSEPS) 9305,9305,9306	MAIN 461
9305	XSEP=.6*XSEPS+.4*XSEP	MAIN 462
	GO TO 9307	MAIN 463
9306	XSEP=.6*XSEP+.4*XSEPS	MAIN 464
9307	IF(XSEP-XMAX) 9212,9212,7835	MAIN 465
9212	CALL CPC(ISEPT,NGAM,NF,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,	MAIN 466
	1THICK,RDRB,GAMAW,UINF,UDOT,1.,XSEP,DXI,CP1)	MAIN 467
	IF( NOTBL .EQ. 2 .AND. XSEP .GT. 0.) XSEP=-.98	
	GO TO 3248	MAIN 468
7743	IF(NITS-1) 7737,7737,3248	MAIN 469

7737	NITS=NITS+1	MAIN 470
	ELDOT=ELDI	MAIN 471
	GO TO 3248	MAIN 472
1786	WRITE(MOUT,20) NTIME	MAIN 473
	WRITE(MOUT,26) XIVOR	MAIN 477
	PITC = PITCH * 180. / PI	
209	WRITE(MOUT,10) TIME,UINF,XSEP,XATT,PITC	MAIN 473
	ALDFG= ALPH1/DEGRFS	SUPPL349
	WRITE(6,9001) Z,ALDEG,ALPH1, ALPH2, HEAVE	SUPPL350
	IF( PSI360 .GE. PSILOW .AND. PSI360 .LE. PSIUP) GO TO 101	
	IF( NOUT .EQ. 0)	
	1WRITE(MOUT,11)	MAIN 479
	IF( NOUT .EQ. 0)	
	1WRITE(MOUT,12) (N,XGAM(N),VZIP(N),AR(N),ACAP(N,1),XIW(N),GAMAW(N),	MAIN 480
	2N=1,NGPI)	MAIN 481
	IF(ISEP) 7432,7433,7432	MAIN 482
7432	IF( NOUT .EQ. 0)	
	1WRITE(MOUT,13)	MAIN 483
	IF( NOUT .EQ. 0)	
	1WRITE(MOUT,17) (N,XBSIG(N),FPRES(N),ARH(N),BCAP(N,1),N=1,NSIG)	MAIN 484
	WRITE(MOUT,14) ELDOT	MAIN 485
	WRITE(MOUT,18) XSIG(1),CPOT,X4,CPOT,XATT,PREC	MAIN 486
7433	WRITE(MOUT,15)	MAIN 487
	XPC=-1.	MAIN 488
	DO 7102 N=1,NCPI	MAIN 489
	CALL QECAL(ISEP,NGAM,NSIG,NF,XSIG,ACAP,BCAP,THICK,RDBB,GAMAW(1),UI	MAIN 490
	INF,XPC,QFL,-1.)	MAIN 491
	CALL QECAL(ISEP,NGAM,NSIG,NF,XSIG,ACAP,BCAP,THICK,RDBB,GAMAW(1),UI	MAIN 492
	INF,XPC,QUE,1.)	MAIN 493
	CALL CPC(ISEP,NGAM,NF,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,	MAIN 494
	1THICK,RDBB,GAMAW,UINF,JDOT,1.0,XPC,DXI,CPU)	MAIN 495
	CALL CPC(ISEP,NGAM,NF,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,	MAIN 496
	1THICK,RDBB,GAMAW,UINF,UDOT,-1.,XPC,DXI,CPL)	MAIN 497
	IF(N-1) 7546,7545,7546	MAIN 498
7545	CPL=CPU	MAIN 499
7546	DLIFT=CPL-CPU	MAIN 500
	WRITE(MOUT,16) XPC,QEL,CPL,QUE,CPU,DLIFT	MAIN 501
7102	XPC=XPC+PINT	MAIN 502
101	CONTINUE	
	CMPAS=CMPA	MAIN 503
	CALL CLCMT(NCOT,ISEP,NGAM,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,RC	MAIN 504
	1AP,THICK,RDBB,GAMAW,UINF,UDOT,DXI,AROT,CMPA)	MAIN 505
	P(L,2) = PITC	
	P(L,3) = Z(3)	
	P(L,4) = Z(1)	
	P(L,5) = Z(2)	
	P(L,6) = CLVR	
	P(L,7) = CMPA	
	IF( L .LT. 200 ) GO TO 98	
	CALL PLOTSB( PLOTOP , P , L )	
	L= 0	
98	CONTINUE	
	IF(ISTD .EQ. 1) GO TO 9999	
	DO 7950 M=1,MX	MAIN 506
	SCALE(M,2)=SCALE(M,1)	MAIN 507

SCALE(M,1)=SCALS(M)	MAIN 508
DC 7950 N=1,NY	MAIN 509
U(M,N,2)=U(M,N,1)	MAIN 510
7950 U(M,N,1)=USAV(M,N)	MAIN 511
GO TO 9999	MAIN 512
8989 CONTINUE	MAIN 513
99 CONTINUE	
CALL PLOTSB( PLOTOP , P , L )	
CALL ACUCPU( IACU )	
IF( IACU.LT. 35000 ) GO TO 60	
GO TO 40	
60 CONTINUE	
IF( PLOTOP.EQ. 0.) CALL EXIT	
CALL PLTND	
CALL EXIT	
RETURN	
C	
C	
C	
C	
1 FORMAT(13I5)	MAIN 23
2 FORMAT(3F10.4)	MAIN 24
3 FORMAT(2F10.4)	MAIN 25
4 FORMAT(1H1//)	MAIN 26
5 FORMAT(6F10.4)	MAIN 27
6 FORMAT(1H1,50X,34H ANALYSIS OF UNSTEADY AIRFOIL STALL///)	MAIN 28
7 FORMAT(8X,6HUBAR =E13.5/7X,7HUFREQ =E13.5//3X,11HALPHA ONE =E13.5/MAIN 29	
13X,11HALPHA TWO =E13.5/8X,6HHBAR =E13.5/11X,3HA =E13.5/8X,6HFREQ =MAIN 30	
1E13.5//8X,6HRO/B =E13.5//9X,5HREB =E13.5//)	MAIN 31
8 FORMAT(29X,1HN,25X,4HC(N),26X,4HT(N)/)	MAIN 32
9 FORMAT(130,2E30.5)	MAIN 33
10 FORMAT(5X,3HT =E13.5/5X,3HU =E13.5/4X,4HXS =E13.5/4X,4HXO =E13.5/4MAIN 34	
1X,4HPA =E13.5//))	MAIN 35
11 FORMAT(///4X,1HN,11X,1HX,14X,5HVZ(X),12X,5HRN(X),12X,4HA(N),21X,3HMAIN 36	
1XIW,14X,5HGAMMA/)	MAIN 37
12 FORMAT(15,4E17.5,8X,2E17.5)	MAIN 38
13 FORMAT(1H1,8X,1HN,20X,1HX,21X,5HFP(X),22X,5HRH(N),21X,4HB(N)/)	MAIN 39
14 FORMAT(//54X,9H L-DCT =E13.5//51X,27HPRESSURES IN SEPARATED FLOWMAIN 40	
1//55X,1HX,19X,2HCP/)	MAIN 41
15 FORMAT(1H1,11X,1HX,16X,3HQEL,15X,3HCPL,15X,3HQEU,15X,3HCPU,13X,9HCMMAIN 42	
1PL - CPU/)	MAIN 43
16 FORMAT(6E18.5)	MAIN 44
17 FORMAT(110,4E25.5)	MAIN 45
18 FORMAT(3140X,2E20.5//)	MAIN 46
19 FORMAT(15,5F10.4)	MAIN 47
20 FORMAT(1H1,50X,12H TIME STEP NO13//)	MAIN 48
22 FORMAT(///40X,26H INCREASE IN CP REQUIRED ISE13.5//40X,26H INCREASE MAIN 49	
1IN CP POSSIBLE ISE13.5)	MAIN 50
23 FORMAT(///45X,23HPOTENTIAL FLOW XS =E12.4/60X,8HCP(XS) =E12.4/MAIN 51	
1/45X,23HBOUNDARY LAYER XS =E12.4)	MAIN 52
24 FORMAT(15,4F10.4/5F10.4)	MAIN 53
25 FORMAT(12X,4HNV =E12.4,3X,3HS =E12.4,3X,3HM =E12.4,3X,3HG =E12.4,3X,4MAIN 54	
1HX1 =E12.4//12X,4HMI =E12.4,3X,4HWT =E12.4,3X,4HPA =E12.4//))	MAIN 55
26 FORMAT(4X,4HX1 =E13.5)	MAIN 56
9001 FORMAT('0', Y50, 'EQUIVALENT ROTOR BLADE RESPONSE'	SUPPL380

9001A	//	T 5,	'FLAP DISP =',	G14.5	SUPPL381
9001B	,	T47,	'RENDING DISP =',	G14.5	SUPPL382
9001C	,	T39,	'TORSIONAL DISP =',	G14.5	SUPPL383
9001D	/	T38,	'SECTION PITCH ANGLE =',	F9.3, ' DEGREES OR ',	SUPPL384
9001E				F9.4, ' RADIANS '	SUPPL385
9001F	/	T21,	'SECTION PITCH RATE =',	G14.5	SUPPL386
9001G	,	T71,	'SECTION PLUNGING RATE =',	G14.5     //)	SUPPL387
END					MAIN 515

	SUBROUTINE SUPPL	SUPPL 1
	IMPLICIT REAL*8 (A-H,O-Z)	SUPPL 2
	REAL*8 FR1S, FR2S, FR3S, ANSX, OMS	SUPPL 3
C		SUPPL 4
	REAL*4 CLVB, CMVB, CMPAVB	
	1, DUMMY, PLOTOP	
	REAL FTVB, FPVB, FPPRVB, DIDRVB, XMVB, DELVB, XMUVB,	SUPPL 5
A	FOVB, XMUAVB, ATOVB, ATCVB, ATSVB, ROVB, RVB, MVB,	SUPPL 6
C	WDXI, PSI, UINF	SUPPL 7
	REAL ELSIG, DXI, REB, RDBR, FRZ, ARR, AMPLU, FREQU,	SUPPL 8
A	ALPH1, ALPH2, HEAVE, AROT, FREQF, PHIH, RY1, DRY,	SUPPL 9
B	X, TEST, UPRIM, XU, YU, XL, YL, ER1, ER2, ER3, BDBR,	SUPPL 10
C	RROBR	SUPPL 11
	REAL SUM(8), YCLD(8), YNEW(8), DEL(3,3), CMPA(3), CL(3), G(3),	SUPPL 12
A	Z, ZPR(3), SMALLG(3), Y(3,3), YPR(3,3), GCAP(3,3)	SUPPL 13
	COMMON /BL1/ NTIME, NDIMC	
	COMMON /CLCMBL/ CLVB, CMVB, CMPAVB	MAIN
	COMMON /ZZZ/ Z(3)	
	COMMON /INPTVB/ FTVB(64), FPVB(64), FPPRVB(64), DIDRVB(64),	SUPPL 15
A	XMVB(64), DELVB, XMUVB, FOVB, XMUAVB,	SUPPL 16
B	ATOVB, ATCVB, ATSVB, ROVB, RVB(64),	SUPPL 17
C	MVB(64), NVB	SUPPL 18
	COMMON /INPUTS/ NSBL, NZ, NOFF, NGAM, NSIG,	SUPPL 19
A	NCOI, NCORD, LOWER, MSTOP, MAXT, MCTR,	SUPPL 20
B	NOTBL, INDV, ELSIG, DXI, REB, RDBR,	SUPPL 21
C	FRZ, ARR, AMPLU, FREQU, ALPH1, ALPH2,	SUPPL 22
D	HEAVE, AROT, FREQF, PHIH, NY, RY1,	SUPPL 23
E	DRY, X(100), TEST, UPRIM, XU(30), YU(30),	SUPPL 24
F	XL(30), YL(30), ER1, ER2, ER3, BDBR,	SUPPL 25
G	RROBR	SUPPL 26
	H, DUMMY(10), PLOTOP	
	DIMENSION DELTA(3,3)	SUPPL 27
	DIMENSION ALPHA(3,3), BETA(3,3), GAMMA(3,3), OMS(3), OMEGA(3), CHK(3)	SUPPL 28
	DIMENSION AA(10), AB(10), ANB(20), ANT(20), AAX(10), ANSX(20), SORT(3)	SUPPL 29
	1, TOT(2)	
	CF4(X)=F4-B4+(B4*C6-C4)*X*X	SUPPL 30
	Z1(X)=HB*(CF4(X)/GB)**2+(CF4(X)*FR1S+(1.-C6*X*X)*B2-F2)*X*X	SUPPL 31
	Z2(X)=(FZ/FR1S+FR1S*CF4(X)-F2+(1.-C6*X*X)*(B2-BZ/FR1S))*X*X	SUPPL 32
	S1(X)=(2.*HB*CF4(X)/GB**2+(FR1S-FR2S)*X*X)*GA	SUPPL 33
	S2(X)=(FR1S-FR2S)*GA*X*X	SUPPL 34
	FUN(X)=(R1*Z2(X)-R2*Z1(X))**2+(R1*S2(X)-R2*S1(X))*(Z2(X)*S1(X)-Z1(X)*S2(X))	SUPPL 35
	1X)*S2(X))	SUPPL 36
	DATA BBS,REL,NPOL/1.E-7,1.E-6,3/	SUPPL 39
C		SUPPL 40
C	MASSSES AND H'S ARE NONDIMENSIONAL, WITH BLADE MASS AND RADIUS	SUPPL 41
C	AS REFERENCES. NONROTATING NATURAL FREQUENCIES ARE	SUPPL 42
C	DIMENSIONLESS, USING ROTOR SPEED AS REFERENCE. DISTANCES XBAB, SILB,	SUPPL 43
C	AND S2LB ARE FRACTIONS OF SEMICORD. XBAR, SIL, AND S2L ARE	SUPPL 44
C	FRACTIONS OF ROTOR RADIUS.	SUPPL 45
C		SUPPL 46
	NDIMC=3	
	DO 63 K = 1, 8	SUPPL 47
	SUM(K) = 0.	SUPPL 48
63	YNEW(K) = 0.	SUPPL 49
	DO 69 I = 1, NVB	SUPPL 50

	DO 66 K = 1, 8	SUPPL 51
66	YOLD(K) = YNEW(K)	SUPPL 52
	CALL YVB(YNEW,I)	SUPPL 53
	IF(I .LE. 1) GO TO 69	SUPPL 54
	DO 67 K = 1, 8	SUPPL 55
67	SUM(K) = (YNEW(K) + YOLD(K)) * (RVB(I) - RVB(I-1)) / 2. + SUM(K)	SUPPL 56
69	CONTINUE	SUPPL 57
	EM11 = SUM(1)	SUPPL 59
	EM22 = SUM(2)	SUPPL 60
	EM33 = SUM(3)	SUPPL 61
	EM13 = SUM(4)	SUPPL 62
	EM23 = SUM(5)	SUPPL 63
	H11 = SUM(6)	SUPPL 64
	H22 = SUM(7)	SUPPL 65
	H33 = - EM33	SUPPL 66
	H13 = -EM13	SUPPL 67
	H23 = SUM(8)	SUPPL 68
	BDBRR=BDBR/RRDBR	SUPPL 69
	BDS=BDBRR**2	SUPPL 70
	T11=H11*BDS	SUPPL 71
	T22=H22*BDS	SUPPL 72
	T33=H33*BDS	SUPPL 73
	T13=H13*BDS	SUPPL 74
	T23=H23*BDS	SUPPL 75
	FR1S=BDS*ER1**2-T11/EM11	SUPPL 76
	FR2S=ER2**2*BDS-T22/EM22	SUPPL 77
	FR3S=ER3**2*BDS-T33/EM33	SUPPL 78
	FR1=DSQRT(FR1S)	SUPPL 79
	FR2=DSQRT(FR2S)	SUPPL 80
	FR3=DSQRT(FR3S)	SUPPL 81
	RATM=EM11/EM22	SUPPL 82
	ZETA=(1.+RATM)*((RATM*FR1S**2+FR2S**2)/(RATM*FR1S+FR2S)**2	SUPPL 83
	RM=ZETA-1.	SUPPL 84
	SUMS=FR1S+FR2S	SUPPL 85
	HIGHS=(SUMS+DSQRT(SUMS**2-4.*ZETA*FR1S*FR2S))/(2.*ZETA)	SUPPL 86
	SMALS=FR1S*FR2S/HIGHS	SUPPL 87
	DEN=FR2S-FR1S	SUPPL 88
	A1=-(HIGHS-FR1S)/DEN	SUPPL 89
	A2=-1.-A1	SUPPL 90
	B=-A1*A2*DEN/HIGHS	SUPPL 91
	SLAM1=EM11*BDBR**2/EM33	SUPPL 92
	SLAMZ=-A1*SLAM1	SUPPL 93
	SLAM2=-SLAMZ/A2	SUPPL 94
	SUM3=SUMS+FR3S	SUPPL 95
	ADD2=FR1S*(FR2S+FR3S)+FR2S*FR3S	SUPPL 96
	ADDZ=FR1S*FR2S*FR3S	SUPPL 97
	BBAR=1.-(EM13**2/EM11+EM23**2/EM22)/EM33	SUPPL 98
	B4=SUM3+(2.*EM23*T23/EM22+2.*EM13*T13/EM11-FR1S*EM23**2/EM22-FR2S*	SUPPL 99
	EM13**2/EM11)/EM33	SUPPL 100
	B4=B4/BBAR	SUPPL 101
	B2=ADD2+T2.*FR2S*EM13*T13/EM11+2.*FR1S*EM23*T23/EM22-T13**2/EM11-T	SUPPL 102
	123**2/EM22)/EM33	SUPPL 103
	B2=B2/BBAR	SUPPL 104
	BZ=ADDZ-(FR2S*T13**2/EM11+FR1S*T23**2/EM22)/EM33	SUPPL 105
	BZ=BZ/BBAR	SUPPL 106

C6=(EM11*A1**2+EM22*A2**2)/EM33	SUPPL107
F4=SUM3	SUPPL108
C4=(FR2S*EM11*A1**2+FR1S*EM22*A2**2)/EM33	SUPPL109
GA=2.*EM11*A1/EM33	SUPPL110
GB=2.*EM22*A2/EM33	SUPPL111
F2=ADD2	SUPPL112
HA=EM11/EM33	SUPPL113
HB=EM22/EM33	SUPPL114
FZ=ADDZ	SUPPL115
R1=-HA-HB*(GA/GB)**2	SUPPL116
R2=HA*(FR2S/FR1S-1.)	SUPPL117
ZLAM=F4-B4	SUPPL118
TWLAM=B4*C6-C4	SUPPL119
FZHAT=HB*(ZLAM/GB)**2	SUPPL120
F2HAT=B2-F2+FR1S*ZLAM+2.*ZLAM*TWLAM*HB/GB**2	SUPPL121
F4HAT=-C6*R2+FR1S*TWLAM+HB*(TWLAM/GB)**2	SUPPL122
G2HAT=B2-F2*(FZ-BZ)/FR1S+FR1S*ZLAM	SUPPL123
G4HAT=-C6*(B2-BZ/FR1S)+FR1S*TWLAM	SUPPL124
SIGZ=2.*HB*ZLAM*GA/GB**2	SUPPL125
SIG2=GA*(FR1S-FR2S+2.*HB*TWLAM/GB**2)	SUPPL126
GAM2=GA*(FR1S-FR2S)	SUPPL127
UZ=-R2*FZHAT	SUPPL128
U1=R1*G2HAT-R2*F2HAT	SUPPL129
U2=R1*G4HAT-R2*F4HAT	SUPPL130
U3=-R2*SIGZ	SUPPL131
U4=R1*GAM2-R2*SIG2	SUPPL132
U5=SIGZ*G2HAT-GAM2*FZHAT	SUPPL133
U6=SIGZ*G4HAT+SIG2*G2HAT-GAM2*F2HAT	SUPPL134
U7=SIG2*G4HAT-GAM2*F4HAT	SUPPL135
AAX(1)=UZ**2	SUPPL136
AAX(2)=2.*UZ*U1+U3*U5	SUPPL137
AAX(3)=U1**2+2.*UZ*U2+U3*U6+U4*U5	SUPPL138
AAX(4)=2.*U1*U2+U3*U7+U4*U6	SUPPL139
AAX(5)=U2**2+U4*U7	SUPPL140
CALL POLLY(4,RBS,REL,ANSX,AAX)	SUPPL141
XBAR=1.E25	SUPPL142
DO 86 I=1,4	SUPPL143
IP=2*I	SUPPL144
IM=IP-1	SUPPL145
IF(DABS(ANSX(IM)).GT.1.D-10) GO TO 86	SUPPL146
IF(ANSX(IP).LE.0.) GO TO 86	SUPPL147
XBART=DSQRT(ANSX(IP))	SUPPL148
IF(XBART.LT.XBAR) XBAR=XBART	SUPPL149
86 CONTINUE	SUPPL150
IF(XBAR.LT..5E25) GO TO 88	SUPPL151
WRITE(6,87)	SUPPL152
87 FORMAT(1H1,10X,'NO SOLUTION FOR XBAR')	SUPPL153
STOP	SUPPL154
88 CONTINUE	SUPPL155
15 ALOW=(R1*Z2(XBAR)-R2*Z1(XBAR))/(R1*S2(XBAR)-R2*S1(XBAR))	SUPPL156
ALOW=ALOW/XBAR	SUPPL157
BLOW=(CF4(XBAR)-GA*ALOW*XBAR)/(XBAR*CB)	SUPPL158
XI=-ALOW-BLOW	SUPPL159
ETA=(BLOW*A1-ALOW*A2)/(A1-A2)	SUPPL160
S2L=FYA/(B*HIGHS)	SUPPL161

SIL=(XI-RM*HIGHS*S2L)*HIGHS/(FR1S*FR2S)	SUPPL162
WRITE(6,4) FR1,ER2,EF3,RM	SUPPL163
WRITE(6,721) FR1,FR2,FR3,ALOW,BLOW	SUPPL164
WRITE(6,5) EM11,EM22,EM33,FM13,EM23	SUPPL165
WRITE(6,6) H11,H22,H33,H13,H23	SUPPL166
C13=ALOW/BDBR	SUPPL167
C23=BLOW/BDBR	SUPPL168
XBAR=XPAR/BDBR	SUPPL169
S1LB=S1L/BDBR	SUPPL170
S2LB=S2L/BDBR	SUPPL171
WRITE(6,41) BDBR,RRDBR	SUPPL172
WRITE(6,7) XBAR,X9AB,S1L,S1LB,S2L,S2LB,SMALS,HIGHS	SUPPL173
AA(1)=B7	SUPPL174
AA(2)=B2	SUPPL175
AA(3)=B4	SUPPL176
AA(4)=1.	SUPPL177
CALL POLLY(NPOL,BBS,REL,ANB,AA)	SUPPL178
SSX=SLAMZ*XBAR	SUPPL179
DIV=1.-SLAMZ*XBAR**2	SUPPL180
BETA(3,1)=(SLAM1*C13+SSX*FR1S)/DIV	SUPPL181
BETA(3,2)=(SLAM2*C23+SSX*FR2S)/DIV	SUPPL182
BETA(3,3)=(FR3S+SSX*(C13+C23))/DIV	SUPPL183
AXB=A1*XBAR	SUPPL184
BETA(1,1)=FR1S-AXB*BETA(3,1)	SUPPL185
BETA(1,2)=-AXB*BETA(3,2)	SUPPL186
BETA(1,3)=C13-AXB*BETA(3,3)	SUPPL187
AAXB=A2*XBAR	SUPPL188
BETA(2,1)=-AAXB*BETA(3,1)	SUPPL189
BETA(2,2)=FR2S-AAXB*BETA(3,2)	SUPPL190
BETA(2,3)=C23-AAXB*BETA(3,3)	SUPPL191
AB(4)=1.	SUPPL192
AB(3)=BETA(1,1)+BETA(2,2)+BETA(3,3)	SUPPL193
AB(2)=BETA(1,1)*(BETA(2,2)+BETA(3,3))+BETA(2,2)*BETA(3,3)-BETA(3,2)	SUPPL194
1)*BETA(2,3)-BETA(1,2)*BETA(2,1)-BETA(1,3)*BETA(3,1)	SUPPL195
AB(1)=BETA(1,1)*(BETA(2,2)*BETA(3,3)-BETA(3,2)*BETA(2,3))-BETA(2,1)	SUPPL196
1)*(BETA(1,2)*BETA(3,3)-BETA(3,2)*BETA(1,3))+BETA(3,1)*(BETA(1,2)*B	SUPPL197
ETA(2,3)-BETA(1,3)*BETA(2,2))	SUPPL198
CALL POLLY(NPOL,BBS,REL,ANT,AB)	SUPPL199
WRITE(6,44)	SUPPL200
DO 45 I=1,4	SUPPL201
IM=(I-1)*2	SUPPL202
45 WRITE(6,46) IM,AA(I),AB(I)	SUPPL203
WRITE(6,47)	SUPPL204
DO 48 I=1,3	SUPPL205
ITT=2*I	SUPPL206
ITM=ITT-1	SUPPL207
48 WRITE(6,49) ANB(ITT),ANB(ITM),ANT(ITT),ANT(ITM)	SUPPL208
DO 301 I=1,3	SUPPL209
II=2*I	SUPPL210
301 OMS(I)=-ANT(II)	SUPPL211
MAXI=3	SUPPL212
DO 70 I=1,2	SUPPL213
IF(OMS(I).GT.OMS(MAXI)) MAXI=I	SUPPL214
70 CONTINUE	SUPPL215
GO TO (71,72,73),MAXI	SUPPL216



71	I1=2	SUPPL217
	I2=3	SUPPL218
	GO TO 74	SUPPL219
72	I1=1	SUPPL220
	I2=3	SUPPL221
	GO TO 74	SUPPL222
73	I1=1	SUPPL223
	I2=2	SUPPL224
74	IF (OMS(I1).GT.OMS(I2)) GO TO 75	SUPPL225
	MINI=I1	SUPPL226
	MIDI=I2	SUPPL227
	GO TO 76	SUPPL228
75	MINI=I2	SUPPL229
	MIDI=I1	SUPPL230
76	SORT(1)=OMS(MINI)	SUPPL231
	SORT(2)=OMS(MIDI)	SUPPL232
	SORT(3)=OMS(MAXI)	SUPPL233
	DO 77 I=1,3	SUPPL234
	OMS(I)=SORT(I)	SUPPL235
77	OMEGA(I)=DSQRT(CMS(I))	SUPPL236
	DO 302 I=1,3	SUPPL237
302	ALPHA(I,I)=1.	SUPPL238
	DENB=BETA(2,1)*BETA(3,2)-BETA(3,1)*(BETA(2,2)-OMS(1))	SUPPL239
	ALPHA(1,2)=(BETA(1,2)*BETA(3,1)-BETA(3,2)*(BETA(1,1)-OMS(1)))/DENB	SUPPL240
	ALPHA(1,3)=((BETA(2,2)-OMS(1))*(BETA(1,1)-OMS(1))-BETA(1,2)*BETA(2,3))	SUPPL241
	1,1)/DENB	SUPPL242
	CHK(1)=BETA(1,3)*ALPHA(1,1)+BETA(2,3)*ALPHA(1,2)+(BETA(3,3)-OMS(1))	SUPPL243
	1)*ALPHA(1,3)	SUPPL244
	DENB=BETA(3,2)*(BETA(1,1)-CMS(2))-BETA(3,1)*BETA(1,2)	SUPPL245
	ALPHA(2,1)=(BETA(3,1)*(BETA(2,2)-OMS(2))-BETA(2,1)*BETA(3,2))/DENB	SUPPL246
	ALPHA(2,3)=(BETA(2,1)*BETA(1,2)-(BETA(1,1)-OMS(2))*(BETA(2,2)-OMS(2)))	SUPPL247
	12))/DENB	SUPPL248
	CHK(2)=BETA(1,3)*ALPHA(2,1)+BETA(2,3)*ALPHA(2,2)+(BETA(3,3)-OMS(2))	SUPPL249
	1)*ALPHA(2,3)	SUPPL250
	DENB=BETA(2,3)*(BETA(1,1)-CMS(3))-BETA(1,3)*BETA(2,1)	SUPPL251
	ALPHA(3,1)=(BETA(2,1)*(BETA(3,3)-OMS(3))-BETA(3,1)*BETA(2,3))/DENB	SUPPL252
	ALPHA(3,2)=(BETA(3,1)*BETA(1,3)-(BETA(1,1)-OMS(3))*(BETA(3,3)-OMS(3)))	SUPPL253
	13))/DENB	SUPPL254
	CHK(3)=BETA(1,2)*ALPHA(3,1)+(BETA(2,2)-OMS(3))*ALPHA(3,2)+BETA(3,2)	SUPPL255
	1)*ALPHA(3,3)	SUPPL256
	WRITE(6,488)	SUPPL257
	WRITE(6,489) (I,OMEGA(I),BETA(I,1),BETA(I,2),BETA(I,3),ALPHA(I,1),	SUPPL258
	1)ALPHA(I,2),ALPHA(I,3),CHK(I),I=1,3)	SUPPL259
	SORT(1)=1.	SUPPL260
	SORT(2)=0.	SUPPL261
	SORT(3)=0.	SUPPL262
	DO 432 J=1,3	SUPPL263
	GO TO (381,382,383), J	SUPPL264
382	SORT(1)=0.	SUPPL265
	SORT(2)=1.	SUPPL266
	SORT(3)=0.	SUPPL267
	GO TO 381	SUPPL268
383	SORT(1)=0.	SUPPL269
	SORT(2)=0.	SUPPL270
	SORT(3)=1.	SUPPL271

381	DO 384 I=1,3	SUPPL272
	DO 384 K=1,3	SUPPL273
384	DELTA(I,K)=ALPHA(I,K)	SUPPL274
	CALL ALSOL(3,DELTA, SORT, 3)	SUPPL275
	DO 431 I=1,3	SUPPL276
431	GAMMA(I,J)=SORT(I)	SUPPL277
432	CONTINUE	SUPPL278
	WRITE(6,11)	SUPPL279
	WRITE(6,12) (I,GAMMA(I,1),GAMMA(I,2),GAMMA(I,3),I=1,3)	SUPPL280
	AMPLU = XMUAVB * (1. - ROVB**3) / (1. - ROVB**4) * 1.3333333333333333	SUPPL284
	SA = SMALS * S1LB + RM * S2LB * HIGHS	SUPPL285
	SB = SMALS * S1LB**2 + RM * S2LB**2 * HIGHS	SUPPL286
	DEL(1,1) = XMUVB * (1. - ROVB**4) / (4. * (1. - SLAMZ * XBAB**2)	SUPPL287
A	* RRDBR * FM11)	SUPPL288
	DEL(1,2) = 2. * SLAMZ * XBAB * DEL(1,1)	SUPPL289
	DEL(1,3) = A1 * (SLAMZ * XBAB * SB - SA) / (1. - SLAMZ * XBAB**2)	SUPPL290
A	+ B * HIGHS * S2LB	SUPPL291
	DEL(2,1) = A2 / A1 * DEL(1,1)	SUPPL292
	DEL(2,2) = A2 / A1 * DEL(1,2)	SUPPL293
	DEL(2,3) = A2 * (SLAMZ * XBAB * SB - SA) / (1. - SLAMZ * XBAB**2)	SUPPL294
A	- R * SMALS * S2LB	SUPPL295
	DEL(3,1) = - SLAMZ * XBAB * DEL(1,1) / A1	SUPPL296
	DEL(3,2) = -2. * SLAMZ * DEL(1,1) / A1	SUPPL297
	DEL(3,3) = (BDBR / RRDBR)**2 + SLAMZ * (XBAB * SA - SR) /	SUPPL298
A	(1. - SLAMZ * XBAB**2)	SUPPL299
	CMPA(2) = CMPAVB	MAIN
	CL(2) = CLVB	MAIN
	NDIMC = 63	
	COSPSI = 1.	
	SINPSI = 0.	
	TO = ATOVB + ATCVB * COS PSI + ATSVB * SIN PSI	
	TOT(1) = TO - ATOVB	
	DO 50 I=1,3	
50	SMALLG(I) = DEL(I,1) * CLVB + DEL(I,2) * CMPAVB	
	DO 51 I=1,3	
	GCAP(I,1)=0.	
	DO 52 J=1,3	
	YPR(I,J)=0.	
52	GCAP(I,1) = GCAP(I,1) + ALPHA(I,J) * SMALLG(J)	
	GCAP(I,2)=GCAP(I,1)	
	Y(I,1)=GCAP(I,1) / CMS(I)	
51	Y(I,2) = Y(I,1)	
	IF ( PLOTOP .LT. 0.)	
	1 WRITE( 6,9000) TO, Z, TOPR, ZPR, Y, YPR, DEL, SMALLG	
9000	FORMAT(// ' TO= ', 1P1E13.6, ' Z= ', 1P3E13.6, ' TOPR= ', 1P1E13.6	
	1, ' ZPR= ', 1P3E13.6 / ' Y= ', 1P9E13.6/ ' YPR= ', 1P9E13.6	
	2 / ' DEL= ', 1P9E13.6/ ' SMALLG= ', 1P9E13.6//)	
	RETURN	SUPPL300
C		SUPPL301
C		SUPPL302
	ENTRY SUPPI (UINF)	SUPPL303
C		SUPPL304
C		SUPPL305
	CMPA(3) = CMPA(2)	SUPPL306
	CMPA(2) = CMPAVB	MAIN

	CPMA(1) = 2. * CPMA(2) - CPMA(3)	SUPPL308
	CL(3) = CL(2)	SUPPL309
	CL(2) = CLVB	MAIN
	CL(1) = 2. * CL(2) - CL(3)	SUPPL311
	PSI = (BDRR / RRDBR) * NTIME * DXI	SUPPL312
	SIN PSI = SIN(PSI)	SUPPL313
	COS PSI = COS(PSI)	SUPPL314
	TOT(2) = TOT(1)	
	TO = ATOVb + ATCVb * COS PSI + ATSVb * SIN PSI	SUPPL315
	TOT(1) = TO - ATOVb	
	TO PR = (BDRR / RRDBR) * (ATSVb * COS PSI - ATCVb * SIN PSI)	SUPPL316
	DO 60 K = 1, 2	
	DO 64 I = 1, 3	SUPPL317
64	SMALL G(I) = UINF **2 * (DEL(I,1) * CL(K) + DEL(I,2) * CPMA(K))	
A	+ DEL(I,3) * TOT(K)	SUPPL319
	DO 65 I = 1, 3	SUPPL320
	G CAP(I, K) = 0.	
	DO 65 J = 1, 3	SUPPL322
65	G CAP(I, K) = GCAP(I, K) + ALPHA(I,J) * SMALLG(J)	
60	CONTINUE	
	DO 62 I = 1, 3	SUPPL328
	Y(I,2) = Y(I,1)	SUPPL329
	YPR(I,2) = YPR(I,1)	SUPPL330
	WDXI = OMEGA(I) * DXI	SUPPL331
	SWDXI = SIN(WDXI)	SUPPL332
	CWDXI = COS(WDXI)	SUPPL333
	Y(I,1) = Y(I,2) * CWDXI + YPR(I,2) * SWDXI / OMEGA(I)	SUPPL334
A	+ ((GCAP(I,2) - GCAP(I,1)) * (SWDXI - WDXI * CWDXI) / WDXI	SUPPL335
B	+ GCAP(I,1) * (1. - CWDXI) / OMEGA(I))**2	SUPPL336
62	YPR(I,1) = YPR(I,2) * CWDXI - OMEGA(I) * Y(I,2) * SWDXI	SUPPL337
A	+ ((GCAP(I,2) - GCAP(I,1)) * (WDXI * SWDXI + CWDXI - 1.)	SUPPL338
B	/ WDXI + GCAP(I,1) * SWDXI) / OMEGA(I)	SUPPL339
	DO 61 I = 1, 3	SUPPL340
	Z(I) = 0.	SUPPL341
	ZPR(I) = 0.	SUPPL342
	DO 61 J = 1, 3	SUPPL343
	Z(I) = Z(I) + GAMMA(I,J) * Y(J,1)	SUPPL344
61	ZPR(I) = ZPR(I) + GAMMA(I,J) * YPR(J,1)	SUPPL345
	ALPH1 = TO + Z(3)	SUPPL346
	ALPH2 = TO PR + ZPR(3)	SUPPL347
	HEAVE = - ZPR(1) - ZPR(2)	
	IF ( PLOTOP .LT. 0.)	
	1 WRITE( 6,9000) TO, Z, TOPR, ZPR, Y, YPR, DEL, SMALLG	
	2, TOT	
	RETURN	SUPPL351
1	FORMAT(5F10.4)	SUPPL352
2	FORMAT(5F10.4)	SUPPL353
3	FORMAT(1H1,10X,'ITERATION FOR XBAR DIVERGED')	SUPPL354
4	FORMAT(1H1,5X,4HF1 =E13.5,5X,4HF2 =E13.5,5X,4HF3 =E13.5//5X,4HRM =E13.5//)	SUPPL355
	1E13.5///)	SUPPL356
5	FORMAT(5X,5HM11 =E13.5,5X,5HM22 =E13.5,5X,5HM33 =E13.5,5X,5HM13 =E13.5,5X,5HM23 =E13.5//)	SUPPL357
	113.5,5X,5HM23 =E13.5//)	SUPPL358
6	FORMAT(5X,5HT11 =E13.5,5X,5HT22 =E13.5,5X,5HT33 =E13.5,5X,5HT13 =E13.5,5X,5HT23 =E13.5//)	SUPPL359
	113.5,5X,5HT23 =E13.5//)	SUPPL360
7	FORMAT(20X,6HX8/R =E13.5,10X,6HX8/B =E13.5/20X,6H1/R =E13.5,10X,6H1/B =E13.5//)	SUPPL361

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1HL1/B =E13.5/20X,6HL2/R =E13.5,10X,6HL2/B =E13.5/9X,7HK1/M1 =E13.5SUPPL362
1/9X,7HK2/M2 =E13.5) SUPPL363
41 FCRMAT(//10X,5HRR/R =E13.5,20X,6HRR/R =E13.5//) SUPPL364
44 FORMAT(1H1,20X,'POLYNOMIAL COEFFICIENTS'///7X,5HPOWER,12X,5HBLADE,SUPPL365
126X,3H2-D/) SUPPL366
46 FORMAT(I10,2D30.9) SUPPL367
47 FORMAT(1H1,20X,'ROOTS OF POLYNOMIALS'///30X,'BLADE',60X,'2-')/20X,SUPPL368
14HREAL,21X,4HIMAG,31X,4HREAL,21X,4HIMAG/) SUPPL369
49 FORMAT(2D25.9,10X,2D25.9) SUPPL370
11 FORMAT(/////9X,1H1,15X,10HGAMMA(I,1),15X,10HGAMMA(I,2),15X,10HGAMMSUPPL371
1A(I,3)/) SUPPL372
12 FORMAT(I10,3E25.5) SUPPL373
488 FORMAT(1H1,8X,1H1,7X,5HOMEGA,4X,9HBETA(I,1),4X,9HBETA(I,2),4X,9HBSUPPL374
1TA(I,3),3X,10HALPHA(I,1),3X,10HALPHA(I,2),3X,10HALPHA(I,3),9X,3HCHSUPPL375
1K//) SUPPL376
489 FORMAT(I10,8E13.5) SUPPL377
721 FORMAT(///10X,5HFR1 =E13.5,10X,5HFR2 =E13.5,10X,5HFR3 =E13.5//10X,SUPPL378
14HSA =E13.5,10X,4HSB =E13.5//) SUPPL379
END

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	SURROUTINE SETUPS	SETUPS 1
C		SETUPS 2
	IMPLICIT REAL*8 (A-H,O-Z)	SETUPS 3
C		SETUPS 4
C		SETUPS 5
	REAL FTVB, FPVB, FPPRVB, DIDRVB, XMVB, DELVB, XMUVB,	SETUPS 6
A	FOVB, XMUAVB, ATOVB, ATCVB, ATSVB, ROVB, RVB, MVB	SETUPS 7
	REAL ELSIG, DXI, REB, RDBB, FRZ, ARR, AMPLU, FREQU,	SETUPS 8
A	ALPH1, ALPH2, HEAVE, AROT, FREQF, PHIH, RY1, DRY,	SETUPS 9
B	Y, TEST, UPRIM, XU, YU, XL, YL, ER1, ER2, ER3, BDBR,	SETUPS10
C	RROBR	SETUPS11
	H, CMPA, CMPAS, BARG, EMI, HVOR, SSPA, SVOR, TORF, XIVOR	
	I, PLOTOP, PSILOW, PSIUP	
C		SETUPS12
	INTEGER TABLE(7, 80) /560 * ' ' /	
C		SETUPS14
C		SETUPS15
	COMMON /BL1/ NTIME	SETUPS16
C		SETUPS17
	COMMON /INPTVB/ FTVB(64), FPVB(64), FPPRVB(64), DIDRVB(64),	SETUPS18
A	XMVB(64), DELVB, XMUVB, FOVB, XMUAVB,	SETUPS19
B	ATOVB, ATCVB, ATSVB, ROVB, RVB(64),	SETUPS20
C	MVB(64), NVB	SETUPS21
C		SETUPS22
	COMMON /INPUTS/ NSBL, NZ, NOFF, NGAM, NSIG,	SETUPS23
A	NCOI, NCORD, LOWER, MSTOP, MAXT, MTR,	SETUPS24
B	NOTBL, INDV, ELSIG, DXI, REB, RDBB,	SETUPS25
C	FRZ, ARR, AMPLU, FREQU, ALPH1, ALPH2,	SETUPS26
D	HEAVE, AROT, FREQF, PHIH, NY, RY1,	SETUPS27
E	DRY, Y(100), TEST, UPRIM, XU(30), YU(30),	SETUPS28
F	XL(30), YL(30), ER1, ER2, ER3, BDBR,	SETUPS29
G	RROBR	SETUPS30
	H, CMPA, CMPAS, BARG, EMI, HVOR, NVOR, SSPA, SVOR, TORF, XIVOR	
	I, PLOTOP, PSILOW, PSIUP	
	J, NOUT	
C		SETUPS31
C		SETUPS32
C		SETUPS33
	CALL WHERE(TABLE)	SETUPS34
	CALL ZEROIN	SETUPS35
C		SETUPS36
C		SETUPS37
	CALL SETUP('ALPH1', 4, ALPH1)	SETUPS38
	CALL SETUP('ALPHA1', 4, ALPH1)	SETUPS39
	CALL SETUP('ALPH2', 4, ALPH2)	SETUPS40
	CALL SETUP('ALPHA2', 4, ALPH2)	SETUPS41
	CALL SETUP('AMPLU', 4, AMPLU)	SETUPS42
	CALL SETUP('ARR', 4, ARR)	SETUPS43
	CALL SETUP('AROT', 4, AROT)	SETUPS44
	CALL SETUP('ATOVB', 4, ATOVB)	SETUPS45
	CALL SETUP('ATCVB', 4, ATCVB)	SETUPS46
	CALL SETUP('ATSVB', 4, ATSVB)	SETUPS47
	CALL SETUP('BARG', 4, BARG)	
	CALL SETUP('BDBR', 4, BDBR)	SETUPS48
	CALL SETUP('CMPA', 4, CMPA)	

CALL SETUP('CMPAS	' , 4 ,	CMPAS	)	
CALL SETUP('DELVB	' , 4 ,	DELVB	)	SETUPS49
CALL SFTUP('DIDRVB	' , 4 ,	DIDRVB , 64	)	SETUPS50
CALL SFTUP('DRY	' , 4 ,	DRY	)	SETUPS51
CALL SFTUP('DXI	' , 4 ,	DXI	)	SETUPS52
CALL SETUP('ELSIG	' , 4 ,	ELSIG	)	SETUPS53
CALL SETUP('EMI	' , 4 ,	EMI	)	
CALL SETUP('ER1	' , 4 ,	ER1	)	SETUPS54
CALL SFTUP('ER2	' , 4 ,	ER2	)	SETUPS55
CALL SETUP('ER3	' , 4 ,	ER3	)	SETUPS56
CALL SETUP('FPVB	' , 4 ,	FPVB , 64	)	SETUPS57
CALL SETUP('FPPRVB	' , 4 ,	FPPRVB , 64	)	SETUPS58
CALL SETUP('FRZ	' , 4 ,	FRZ	)	SETUPS59
CALL SETUP('FREQU	' , 4 ,	FREQU	)	SETUPS60
CALL SETUP('FREQF	' , 4 ,	FREQF	)	SETUPS61
CALL SETUP('FTVB	' , 4 ,	FTVB , 64	)	SETUPS62
CALL SETUP('FOVB	' , 4 ,	FOVB	)	SETUPS63
CALL SETUP('HEAVE	' , 4 ,	HEAVE	)	SETUPS64
CALL SETUP('HVOR	' , 4 ,	HVOR	)	
CALL SETUP('INDV	' , 4 ,	INDV	)	SETUPS65
CALL SETUP('LOWER	' , 4 ,	LOWER	)	SETUPS66
CALL SETUP('MAXT	' , 4 ,	MAXT	)	SETUPS67
CALL SFTUP('MCTR	' , 4 ,	MCTR	)	SETUPS68
CALL SETUP('MSTOP	' , 4 ,	MSTOP	)	SETUPS69
CALL SETUP('MVB	' , 4 ,	MVB , 64	)	SETUPS70
CALL SETUP('NCOI	' , 4 ,	NCOI	)	SETUPS71
CALL SETUP('NCORD	' , 4 ,	NCORD	)	SETUPS72
CALL SETUP('NGAM	' , 4 ,	NGAM	)	SETUPS73
CALL SETUP('NOFF	' , 4 ,	KOFF	)	SETUPS74
CALL SFTUP('NOTBL	' , 4 ,	ACTBL	)	SETUPS75
CALL SETUP('NOUT	' , 4 ,	NOUT	)	
CALL SETUP('NSBL	' , 4 ,	NSBL	)	SETUPS76
CALL SETUP('NSIG	' , 4 ,	NSIG	)	SETUPS77
CALL SETUP('NVB	' , 4 ,	NVB	)	SETUPS78
CALL SETUP('NVOR	' , 4 ,	NVOR	)	
CALL SETUP('NY	' , 4 ,	NY	)	SETUPS79
CALL SETUP('NZ	' , 4 ,	NZ	)	SETUPS80
CALL SETUP('PHIH	' , 4 ,	PHIH	)	SETUPS81
CALL SETUP('PLOTOP	' , 4 ,	PLOTOP	)	
CALL SETUP('PSILOW	' , 4 ,	PSILOW	)	
CALL SETUP('PSIUP	' , 4 ,	PSIUP	)	
CALL SETUP('RVB	' , 4 ,	RVB , 64	)	SETUPS82
CALL SETUP('RDBB	' , 4 ,	RDBB	)	SETUPS83
CALL SETUP('REB	' , 4 ,	REB	)	SETUPS84
CALL SETUP('RRDBR	' , 4 ,	RRDBR	)	SETUPS85
CALL SETUP('ROVB	' , 4 ,	ROVB	)	SETUPS86
CALL SETUP('RYI	' , 4 ,	RYI	)	SETUPS87
CALL SETUP('SSPA	' , 4 ,	SSPA	)	
CALL SFTUP('SVOR	' , 4 ,	SVOR	)	
CALL SETUP('TEST	' , 4 ,	TEST	)	SETUPS88
CALL SETUP('TORF	' , 4 ,	TORF	)	
CALL SETUP('UPRIM	' , 4 ,	UPRIM	)	SETUPS89
CALL SETUP('XIVOR	' , 4 ,	XIVOR	)	
CALL SETUP('XL	' , 4 ,	XL , 30	)	SETUPS90
CALL SETUP('XNVB	' , 4 ,	XNVB , 64	)	SETUPS91

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CALL SETUP('XMUVR',4,XMUVR)
CALL SFUP('XUAVB',4,XMJAVB)
CALL SETUP('XU',4,XU,30)
CALL SETUP('Y',4,Y,100)
CALL SETUP('YL',4,YL,30)
CALL SETUP('YU',4,YU,30)

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SETUP592
SETUP593
SETUP594
SETUP595
SETUP596
SETUP597
SETJPS98
SETUP599
SETUP100
SETUP101
SETUP102
SETUP103
SETUP104

```

C  
C  
C  
C  
C  
C  
C

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PSILOW= 1.E10
PSIUP= -1.E10
PLOTOP = 1.

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NOUT= 0

RETURN

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SETUP105
SETUP106

```

C

END

	SUBROUTINE BLC(X,Y,MST,MEND,NY,RV,DRY,DXI,RER,UPRIM,FLAM,XFLAM,TESBLC	1
	IT,U,SCALE,UE,UC,V,XSEP,USEP,DISS,THETS,LOWER,LAMQ,MSEP,XC,USAV,SCALC	2
	ILS,NITS,NTIME,NOTBL,XTEST,NZ,NOUT)	
C		BLC 4
C	PROGRAM FOR ANALYZING LAMINAR AND TURBULENT BOUNDARY LAYERS	BLC 5
C	BY THE METHOD OF FINITE DIFFERENCES. IF THE INTEGER LAMQ	BLC 6
C	IS GREATER THAN ZERO, THE BOUNDARY LAYER IS LAMINAR.	BLC 7
C		BLC 8
	COMMON /BL1/ NDUMMY,NDIMC,ISTD	
	DIMENSION USAV(300,100),SCALS(300)	BLC 9
	DIMENSION X(300),Y(100),UE(300,3),UC(100,3),V(100,2),XC(300)	BLC 10
	DIMENSION SO(100),SE(100),SF(100),VISC(100,2),GRAD(100)	BLC 11
	DIMENSION A(100),B(100),C(100),D(100),F(100)	BLC 12
	DIMENSION ALPHA(100),BETA(100),GAMMA(100),DELTA(100)	BLC 13
	DIMENSION SCALE(300,2),VAR1(100),VAR2(100)	BLC 14
	DIMENSION FLAM(10),XFLAM(10),YB1(100),YB2(100)	BLC 15
	DIMENSION U(300,100,2)	BLC 16
	DIMENSION CAPG(100),CAPH(100),CAPJ(100),CAPK(100)	BLC 17
	DOUBLE PRECISION AP(100),BP(100),CP(100),DP(100),FP(100),UP(100)	BLC 18
10	FORMAT(1H1,41X,36H ANALYSIS OF LAMINAR BOUNDARY LAYER//51X,12HTIBLC	BLC 19
	1ME STEP NO13//51X,12HITERATION NO13//4X,1HM,8X,1HX,13X,2HXC,12X,2BLC	BLC 20
	1HUE,10X,6H-DP/DX,9X,5HDELTA,9X,5HDISPL,9X,5HTHETA,9X,5HSHEAR//	BLC 21
11	FORMAT(1H1,41X,36H ANALYSIS OF TURBULENT BOUNDARY LAYER//51X,12HTIBLC	BLC 22
	1ME STEP NO13//51X,12HITERATION NO13//4X,1HM,8X,1HX,13X,2HXC,12X,2BLC	BLC 23
	1HUE,10X,6H-DP/DX,9X,5HDELTA,9X,5HDISPL,9X,5HTHETA,9X,5HSHEAR,4X, BLC	BLC 24
	3 'I'//)	
12	FORMAT(15,8E14.4,I3)	
20	FORMAT(1H1,2X,3HM =14//2X,3HX =E14.5//2X, 4HUE =E14.5,10X,17H-(1/RBLC	BLC 26
	1H0)(DP/DX) =E14.5,10X,5HREB =E14.5,10X,4HUF =E14.5//)	BLC 27
24	FORMAT(2X,25H PHYSICAL DELTA =E14.5,8X,12HDELTA STAR =E14.5BLC	BLC 28
	15,8X,7HTHETA =E14.5//2X,25HTRANSFORMED DELTA =E14.5,8X,12HDEBLC	BLC 29
	1LTA STAR =E14.5,8X,7HTHETA =E14.5//)	BLC 30
21	FORMAT(25X,1HY,19X,1HU,19X,1HV,16X,5H DU/DY,14X,6HNUE/NU//)	BLC 31
22	FORMAT(10X,5E20.5)	BLC 32
23	FORMAT(//30X,17HSEPARATION AT X =E13.5,6H, XC =E13.5)	BLC 33
25	FORMAT(///40X,12HWALL SHEAR =E14.5//)	BLC 34
30	FORMAT(//50X,17HTRANSITION AT X =E14.5)	BLC 35
35	FORMAT(//20X,35HSCALE CHANGE - Y-MAX INCREASED FROME12.4,3H TOE12.4BLC	BLC 36
	I//)	BLC 37
810	FORMAT(10X,7HAT STEPI3,22H, THE WALL GRADIENT ISEL2.4)	BLC 38
	BCON = 1.57DXI	BLC 51
	FCON = 1./(2.*DXI)	BLC 52
	IF(ISTD.NE.1) GO TO 900	
	DXI=1.E30	
	BCON=0.	
	FCON= 0.	
900	CONTINUE	
	MOUT=6	BLC 39
	MTRAN=-1	BLC 40
	YSUB2=Y(2)	BLC 41
	MST2 = MST - 2	BLC 42
	MST1=MST-1	BLC 43
	NOUT1= NOUT +1	
	MST1MD= MOD( MST1, NOUT1)	
	MAXIT=0	



	GO TO (543,550),LOWER	BLC	44
543	IF(LAMQ) 544,544,545	BLC	45
544	WRITE(MOUT,11) NTIME,NITS	BLC	46
	GO TO 550	BLC	47
545	WRITE(MOUT,10) NTIME,NITS	BLC	48
550	CONTINUE	BLC	49
	YTR = SQRT(REB)	BLC	50
	UC(1,1) = 0.	BLC	53
	V(1,1) = 0.	BLC	54
	NV = NY - 2	BLC	55
	NVM1 = NV - 1	BLC	56
	NVP1 = NV + 1	BLC	57
	CALL YDIFF(NY,ALPHA,BETA,GAMMA,DELTA,SD,SE,SF,C2,C3,C4,Y)	BLC	58
	DO 41 N=1,NVP1	BLC	59
	VISC(N,1) = 1.	BLC	60
41	VISC(N,2) = 1.	BLC	61
	DO 42 M=MST2,MST1	BLC	62
	L = MST1-M+2	BLC	63
	DO 50 N=1,NV	BLC	64
50	GRAD(N+1) = SD(N+1)*UC(N+2,L)+SE(N+1)*UC(N+1,L)-SF(N+1)*UC(N,L)	BLC	65
	GRAD(1) = C2*UC(2,L)+C3*UC(3,L)+C4*UC(4,L)	BLC	66
	MM=M-1	BLC	67
	CALL PGRAD(MM,X,UE,DXI,PRESS,SA,SR,SC,SR,SS)	BLC	68
	DO 456 N=1,NY	BLC	69
456	UC(N,1)=UC(N,L)	BLC	70
	CALL SETIT(LAMQ,M,NV,REB,X,Y,UC,PRESS,GRAD,DELT,DISP,THETA,VISC,MTBL3	BLC	71
	IRAN)	BLC	72
42	CONTINUE	BLC	73
	MEND1 = MEND - 1	BLC	74
	GRADS=GRAD(1)	BLC	75
	GRADSS=GRAD(1)	BLC	76
C		BLC	77
C	THE MAIN CALCULATION STARTS HERE.	BLC	78
C		BLC	79
	DO 99 M=MST1,MEND1	BLC	80
	ITER=0	BLC	81
	WALLG=0.	BLC	82
	MPI=M+1	BLC	83
	DELTP = DELT/YTR	BLC	84
	DISPT = DISP*YTR	BLC	85
	THEYT = THETA*YTR	BLC	86
	SHEAR = GRAD(1)/YTR	BLC	87
	IF( MOD(M, NOUT1).NE. MST1MD) GO TO 225		
	GO TO (561,562),LOWER	BLC	88
561	WRITE(MOUT,12) M,X(M),XC(M),UE(M,1),PRESS,DELTP,DISP,THETA,SHEAR	BLC	89
	1, MAXIT		
	GO TO 225	BLC	90
562	WRITE(MOUT,20) M,X(M),UE(M,1),PRESS,REB,UPRIM	BLC	91
	WRITE(MOUT,24) DELTP,DISP,THETA,DELT,DISPT,THEYT	BLC	92
	WRITE(MOUT,21)	BLC	93
	WRITE(MOUT,22) (Y(N),UC(N,2),V(N,1),GRAD(N),VISC(N,1),N=1,NVP1)	BLC	94
	WRITE(MOUT,25) SHEAR	BLC	95
225	IF(GRADSS-GRADS-1.E-6) 229,229,408	BLC	96
408	XSX=X(M-2)+(X(M-1)-X(M-2))*GRADSS/(GRADSS-GRADS)	BLC	97
	IF(XSX-X(M)) 409,409,229	BLC	98

409	WFS=(XSX-X(M-1))/(X(M)-X(M-1))	BLC	99
	GO TO 224	BLC	100
229	IF ( GRAD(1) ) 227, 227, 273		
273	IF (DISP .GT. 0. .AND. THETA .GT. 0.) GO TO 223		
283	CONTINUE		
	XSEP= XC(M-1)		
	USEP=UE(M-1,1)		
	XBL=X(M-1)		
	WRITE(MOUT,23) XBL, XSEP		
	RETURN		
227	WFS=GRADS/(GRADS-GRAD(1))	BLC	102
224	WFS1=1.-WFS	BLC	103
	XSEP=WFS1*XC(M-1)+WFS*XC(M)	BLC	104
	XBL=WFS1*X(M-1)+WFS*X(M)	BLC	105
	USEP=WFS1*UE(M-1,1)+WFS*UE(M,1)	BLC	106
	WFP=(XBL-X(M-2))/(X(M-1)-X(M-2))	BLC	107
	WFP1=1.-WFP	BLC	108
	DISS=DISSS*WFP1+DISS*WFP	BLC	109
	THETS=THETSS*WFP1+THETS*WFP	BLC	110
	WRITE(MOUT,23) XBL,XSEP	BLC	111
	IF(LAMQ.EQ.0.AND.M.LT.MTRAN+5) LAMQ=1	BLC	112
	GO TO 222	BLC	113
223	CONTINUE	BLC	114
	IF( NOTBL .EQ. 2 .AND. NITS .GT. 1 .AND. M.GT. NZ .AND.		
1	XC(M) .GT. XTEST) GO TO 283		
	IF(LAMQ) 801,801,802	BLC	115
802	IF( NOTBL .EQ. 2) GO TO 801		
	CALL TRANS(UPRIM,PRESS,THETA,REB,UC,NY,FLAM,XFLAM,LAMQ)	BLC	116
	IF(LAMQ) 805,805,801	BLC	117
805	WRITE(MOUT,30) X(M)	BLC	118
	MTRAN = M+1	BLC	119
801	CONTINUE	BLC	120
	IF(Y(NV)-DELT) 620,641,641	BLC	121
620	RY=RY+DRY	BLC	122
C		BLC	123
C	RESCALING CALCULATION STARTS HERE.	BLC	124
C		BLC	125
	DO 632 N=1,NY	BLC	126
	YB1(N) = Y(N)	BLC	127
	VAR1(N) = UC(N,2)	BLC	128
632	VAR2(N) = UC(N,3)	BLC	129
	CALL YSET(RY,YSUB2,NY,Y)	BLC	130
	WRITE(MOUT,35) YB1(NY),Y(NY)	BLC	131
	DO 633 N=2,NVPI	BLC	132
	YIN = Y(N)	BLC	133
	CALL TERP(YIN,YB1,VAR1,NY,UPAS1)	BLC	134
	UC(N,2) = UPAS1	BLC	135
	CALL TERP(YIN,YB1,VAR2,NY,UPAS2)	BLC	136
633	UC(N,3) = UPAS2	BLC	137
	CALL YDIFF(NY,ALPHA,BETA,GAMMA,DELTA,SD,SE,SF,C2,C3,C4,Y)	BLC	138
	IF(LAMQ) 700,700,701	BLC	139
700	DO 635 N=2,NVPI	BLC	140
	VAR1(N) = VISC(N,1)	BLC	141
635	VAR2(N) = VISC(N,2)	BLC	142
	DO 636 N=2,NVPI	BLC	143

	YIN = Y(N)	BLC	144
	CALL TERP(YIN,YB1,VARI,NVP1,UPAS1)	BLC	145
	VISC(N,1) = UPAS1	BLC	146
	CALL TERP(YIN,YB1,VAR2,NVP1,UPAS2)	BLC	147
636	VISC(N,2) = UPAS2	BLC	148
7C1	DO 637 N=2,NVP1	BLC	149
	VARI(N) = V(N,1)	BLC	150
637	VAR2(N) = V(N,2)	BLC	151
	DO 638 N=2,NVP1	BLC	152
	YIN = Y(N)	BLC	153
	CALL TERP(YIN,YB1,VARI,NVP1,UPAS1)	BLC	154
	V(N,1) = UPAS1	BLC	155
	CALL TERP(YIN,YB1,VAR2,NVP1,UPAS2)	BLC	156
638	V(N,2) = UPAS2	BLC	157
641	CONTINUE	BLC	158
C		BLC	159
C	RESCALING CALCULATION ENDS HERE.	BLC	160
C		BLC	161
	CALL PGRAD(M,X,UE,DXI,PRESS,SA,SB,SC,SR,SS)	BLC	162
C		BLC	163
C	RECURSION RELATIONS ARE SET UP HERE.	BLC	164
C		BLC	165
	IF (ISTD.EQ. 1) GO TO 820		
	IF(SCALE(M+1,1)-1.) 522,522,521	BLC	166
521	IF(SCALE(M+1,2)-1.) 522,522,523	BLC	167
522	LACKU=1	BLC	168
	FACU1=UE(M+1,2)/UE(M+1,1)	BLC	169
	FACU2=UE(M+1,3)/UE(M+1,1)	BLC	170
	GO TO 820	BLC	171
523	LACKU=2	BLC	172
	DO 610 NN=1,NY	BLC	173
	VARI(NN) = U(M+1,NN,1)	BLC	174
610	VAR2(NN) = U(M+1,NN,2)	BLC	175
	CALL YSET(SCALE(M+1,1),YSUB2,NY,YB1)	BLC	176
	CALL YSET(SCALE(M+1,2),YSUB2,NY,YB2)	BLC	177
820	DO 88 N=2,NV	BLC	178
	CALL CAPS(ITER,N,CAPG,CAPH,CAPJ,CAPK,SR,SS,SD,SE,SF,VISC,V,UC)	BLC	179
	A(N)=-SF(N)*CAPG(N)-DELTA(N)*CAPH(N)+SF(N)*CAPJ(N)	BLC	180
	B(N)=BCON+SA*CAPK(N)+SF(N)*CAPG(N)-GAMMA(N)*CAPH(N)-SE(N)*CAPJ(N)	BLC	181
	C(N)=SD(N)*CAPG(N)-BETA(N)*CAPH(N)-SD(N)*CAPJ(N)	BLC	182
	D(N) = -ALPHA(N)*CAPH(N)	BLC	183
	IF(ISTD.EQ. 1) GO TO 576		
	GO TO (574,575),LACKU	BLC	184
574	UPAS1=FACU1*UC(N,1)	BLC	185
	UPAS2=FACU2*UC(N,1)	BLC	186
	GO TO 576	BLC	187
575	YIN = Y(N)	BLC	188
	CALL TERP(YIN,YB1,VARI,NY,UPAS1)	BLC	189
	CALL TERP(YIN,YB2,VAR2,NY,UPAS2)	BLC	190
576	F(N) = PRESS+FCON*(4.*UPAS1-UPAS2)+CAPK(N)*(SB*UC(N,2)-SC*UC(N,3))	BLC	191
88	CONTINUE	BLC	192
C		BLC	193
C	SOLUTION FOR VELOCITY PROFILE STARTS HERE.	BLC	194
C		BLC	195
	DO 89 N=2,NV	BLC	196

	AP(N) = A(N)	BLC	197
	BP(N) = B(N)	BLC	198
	CP(N) = C(N)	BLC	199
	DP(N) = D(N)	BLC	200
89	FP(N) = F(N)	BLC	201
	DO 77 N=2,NVMI	BLC	202
	CP(N) = CP(N)/BP(N)	BLC	203
	DP(N) = DP(N)/BP(N)	BLC	204
	FP(N) = FP(N)/BP(N)	BLC	205
	BP(N+1) = BP(N+1) - CP(N)*AP(N+1)	BLC	206
	CP(N+1) = CP(N+1) - DP(N)*AP(N+1)	BLC	207
77	FP(N+1) = FP(N+1) - FP(N)*AP(N+1)	BLC	208
	UP(NY) = UE(M+1,1)	BLC	209
	UP(NVP1) = UP(NY)	BLC	210
	UP(NV) = (FP(NV)-UP(NY)*(DP(NV) + CP(NV)))/BP(NV)	BLC	211
	DO 66 N=3,NV	BLC	212
	NN=NV+2-N	BLC	213
66	UP(NN) = FP(NN) - DP(NN)*UP(NN+2) - CP(NN)*UP(NN+1)	BLC	214
	DO 65 N=2,NY	BLC	215
65	UC(N,1) = UP(N)	BLC	216
	IF(ITER) 843,841,843	BLC	217
841	DO 842 N=2,NVPI	BLC	218
	V(N,2) = V(N,1)	BLC	219
842	VISC(N,2)=VISC(N,1)	BLC	220
	DISS=DISS	BLC	221
	DISS=DISP	BLC	222
	THETSS=THETS	BLC	223
	THETS=THETA	BLC	224
	GRADSS=GRADS	BLC	225
	GRADS=GRAD(1)	BLC	226
843	DO 55 N=2,NVPI	BLC	227
55	V(N,1) = V(N-1,1)-.5*(Y(N)-Y(N-1))*(SA*(UC(N,1)+UC(N-1,1))-SB*(UC(N,1)+UC(N-1,2))+SC*(UC(N,3)+UC(N-1,3)))	BLC	228
	DO 56 N=1,NV	BLC	230
56	GRAD(N+1) = SD(N+1)*UC(N+2,1)+SE(N+1)*UC(N+1,1)-SF(N+1)*UC(N,1)	BLC	231
	GRAD(1) = C2*UC(2,1)+C3*UC(3,1)+C4*UC(4,1)	BLC	232
	CALL SETITTLAMQ,NPI,NV,REB,X,Y,UC,PRESS,GRAD,DELT,DISP,THETA,VISC,	BLC	233
	IMTRAN)	BLC	234
	ITER=ITER+1	BLC	235
	GO TO (830,809),LOWER	BLC	236
809	WRITE(MOUT,810) ITER,GRAD(1)	BLC	237
830	IF(ITER-9) 811,811,812	BLC	238
811	EPW=ABS(GRAD(1)-WALLG)	BLC	239
	IF(WALLG-1.) 120,120,119	BLC	240
119	EPW=EPW/WALLG	BLC	241
120	IF(EPW-TEST) 812,814,814	BLC	242
814	WALLG=GRAD(1)	BLC	243
	GO TO 820	BLC	244
812	DO 44 N=1,NY	BLC	245
	UC(N,3) = UC(N,2)	BLC	246
	UC(N,2) = UC(N,1)	BLC	247
44	CONTINUE		
	MAXIT=ITER		
	IF(ISTD .EQ. 1) GO TO 99		
	DO 48 N=1,NY		

48 USAV(M+1,N)=UC(N,1)  
SCALS(M+1)=RY

99 CONTINUE  
XSEP=1.1

222 USEP=UE(MX,1)

CONTINUE  
RETURN  
END

BLC 249

BLC 250

BLC 251

BLC 252

BLC 253

BLC 254

```

SUBROUTINE PLOTSB( PLOTOP , P , L )
  REAL * 8 ORD(6)
  DIMENSION P(200,7), TIT1(56) , NF(5,4)
1 , NFP(6)
  DATA N1 , N2 , NO , N42
1 / 1 , 2 , 0 , 42 /
  DATA ORD/ , ' THETA-P' , ' TORS ' , ' FLAP-H ' , ' BEND-H ' ,
1 ' CL ' , ' CM-A ' /
  IF (PLOTOP .EQ. 0.) RETURN
  IF ( L .LT. 2) RETURN
  IF ( PLOTOP .EQ. 2.) GO TO 2
  PLOTOP = 2.
  CALL IOFRMV ( 'CRIMI -PETE ' , '30' , '5100' )
2 CONTINUE
3 NL=1
  DO 1 J = 1 , 6
    CALL EZPLOT(9. , N1 , N1 , P , P(1,J+1) , L , -N1 , N2
1 , N42 , 1 , ' ' , 12 , ' PSI-DEGREES' , 8 , ORD( J)
2 , N1 , N1 , XL , XU , N1 , YL , YU ,N1 , NO , NL)
1 CONTINUE
  NFP(1)= -1
  NFP(2)= 66
  NFP(3)= 50
  NFP(4)= 50
  NFP(5)= 680
  CALL EZPLOT(9. , N1 , N1 , P , P(1,2 ) , L , -N1 , N2
1 , N42 , 1 , ' ' , 12 , ' PSI-DEGREES' , 8 , ORD( 1)
2 , NFP , N1 , XL , XU , N1 , YL , YU ,N1 , NO , N1)
  NFP(1)= -2
  NFP(2)= 66
  NFP(4)= 350
  NFP(5)= 380
  CALL EZPLOT(9. , N1 , N1 , P , P(1,6 ) , L , -N1 , N2
1 , N42 , 1 , ' ' , 12 , ' ' , 8 , ORD( 5)
2 , NFP , N1 , XL , XU , N1 , YL , YU ,N1 , NO , N1)
  NFP(2)= 50
  NFP(4)= 690
  NFP(5)= 40
  CALL EZPLOT(9. , N1 , N1 , P , P(1,7 ) , L , -N1 , N2
1 , N42 , 1 , ' ' , 12 , ' ' , 8 , ORD( 6)
2 , NFP , N1 , XL , XU , N1 , YL , YU ,N1 , NO , N1)
  NFP(1)= -1
  NFP(2)= 50
  NFP(3)= 50
  NFP(4)= 50
  NFP(5)= 680
  CALL EZPLOT(9. , N1 , N1 , P , P(1,3 ) , L , -N1 , N2
1 , N42 , 1 , ' ' , 12 , ' PSI-DEGREES' , 8 , ORD( 2)
2 , NFP , N1 , XL , XU , N1 , YL , YU ,N1 , NO , N1)
  NFP(1)= -2
  NFP(2)= 66
  NFP(4)= 350
  NFP(5)= 380
  CALL EZPLOT(9. , N1 , N1 , P , P(1,4 ) , L , -N1 , N2
1 , N42 , 1 , ' ' , 12 , ' ' , 8 , ORD( 3)

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2 , NFP , N1 , XL , XU , N1 , YL , YU , N1 , NO , N1)
  NFP(2) = 50
  NFP(4) = 690
  NFP(5) = 40
CALL EZPLOT(9. , N1 , N1, P , P(1,5) , L , -N1 , N2
1 , N42 , 1 , ' , 12 , ' , 8 , ORD( 4)
2 , NFP , N1 , XL , XU , N1 , YL , YU , N1 , NO , N1)
  RETURN
  END

```

	SUBROUTINE STAG(MX,NY,MSTOP,MST,DXI,RY,DRY,X,Y,UE,UC,V,USAV,SCALS,STAG	1
	1ISEP)	2
C	PROGRAM FOR CALCULATING THE BOUNDARY LAYER PROFILE NEAR	3
C	THE STAGNATION POINT	4
C		5
	COMMON /BL1/ NTIME,NDIMC,ISTD	
	DIMENSION USAV(300,100),SCALS(300)	6
	DIMENSION PHI7(24),PHIP(24),ETAP(24)	7
	DIMENSION X(300),Y(100),UE(300,3),UC(100,3),V(100,2)	8
	DIMENSION EF(100),EFP(100)	9
	DATA ETAP /0.,.2,.4,.6,.8,1.,1.2,1.4,1.6,1.8,2.,2.2,2.4,2.6,2.8,3.	10
	1,3.2,3.4,3.6,3.8,4.,4.2,4.4,4.6/	11
	DATA PHIZ /0.,.0233,.0981,.1867,.3124,.4592,.622,.7967,.9793,1.164	12
	19,1.362,1.5578,1.7553,1.9538,2.153,2.3526,2.5523,2.7522,2.9521,3.1	13
	521,3.3521,3.5521,3.7521,3.9521/	14
	DATA PHIP /0.,.2266,.4145,.5663,.6859,.7779,.8467,.8968,.9323,.956	15
	18,.9732,.9839,.9905,.9946,.997,.9984,.9992,.9996,.9998,.9999,1.,1.	16
	1,1.,1./	17
	BAG=.08	18
	IF(1ISEP) 10,10,5	19
5	BAG=.5	20
10	EF(1) = 0.	21
	EFP(1) = 0.	22
	DO 20 M=1,MX	23
	IF(UE(M,1)) 20,20,19	24
19	MSP = M	25
	GO TO 21	26
20	CONTINUE	27
21	ASTAG = (UE(MSP+2,1)-UE(MSP+1,1))/(X(MSP+2)-X(MSP+1))	28
	IF(ASTAG) 22,22,23	29
22	ASTAG=(UE(MSP,1)-UE(MSP-1,1))/(X(MSP)-X(MSP-1))	30
23	SQAS = SQRT(ASTAG)	31
	DELT = 2.67/SQAS	32
309	IF(DELT-Y(NY-3)) 311,310,310	33
310	RY=RY+DRY	34
	CALL YSET(RY,Y(2),NY,Y)	35
	GO TO 309	36
311	CONTINUE	37
	DO 80 N=2,NY	38
	YET = Y(N)*SQAS	39
	DO 33 NN=1,24	40
	IF(YET-ETAP(NN)) 408,408,33	41
408	MARK = NN	42
	GO TO 410	43
33	CONTINUE	44
	EF(N) = YET-.6479	45
	EFP(N) = 1.	46
	GO TO 80	47
410	FRACT = (YET-ETAP(MARK-1))/(ETAP(MARK)-ETAP(MARK-1))	48
	FRAC1 = 1.-FRACT	49
	EFP(N) = PHIZ(MARK-1)*FRAC1+PHIZ(MARK)*FRACT	50
	EFP(N) = PHIP(MARK-1)*FRAC1+PHIP(MARK)*FRACT	51
80	CONTINUE	52
	M1 = MSP-MSTOP	53
	M2 = MSP+MSTOP	54



	M=M1-1	STAG	55
50	M=M+1	STAG	56
	MST=M+1	STAG	57
	SCALS(M)=RY	STAG	58
	DO 71 N=1,NY	STAG	59
	UC(N,3) = UC(N,2)	STAG	60
	UC(N,2) = UE(M,1)*EFP(N)	STAG	61
	V(N,2) = V(N,1)	STAG	62
	V(N,1) = -SQAS*EF(N)	STAG	63
	IF(ISTD.EQ. 1) GO TO 71		
	USAV(M,N)=UC(N,2)	STAG	64
71	CONTINUE	STAG	65
	IF(M-M2) 50,55,55	STAG	66
55	IF(UF(M,1)-BAG) 50,50,81	STAG	67
81	CONTINUE	STAG	68
	RETURN	STAG	69
	END	STAG	70

	SUBROUTINE ATTPR(PREC,XSIG,NSIG,ASZ,AS,AR,CMAT,RMAT,NGAM,NF,ACAP,TATTPR	1
	THICK,RDBB,GAMAW,UINF,UDOT,DXI,BCAP)	2
	DIMENSION XSIG(100),ASZ(30),AS(30,30),AR(30),BCAP(100,3)	3
	DIMENSION ACAP(30,3),THICK(24),GAMAW(1000)	4
	DOUBLE PRECISION CMAT(60,60),RMAT(130)	5
	PI=3.14159	6
	NGPI=NGAM+1	7
	DO 50 M=1,NGPI	8
	CMAT(M,1)=ASZ(M)	9
	RMAT(M)=AR(M)	10
	DC 25 N=1,NGAM	11
25	CMAT(M,N+1)=AS(M,N)	12
50	CONTINUE	13
	CALL ALSOL(NGPI,CMAT,RMAT)	14
	DO 75 M=1,NGPI	15
75	ACAP(M,1)=RMAT(M)	16
	GAMAW(1)=GAMI(ACAP,DXI,PI)	17
	SAVE=XSIG(NSIG+1)	18
	XSIG(NSIG+1)=2.	19
	CALL CPC(0,NGAM,NF,XSIG,NSIG,XSIG,NSIG,XSIG,NSIG,ACAP,BCAP,THICK,RATTPR	20
	10BB,GAMAW,UINF,UDOT,1.,SAVE,DXI,PREC)	21
	XSIG(NSIG+1)=SAVE	22
	RETURN	23
	END	24

	SUBROUTINE UNPOP(NGAM,AR,ALAM,AFACT,RMAT,CMAT,XGAM,AS,ACAP,MX,NZ,NUNPOP	1
	IF,XSIG,BCAP,THICK,RDBB,UINF,XC,UE)	UNPOP 2
	DIMENSION AR(30),ALAM(30),XGAM(30),AS(30,30),ACAP(30,3),XSIG(100),UNPOP	3
	BCAP(100,3),THICK(24),XC(300),JE(300,3)	UNPOP 4
	DOUBLE PRECISION RMAT(130),CMAT(60,60)	UNPOP 5
	NGP1=NGAM+1	UNPOP 6
	DO 5 M=1,NGP1	UNPOP 7
	SUB=AR(M)-ALAM(M)*AFACT/3.	UNPOP 8
	RMAT(M)=SUB	UNPOP 9
	CMAT(M,1)=1.	UNPOP 10
	CMAT(M,2)=XGAM(M)	UNPOP 11
	DO 5 N=2,NGAM	UNPOP 12
5	CMAT(M,N+1)=AS(M,N)	UNPOP 13
	CALL ALSOL(NGP1,CMAT,RMAT)	UNPOP 14
	DO 10 N=1,NGP1	UNPOP 15
10	ACAP(N,1)=RMAT(N)	UNPOP 16
	DO 15 M=1,MX	UNPOP 17
	SIGN=1.	UNPOP 18
	IF(M-NZ) 12,14,14	UNPOP 19
12	SIGN=-SIGN	UNPOP 20
14	CALL QECAL(0,NGAM,NGAM,NF,XSIG,ACAP,BCAP,THICK,RDBB,O.,UINF,XC(M),UNPOP	21
	IUE(M,1),SIGN)	UNPOP 22
15	CONTINUE	UNPOP 23
	RETURN	UNPOP 24
	END	UNPOP 25

```

SUBROUTINE ALSOL(NT, C, R)
DCUBLE PRECISION C, NDIMC, NOIMC), R(130)
DOUBLE PRECISION CMAX,SAVE,SUM
COMMON /RL1/ NTIME, NOIMC
NT1 = NT-1
DO 99 J=1,NT1
  CMAX = C(NT,J)
  L=NT
  DO 10 I=J,NT1
    IF (DABS(CMAX)-DABS(C(I,J))) 5,10,10
5    CMAX = C(I,J)
    L=I
10  CONTINUE
    DO 15 JJ=J,NT
      SAVE = C(L,JJ)
      C(L,JJ) = C(J,JJ)
15  C(J,JJ) = SAVE/CMAX
      SAVE = R(L)
      R(L) = R(J)
      R(J) = SAVE/CMAX
      JP1 = J+1
      DO 25 I=JP1,NT
        DO 20 JJ=JP1,NT
20      C(I,JJ) = C(I,JJ) - C(I,J)*C(J,JJ)
25      R(I) = R(I) - R(J)*C(I,J)
99  CONTINUE
    R(NT) = R(NT)/C(NT,NT)
    DO 150 K=1,NT1
      I=NT-K
      IP1 = I+1
      SUM = 0.
      DO 125 J=IP1,NT
125    SUM = SUM + R(J)*C(I,J)
150    R(I) = R(I) - SUM
    RETURN
  END

```

ALSOL

	SUBROUTINE CPC(ISEP,NGAM,NF,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,CPC	1
	1,BCAP,THICK,RDBB,GAMAW,UINF,UDOT,SIGN,XC,DXI,CP)	CPC 2
	DIMENSION XSIG(100),XSIGA(100),XSIGB(100),ACAP(30,3),BCAP(100,3)	CPC 3
	DIMENSION GAMAW(1000),THICK(24)	CPC 4
	THETA=ARCT(XC)	CPC 5
	RECIP=1./(UINF*UINF)	CPC 6
	SUM=0.	CPC 7
	ANGLE=0.	CPC 8
	DO 5 N=1,NF	CPC 9
	ANGLE=ANGLE+THETA	CPC 10
5	SUM=SUM+THICK(N)*COS(ANGLE)	CPC 11
	CP=UDOT*RECIP*(THICK(1)+2.*(1.-XC)*SUM)	CPC 12
	CALL DECAL(ISEP,NGAM,NSIG,NF,XSIG,ACAP,BCAP,THICK,RDBB,GAMAW(1),UICPC	13
	1NF,XC,U,SIGN)	CPC 14
	CP=CP+2.*(SIGN*U/UINF-1.)	CPC 15
	CALL EGAMI(1,NGAM,ACAP,BCAP(1,1),XSIG(1),XSIG(NSIG+1),GAMAW(1),XC,CPC	16
	1VAL1)	CPC 17
	CALL EGAMI(2,NGAM,ACAP,BCAP(1,2),XSIGA(1),XSIGA(NSIGA+1),GAMAW(2),CPC	18
	1XC,VAL2)	CPC 19
	CALL EGAMI(3,NGAM,ACAP,BCAP(1,3),XSIGB(1),XSIGB(NSIGB+1),GAMAW(3),CPC	20
	1XC,VAL3)	CPC 21
	CP=CP+SIGN*RECIP*(1.5*VAL1-2.*VAL2+.5*VAL3)/DXI	CPC 22
	IF(ISEP) 20,20,10	CPC 23
10	CALL FSIGI(1,NSIG,XSIG,BCAP,XC,VAL1)	CPC 24
	CALL ESIGI(2,NSIGA,XSIGA,BCAP,XC,VAL2)	CPC 25
	CALL ESIGI(3,NSIGB,XSIGB,BCAP,XC,VAL3)	CPC 26
	CP=CP+RECIP*(1.5*VAL1-2.*VAL2+.5*VAL3)/DXI	CPC 27
20	CP=-CP	CPC 28
	RETURN	CPC 29
	END	

	SUBROUTINE CLCM(NCOI,ISEP,NGAM,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACLCM	1
	ICAP,BCAP,THICK,RDBB,GAMAW,UINF,UDOT,DXI,AROT,CMPA)	2
	COMMON /CLCMBL/ CLVB, CMVB, CMPAVB	MAIN
	DIMENSION ARGL(21),ARGM(21)	CLCM 3
	DIMENSION GAMAW(1000),THICK(24)	CLCM 4
	DIMENSION XSIG(100),XSIGA(100),XSIGB(100),ACAP(30,3),BCAP(100,3)	CLCM 5
4	FORMAT(/740X,4HCL=E13.5/40X,4HCM=E13.5,17H (ABOUT MIDCHOR))/40X,	CLCM 6
	14HCM=E13.5,24H (ABOUT PITCH AXIS - A=F7.4,1H))	CLCM 7
	MOUT=6	CLCM 8
	SAVE=THICK(1)	CLCM 9
	THICK(1)=0.	CLCM 10
	DT=3.14159/FLOAT(NCOI)	CLCM 11
	CL=0.	CLCM 12
	CM=0.	CLCM 13
	XI=-1.	CLCM 14
	ANGLE=0.	CLCM 15
	FLI=0.	CLCM 16
	FMI=0.	CLCM 17
	IF (ISEP) 5,5,7	CLCM 18
7	XATT=XSIG(NSIG+1)	CLCM 19
	IF (XATT-.95) 8,5,5	CLCM 20
8	XAQ=XATT+.5E-4	CLCM 21
	XAP=XAQ+.025	CLCM 22
	C1=-.5*(1.+XATT)	CLCM 23
	C2=C1+XATT	CLCM 24
	C1P=.5*(1.-XAP)	CLCM 25
	C2P=C1P+XAP	CLCM 26
	DO 10 I=1,NCOI	CLCM 27
	ANGLE=ANGLE+DT	CLCM 28
	XIPI=C1*COS(ANGLE)+C2	CLCM 29
	CALL CPC(ISEP,NGAM,I,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,TC	CLCM 30
	1THICK,RDBB,GAMAW,UINF,UDOT,1.0,XIPI,DXI,CPU)	CLCM 31
	CALL CPC(ISEP,NGAM,I,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,TC	CLCM 32
	1THICK,RDBB,GAMAW,UINF,UDOT,-1.,XIPI,DXI,CPL)	CLCM 33
	FLIPI=CPL-CPU	CLCM 34
	FMIPI=XIPI*FLIPI	CLCM 35
	CL=CL+(XIPI-XI)*(FLIPI+FLI)	CLCM 36
	CM=CM+(XIPI-XI)*(FMIPI+FMI)	CLCM 37
	XI=XIPI	CLCM 38
	FLI=FLIPI	CLCM 39
10	FMI=FMIPI	CLCM 40
	XI=1.	CLCM 41
	FLI=0.	CLCM 42
	FMI=0.	CLCM 43
	ANGLE=0.	CLCM 44
	DO 15 I=1,NCOI	CLCM 45
	ANGLE=ANGLE+DT	CLCM 46
	XIPI=C1P*COS(ANGLE)+C2P	CLCM 47
	CALL CPC(ISEP,NGAM,I,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,TC	CLCM 48
	1THICK,RDBB,GAMAW,UINF,UDOT,1.0,XIPI,DXI,CPU)	CLCM 49
	CALL CPC(ISEP,NGAM,I,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,TC	CLCM 50
	1THICK,RDBB,GAMAW,UINF,UDOT,-1.,XIPI,DXI,CPL)	CLCM 51
	FLIPI=CPL-CPU	CLCM 52
	FMIPI=XIPI*FLIPI	CLCM 53
	CL=CL-(XIPI-XI)*(FLIPI+FLI)	CLCM 54

	CM=CM-(XIPI-XI)*(FMIPI+FMI)	CLCM	55
	XI=XIPI	CLCM	56
	FLI=FLIPI	CLCM	57
15	FMI=FMIPI	CLCM	58
	XIPI=XAQ	CLCM	59
	DO 16 I=1,21	CLCM	60
	CALL CPC(I SEP,NGAM,1,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,TCLCM	CLCM	61
	THICK,RDBB,GAMAW,UINF,UDOT,1.0,XIPI,DXI,CPU)	CLCM	62
	CALL CPC(I SEP,NGAM,1,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,TCLCM	CLCM	63
	THICK,RDBB,GAMAW,UINF,UDOT,-1.,XIPI,DXI,CPL)	CLCM	64
	ARGL(I)=CPL-CPU	CLCM	65
	ARGM(I)=XIPI*ARGL(I)	CLCM	66
16	XIPI=XIPI+.00125	CLCM	67
	SUML=0.	CLCM	68
	SUMM=0.	CLCM	69
	DO 17 I=1,19,2	CLCM	70
	SUML=SUML+2.*ARGL(I)+4.*ARGL(I+1)	CLCM	71
17	SUMM=SUMM+2.*ARGM(I)+4.*ARGM(I+1)	CLCM	72
	CL=CL+0.833333E-3*(SUML+ARGL(21)-ARGL(1))	CLCM	73
	CM=CM+0.833333E-3*(SUMM+ARGM(21)-ARGM(1))	CLCM	74
	BCON=16.*RCAP(1,1)*SQRT(5.E-4*(XATT-XSIG(1)))/UINF	CLCM	75
	CL=CL+BCON	CLCM	76
	CM=CM+XATT*BCON	CLCM	77
	GO TO 100	CLCM	78
5	DO 99 I=1,NCOT	CLCM	79
	ANGLE=ANGLE+DT	CLCM	80
	XIPI=-COS(ANGLE)	CLCM	81
	CALL CPC(I SEP,NGAM,1,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,TCLCM	CLCM	82
	THICK,RDBB,GAMAW,UINF,UDOT,1.0,XIPI,DXI,CPU)	CLCM	83
	CALL CPC(I SEP,NGAM,1,XSIG,NSIG,XSIGA,NSIGA,XSIGB,NSIGB,ACAP,BCAP,TCLCM	CLCM	84
	THICK,RDBB,GAMAW,UINF,UDOT,-1.,XIPI,DXI,CPL)	CLCM	85
	FLIPI=CPL-CPU	CLCM	86
	FMIPI=XIPI*FLIPI	CLCM	87
	CL=CL+(XIPI-XI)*(FLIPI+FLI)	CLCM	88
	CM=CM+(XIPI-XI)*(FMIPI+FMI)	CLCM	89
	XI=XIPI	CLCM	90
	FLI=FLIPI	CLCM	91
99	FMI=FMIPI	CLCM	92
100	CL=.25*CL	CLCM	93
	CM=-.125*CM	CLCM	94
	CPA=CM+AROT*CL*.5	CLCM	95
	WRITE(MOUT,4) CL,CM,CPA,AROT	CLCM	96
	THICK(1)=SAVE	CLCM	97
	CLVB = CL	MAIN	
	CMVB = CM	MAIN	
	CPAVB = CPA	MAIN	
	RETURN	CLCM	98
	END		

	SUBROUTINE QECAL (ISEP,NGAM,NSIG,NF,XSIG,ACAP,BCAP,THICK,RDBB,GAMMA,QECAL	1
1	UINF,XC,U,SIGN)	QECAL 2
	DIMENSION ACAP(30,3),BCAP(100,3),XSIG(100)	QECAL 3
	DIMENSION THICK(24)	QECAL 4
	EPS=1.E-6	QECAL 5
	CORR=.707107/(1.-.63662*SQRT(RDBB)+.25*RDBB)	QECAL 6
	SINT=SQRT(1.-XC*XC)	QECAL 7
	THETA=ARCT(XC)	QECAL 8
	COUNT=0.	QECAL 9
	SUM=0.	QECAL 10
	SINT2=SIN(.5*THETA)	QECAL 11
	COST2=COS(.5*THETA)	QECAL 12
	IF(SINT-EPS) 4,6,6	QECAL 13
4	FACT=THETA*.5	QECAL 14
	GO TO 8	QECAL 15
6	FACT=(1.-XC)/SINT	QECAL 16
8	DO 10 N=1,NF	QECAL 17
	COUNT=COUNT+1.	QECAL 18
	ANGLE=THETA*COUNT	QECAL 19
	SUM=SUM+THICK(N)*(COUNT*FACT*SIN(ANGLE)-COS(ANGLE))	QECAL 20
10	CONTINUE	QECAL 21
	U=2.*SIGN*UINF*COST2*SUM+ACAP(1,1)*SINT2+.25*COST2*(1.+XC)*(3.*XC-	QECAL 22
	11.)*GAMMA	QECAL 23
	SUM=0.	QECAL 24
	ANGLE=0.	QECAL 25
	DO 12 N=1,NGAM	QECAL 26
	ANGLE=ANGLE+THETA	QECAL 27
12	SUM=SUM+ACAP(N+1,1)*SIN(ANGLE)	QECAL 28
	U=U+COST2*SUM	QECAL 29
	IF(ISEP) 25,99,25	QECAL 30
25	SUM=0.	QECAL 31
	XSEP=XSIG(1)	QECAL 32
	XATT=XSIG(NSIG+1)	QECAL 33
	DO 40 N=2,NSIG	QECAL 34
40	SUM=SUM+BCAP(N,1)*FB(XSIG(N-1),XSIG(N),XSIG(N+1),XC)	QECAL 35
	IF(XC-XATT-EPS) 45,45,46	QECAL 36
46	FACT=(1.-XATT)**(-1.5)*SQRT((XATT-XSEP)*(1.-XC)/(XC-XATT))*(1.+3.*	QECAL 37
	1XATT-4.*XC)-SIGN*(1.-SQRT((XSEP-XC)/(XATT-XC)))	QECAL 38
	GO TO 55	QECAL 39
45	IF(XSEP-XC) 49,49,48	QECAL 40
48	FACT=-SIGN*(1.-SQRT((XSEP-XC)/(XATT-XC)))	QECAL 41
	GO TO 55	QECAL 42
49	FACT=-SIGN	QECAL 43
55	U=U+COST2*(BCAP(1,1)*FACT+SIGN*SJM)	QECAL 44
99	U=(SIGN*UINF*SQRT(1.+XC)+ CORR*U)/SQRT(1.+XC+.5*RDBB)	QECAL 45
	RETURN	QECAL 46
	END	



	SLBRoutine YVR(Y, I)	YVR	1
	REAL Y(10)	YVR	2
	REAL MVR	YVR	3
	COMMON /INPTVR/ FTVB(64), FPVB(64), FPPRVB(64), DIDRVB(64),	YVB	4
A	XMVB(64), DELVB, XMUVB, FOVB, XMUAVB,	YVB	5
B	ATOVB, ATCVB, ATSVB, ROVB, RVB(64),	YVB	6
C	MVB(64), NVB	YVR	7
	Y(1) = (RVB(I) - DELVB)**2 * MVB(I)	YVB	8
	Y(2) = FPVB(I)**2 * MVB(I)	YVB	9
	Y(3) = FTVB(I)**2 * DIDRVB(I)	YVB	10
	Y(4) = (DELVB - FVB(I)) * FTVB(I) * XMVB(I) * MVB(I)	YVB	11
	Y(5) = FPVB(I) * FTVB(I) * XMVB(I) * MVB(I)	YVB	12
	Y(6) = RVB(I) * (DELVB - RVB(I)) * MVB(I)	YVB	13
	Y(8) = (RVB(I) - DELVB) * FPPRVB(I) * FTVB(I) * XMVB(I) * MVB(I)	YVB	14
	IP1 = I+1	YVR	15
	IF(IP1 .GE. NVB) GO TO 12	YVB	16
	SUM = 0.	YVR	17
	DO 10 J = IP1, NVB	YVB	18
10	SUM = SUM - (RVB(4+1) - RVB(4)) * (RVB(4+1) * MVB(J+1)	YVB	19
A	+ RVB(J) * MVB(J))	YVB	20
12	Y(7) = FPPRVB(I) ** 2 * SUM / 2.	YVB	21
	RETURN	YVR	22
	END		

	SUBROUTINE POLLY(N,BBS,REL,AN,AA)	POLLY 1
	IMPLICIT REAL*8 (A-H,O-Z)	POLLY 2
C	COMPLEX ROOTS OF A POLYNOMIAL BAIRSTOWS METHOD	POLLY 3
	DIMENSION A(30),AN(60),C(26),ABAR(26),B(30),AA(30)	POLLY 4
	III=1	POLLY 5
	7 NP1=N+1	POLLY 6
	NP1=N+2	POLLY 7
	DO 60 I=1,NP1	POLLY 8
	LLL=NP1-I	POLLY 9
601	A(I)=AA(LLL)	POLLY 10
13	DO 14 K=1,NP1	POLLY 11
14	ABAR(K)=A(K)	POLLY 12
	ABSSQ=BBS*BBS	POLLY 13
	RELSQ=REL*REL	POLLY 14
	NBAR=N	POLLY 15
	B(1)=A(1)	POLLY 16
	C(1)=A(1)	POLLY 17
15	IF(NBAR-2)200,210,17	POLLY 18
17	P1=.2	POLLY 19
	Q1=.1	POLLY 20
18	ITER=0	POLLY 21
19	P1=P1*5.	POLLY 22
	Q1=Q1*10.	POLLY 23
33	P=P1	POLLY 24
	Q=Q1	POLLY 25
	NBP1=NBAR+1	POLLY 26
34	L=1	POLLY 27
	LAST=NBAR	POLLY 28
	DTFST=9.99D36	POLLY 29
C	BAIRSTOW ITERATION	POLLY 30
37	B(2)=ABAR(2)-P*B(1)	POLLY 31
	DO 40 K=3,NBP1	POLLY 32
40	B(K)=ABAR(K)-P*B(K-1)-Q*B(K-2)	POLLY 33
45	C(2)=B(2)-P*C(1)	POLLY 34
	DO 50 K=3, LAST	POLLY 35
50	C(K)=B(K)-P*C(K-1)-Q*C(K-2)	POLLY 36
	C(LAST)=C(LAST)-B(LAST)	POLLY 37
	D=C(LAST-1)*C(LAST-1)-C(LAST)*C(LAST-2)	POLLY 38
	DSQR=D*D	POLLY 39
	IF(DSQR-1.D-36)19,19,60	POLLY 40
60	DELP=(B(LAST)*C(LAST-1)-B(LAST+1)*C(LAST-2))/D	POLLY 41
	DELQ=(B(LAST+1)*C(LAST-1)-B(LAST)*C(LAST))/D	POLLY 42
C	TEST FOR CONVERGENCE	POLLY 43
	RELP=DELP/P	POLLY 44
	RELQ=DELQ/Q	POLLY 45
	RELPS=RELP*RELP	POLLY 46
	RELQS=RELQ*RELQ	POLLY 47
	DELSQ=RELPS+RELQS	POLLY 48
	P=P+DELP	POLLY 49
	Q=Q+DELQ	POLLY 50
	IF(RELPS-RELSQ)70,70,65	POLLY 51
65	IF(DELP*DELP-ABSSQ)70,70,80	POLLY 52
70	IF(RELQS-RELSQ)120,120,75	POLLY 53
75	IF(DELQ*DELQ-ABSSQ)120,120,80	POLLY 54
80	GO TO (90,100),L	POLLY 55

90	ITER=ITER+1	POLLY 56
	IF(250-ITER)310,37,37	POLLY 57
100	IF(DTEST-DELSQ)34,34,110	POLLY 58
110	DTEST=DELSQ	POLLY 59
	R(2)=A(2)-P*B(1)	POLLY 60
	DO 115 K=3,NP1	POLLY 61
115	R(K)=A(K)-P*B(K-1)-Q*B(K-2)	POLLY 62
	GO TO 45	POLLY 63
C	ITERATION HAS CONVERGED	POLLY 64
120	GO TO (130,140),L	POLLY 65
130	L=2	POLLY 66
	LAST=N	POLLY 67
	GO TO 110	POLLY 68
C	FACTOR OUT QUADRATIC	POLLY 69
140	NBAR=NBAR-2	POLLY 70
	NBP1=NBAR+1	POLLY 71
	ABAR(2)=ABAR(2)-P*ABAR(1)	POLLY 72
	DO 150 K=3,NBP1	POLLY 73
150	ABAR(K)=ABAR(K)-P*ABAR(K-1)-Q*ABAR(K-2)	POLLY 74
	GO TO 250	POLLY 75
C	SOLVE LINEAR EQUATION	POLLY 76
200	NBAR=NBAR-1	POLLY 77
	R1=-ABAR(2)/ABAR(1)	POLLY 78
	R2=0.	POLLY 79
	GO TO 262	POLLY 80
C	NORMALIZE QUADRATIC	POLLY 81
210	P=ABAR(2)/ABAR(1)	POLLY 82
	Q=ABAR(3)/ABAR(1)	POLLY 83
	NBAR=NBAR-2	POLLY 84
C	SOLVE NORMALIZED QUADRATIC	POLLY 85
250	R1=-P/2.	POLLY 86
	C1=R1*R1-Q	POLLY 87
	IF(C1)270,280,260	POLLY 88
260	C1=DSQRT(C1)	POLLY 89
	R2=R1-C1	POLLY 90
	R1=R1+C1	POLLY 91
262	C1=0.	POLLY 92
	GO TO 290	POLLY 93
270	C1=-C1	POLLY 94
	C1=DSQRT(C1)	POLLY 95
280	R2=R1	POLLY 96
290	C2=-C1	POLLY 97
	AN(III)=C1	POLLY 98
	AN(III+1)=R1	POLLY 99
	AN(III+2)=C2	POLLY100
	AN(III+3)=R2	POLLY101
	III=III+4	POLLY102
	IF(NBAR-1)4,200,15	POLLY103
C	SPECIAL CONDITIONS	POLLY104
310	WRITE (6,600)	POLLY105
600	FORMAT(IX,50HNO CONVERGENCE IN 250 ITERATIONS ,POLLY HAS SPOKEN)	POLLY106
4	CONTINUE	POLLY107
	RETURN	POLLY108
	END	

	SUBROUTINE SETIT(LGO,M,NV,REB,X,Y,UC,PRESS,GRAD,DELT,DISP,THETA,VISSETUP	1
	ISC,MTRAN)	SETUP 2
C		SETUP 3
C	SUBROUTINE FOR CALCULATION OF BOUNDARY LAYER THICKNESS,	SETUP 4
C	DISPLACEMENT THICKNESS, MOMENTUM THICKNESS AND EDDY VISCOSITY.	SETUP 5
C		SETUP 6
	DIMENSION X(300),Y(100),UC(100,3),VISC(100,2),GRAD(100)	SETUP 7
	RTR=SQRT(REB)	SETUP 8
	NY = NV + 2	SETUP 9
	UEDGE = .995*UC(NY,1)	SETUP 10
	DO 10 N=1,NV	SETUP 11
	IF(UEDGE-UC(N+1,1)) 41,41,10	SETUP 12
41	NDELT = N	SETUP 13
	GO TO 20	SETUP 14
10	CONTINUE	SETUP 15
20	DELT = Y(NDELT)+(UEDGE-UC(NDELT,1))*(Y(NDELT+1)-Y(NDELT))/(UC(NDELT	SETUP 16
	Y+1,1)-UC(NDELT,1))	SETUP 17
	SUM = 0.	SETUP 18
	DO 50 N=2,NY	SETUP 19
50	SUM = SUM+(Y(N)-Y(N-1))*(UC(N,1)+UC(N-1,1))	SETUP 20
	DISP = (Y(NY)-.5*SUM/UC(NY,1))/RTR	SETUP 21
	SUM = 0.	SETUP 22
	UEDGE = UC(NY,1)	SETUP 23
	DO 60 N=2,NY	SETUP 24
60	SUM = SUM+(Y(N)-Y(N-1))*(UEDGE-UC(N,1))*UC(N,1)+(UEDGE-UC(N-1,1)	SETUP 25
	1*UC(N-1,1))	SETUP 26
	THETA = .5*SUM/(RTR*UEDGE**2)	SETUP 27
	IF(LGO) 53,53,56	SETUP 28
53	NVPI=NV+1	SETUP 29
	EASE = 1.	SETUP 30
	IF(M-MTRAN) 31,32,32	SETUP 31
32	IF(MTRAN+5-M) 31,31,33	SETUP 32
33	EASE = (X(M)-X(MTRAN))/(X(MTRAN+5)-X(MTRAN))	SETUP 33
31	CONTINUE	SETUP 34
	INNER=0	SETUP 35
	FAC1 = .16*RTR*EASE	SETUP 36
	FAC2 = .0168*UEDGE*DISP*REB*EASE	SETUP 37
	FFAC1 = -RTR/26.	SETUP 38
	EFAC2 = PRESS/RTR	SETUP 39
	TAUW = GRAD(1)/RTR	SETUP 40
	DO 160 N=2,NVPI	SETUP 41
	ALTER = 1.+FAC2/(1.+5.5*(Y(N)/DELT)**6)	SETUP 42
	IF(INNER) 402,401,402	SETUP 43
402	VISC(N,1)=ALTER	SETUP 44
	GO TO 160	SETUP 45
401	CONTINUE	SETUP 46
	TAUMY=TAUW-Y(N)*EFAC2	SETUP 47
	IF(TAUMY) 701,701,702	SETUP 48
701	VISC(N,1)=1.	SETUP 49
	GO TO 703	SETUP 50
702	EX=Y(N)*EFAC1*SQRT(TAUMY)	SETUP 51
	VISC(N,1) = 1.+FAC1*Y(N)*Y(N)*ABS(GRAD(N))*((1.-EXP(EX))**2	SETUP 52
703	IF(VISC(N,1)-ALTER) 160,160,521	SETUP 53
521	VISC(N,1)=ALTER	SETUP 54
	INNER=1	SETUP 55

160	CONTINUE	SETUP 56
	SAVE=1.	SETUP 57
	DO 162 N=2,NV	SETUP 58
	RAVE=VISC(N,1)	SETUP 59
	VISC(N,1)=(VISC(N+1,1)+RAVE+SAVE)/3.	SETUP 60
162	SAVE=RAVE	SETUP 61
56	CONTINUE	SETUP 62
	RETURN	SETUP 63
	END	

	SLROUTINE MIXER(FPRES,PREC,UINF,UDOT,THICK,NF,XBSIG,NSIG,INDT,DELMIXER	1
	11,THET1,REB,USEP,X4,CP4)	MIXER 2
	DIMENSION FPRES(100),THICK(24),XBSIG(100)	MIXER 3
	FCAP(X)=-19.556*X+107.535*X*X-336.33*X**3+508.1*X**4-295.96*X**5	MIXER 4
	UI1(X)=-.46532*X+.68425*X*X-.45293*X**3+.6592*X**4	MIXER 5
	UI2(X)=-.045929*X-1.91615*X*X+2.91843*X**3-5.42125*X**4	MIXER 6
	DIST=.5*(XBSIG(2)-XBSIG(1))	MIXER 7
	XSEP=XBSIG(1)-DIST	MIXER 8
	XATT=XBSIG(NSIG)+DIST	MIXER 9
C		MIXER 10
C	IF INDT IS NONZERO, THE BOUNDARY LAYER IS TURBULENT	MIXER 11
C	AT SEPARATION.	MIXER 12
C		MIXER 13
	CALL H4X4(INDT,XSEP,DEL1,THET1,XATT,REB,USEP,X3,H3,X4,H4)	MIXER 14
	IF (XSEP-1.) 24,25,25	MIXER 15
25	CP4=0.	MIXER 16
	GO TO 27	MIXER 17
24	URAT=EXP(-.08712-UI1(H4)-.24723*(.3255+UI2(H4)))	MIXER 18
	CP4=1.-(1.-PREC)/URAT**2	MIXER 19
	DEADL=XATT-XSEP	MIXER 20
	IF (DEADL-2.) 5,6,6	MIXER 21
5	G=(.5*DEADL)**2	MIXER 22
	GO TO 7	MIXER 23
6	G=1.	MIXER 24
7	CP4=PREC+(CP4-PREC)*(1.-G*XSEP)	MIXER 25
27	CONTINUE	MIXER 26
	COEF=(PREC-CP4)/(XATT-X4)	MIXER 27
	CZ=2.*UDOT/UINF	MIXER 28
	C2=-2.*UINF	MIXER 29
	DO 20 M=1,NSIG	MIXER 30
	SUM=0.	MIXER 31
	COUNT=0.	MIXER 32
	X=XBSIG(M)	MIXER 33
	IF (X-1.) 2,2,3	MIXER 34
2	THETA = ARCT(X)	MIXER 35
	TANT = SIN(.5*THETA)/COS(.5*THETA)	MIXER 36
	CI = -CZ*(1.-COS(THETA))	MIXER 37
	DO 10 N=1,NF	MIXER 38
	COUNT=COUNT+1.	MIXER 39
	ANGLE=COUNT*THETA	MIXER 40
10	SUM=SUM+THICK(N)*(CI*COS(ANGLE)+C2*(COUNT*TANT*SIN(ANGLE)-C)S(ANGL	MIXER 41
	1E)))	MIXER 42
	SUM=SUM-.5*CZ*THICK(1)	MIXER 43
	GO TO 35	MIXER 44
3	CI=CZ*(1.-X)	MIXER 45
	XRAD=1./(X+SQRT(X*X-1.))	MIXER 46
	CI=CZ*(X-1.)	MIXER 47
	RF=SQRT((X-1.)/(X+1.))	MIXER 48
	SUM=THICK(1)*XRAD*(C2*(RF-1.)-CZ*(1.-.5*XRAD))	MIXER 49
	FRAD=XRAD	MIXER 50
	COUNT=1.	MIXER 51
	DO 30 N=2,NF	MIXER 52
	COUNT=COUNT+1.	MIXER 53
	FRAD=FRAD*XRAD	MIXER 54
30	SUM=SUM+THICK(N)*FRAD*(C2*(COUNT*RF-1.)+CI)	MIXER 55

35 CP=CP4  
IF (X-X4) 55,50,50  
50 CP=CP+(X-X4)\*COEF  
55 CONTINUE  
FPRES(M)=-UINF\*CP+SUM  
20 CONTINUE  
RETURN  
END

MIXER 56  
MIXER 57  
MIXER 58  
MIXER 59  
MIXER 60  
MIXER 61  
MIXER 62  
MIXER 63

	SUBROUTINE BU88(DEL1,THET1,REB,XC1,U1,XC5,DCP,DEL5,X,XC,MX,NZ,X5,UBUB3	1
15,UE,ALTC,RENFL,USTOP)		2
DIMENSION X(300),XC(300),UE(300,3)		3
FCAP(X)=-19.556*X+107.535*X*X-336.33*X**3+508.1*X**4-295.26*X**5		4
UI1(X)=-.46532*X+.68425*X*X-.45293*X**3+.6592*X**4		5
UI2(X)=-.045929*X-1.91615*X*X+2.91843*X**3-5.42125*X**4		6
FDEL1(X)=EXP(2.5773-.34252*X-.4379*X*X-.076511*X**3-.0039707*X**4)		7
FAICH(X)=EXP(-3.7481+.038772*X+.41967*X*X+.071046*X**3+.0032162*X**4)		8
DEL1(X)=-.045929*ALOG(X)-3.9242*X+.54535*X*X-1.39147*X**3-11.8425*X**4		10
25 FORMAT(1H1,44X,31H ANALYSIS OF LEADING-EDGE BUBBLE////34X,1HX,19X,10H		12
1HU,19X,1HH,18X,4H DISP/)		13
30 FORMAT(20X,4F20.5)		14
MOUT=6		15
H1=.25		16
H5=.429		17
DO 5 M=NZ,MX		18
IF(XC1-XC(M)) 4,4,5		19
4 M1=M		20
GO TO 6		21
5 CONTINUE		22
6 X1=X(M1-1)+X(M1)-X(M1-1))*X(XC1-XC(M1-1))/(XC(M1)-XC(M1-1))		23
X4=X1+RENFL/(U1*REB)		24
ARG=ALOG((X4-X1)/(REB*DEL1*DEL1*U1))		25
H4=.25*FAICH(ARG)		26
DEL4=.53*FDEL1(ARG)*DEL1		27
X5=X4+10.5*DEL4*(1.-(H4/.429)**2)		28
IF(U1-USTOP) 41,41,40		29
40 ALTL=ALTC*DEL1		30
IF(X5-X1.LT.ALTL) X5=X1+ALTL		31
41 URAT=EXP(-.08712-UI1(H4)-.24723*(.3255+UI2(H4)))		32
DCP=U1*U1*(1.-URAT**2)		33
DRAT=EXP(-2.24374-FCAP(H4)+.24723*(2.0214+DEL1(H4)))		34
DEL5=DRAT*DEL4		35
DO 7 M=NZ,MX		36
IF(X5-X(M)) 16,16,7		37
16 M5=M		38
GO TO 8		39
7 CONTINUE		40
8 FACT=(X5-X(M5-1))/(X(M5)-X(M5-1))		41
FACT1=1.-FACT		42
XC5=XC(M5-1)*FACT1+XC(M5)*FACT		43
U5=UE(M5-1,1)*FACT1+UE(M5,1)*FACT		44
WRITE(MOUT,25)		45
WRITE(MOUT,30) X1,U1,H1,DEL1		46
WRITE(MOUT,30) X4,U1,H4,DEL4		47
WRITE(MOUT,30) X5,U5,H5,DEL5		48
RETURN		49
END		50



	SUBROUTINE YSET(R,A,NY,Y)	YSET	1
	DIMENSION Y(100)	YSET	2
	RP1=1.+R	YSET	3
	Y(1)=0.	YSET	4
	Y(2)=A	YSET	5
	DO 10 N=3,NY	YSET	6
10	Y(N)=RP1*Y(N-1)-R*Y(N-2)	YSET	7
	RETURN	YSET	8
	END	YSET	9

	SUBROUTINE H4X4(INDT,X1,DEL1,THET1,X5,REB,U1,X3,H3,X4,H4)	H4X4	1
	CURLF(H)=26.703/H+305.03*ALOG(H)-2111.3*H+3327.8*H*H-2403.9*H**3	H4X4	2
	FDEL1(X)=EXP(2.5773-.34252*X-.4379*X*X-.076511*X**3-.0039707*X**4)	H4X4	3
	FAICH(X)=EXP(-3.7481+.038772*X+.41967*X*X+.071046*X**3+.0032162*X**H4X4	H4X4	4
	1*4)	H4X4	5
10	FORMAT(/20X,54HA SOLUTION FOR X4 COULD NOT BE OBTAINED IN 1000 TRH4X4	H4X4	6
	IALS)	H4X4	7
	MOUT=6	H4X4	8
C		H4X4	9
C	IF INDT IS NONZERO, THE BOUNDARY LAYER IS TURBULENT	H4X4	10
C	AT SEPARATION.	H4X4	11
C		H4X4	12
	IF(INDT) 2,5,2	H4X4	13
2	H3=THET1/DEL1	H4X4	14
	X3=X1	H4X4	15
	DEL3=DEL1	H4X4	16
	GO TO 20	H4X4	17
5	X3=X1+5.F4/(U1*REB)	H4X4	18
	ARG=ALOG((X3-X1)/(REB*DEL1*DEL1))	H4X4	19
	H3=THET1*FAICH(ARG)/DEL1	H4X4	20
	DEL3=.58*FDEL1(ARG)*DEL1	H4X4	21
	IF(X3-X5) 20,15,15	H4X4	22
15	H4=.429	H4X4	23
	X4=X5	H4X4	24
	GO TO 50	H4X4	25
20	CONTINUE	H4X4	26
	IGO=0	H4X4	27
	DIST=X5-X1	H4X4	28
	UNDER=0.	H4X4	29
	H4=H3+H3	H4X4	30
	COEF1=DEL3*H3	H4X4	31
	COEF2=10.5*DEL3*H3	H4X4	32
	SUB=X3-COEF1*CURLF(H3)	H4X4	33
95	OVER=H4	H4X4	34
	H4=.5*(H4+UNDER)	H4X4	35
	X4=CURLF(H4)*COEF1+SUB	H4X4	36
	ALTER=X5-COEF2*(1.-(H4/.429)**2)/H4	H4X4	37
	IGO=IGO+1	H4X4	38
	IF(X4-ALTER) 41,50,42	H4X4	39
41	IF(IGO-1000) 95,61,61	H4X4	40
42	IF(ABS(X4-ALTER)/DIST-.001) 50,50,43	H4X4	41
43	UNDER=H4	H4X4	42
	H4=.5*(OVER+H4)	H4X4	43
	X4=CURLF(H4)*COEF1+SUB	H4X4	44
	ALTER=X5-COEF2*(1.-(H4/.429)**2)/H4	H4X4	45
	IGO=IGO+1	H4X4	46
	IF(X4-ALTER) 52,50,51	H4X4	47
51	IF(IGO-1000) 43,61,61	H4X4	48
52	IF(ABS(X4-ALTER)/DIST-.001) 50,50,95	H4X4	49
61	H4=.429	H4X4	50
	X4=X5	H4X4	51
	WRITE(MOUT,10)	H4X4	52
50	CONTINUE	H4X4	53
	RETURN	H4X4	54
	END	H4X4	55

	SUBROUTINE SETSX(NSP1,XSEP,XATT,XSIG,ANGLE)	SETSX 1
	DIMENSION XSIG(100)	SETSX 2
	A=.5*(XSEP+XATT)	SETSX 3
	B=.5*(XATT-XSEP)	SETSX 4
	ARG=0.	SETSX 5
	DO 5 N=1,NSP1	SETSX 6
	XSIG(N)=A-B*COS(ARG)	SETSX 7
5	ARG=ARG+ANGLE	SETSX 8
	RETURN	SETSX 9
	END	SETSX 10

	FUNCTION ARCT(X)	ARCT	1
	PI=3.14159	ARCT	2
	IF (ABS(X)-1.E-6) 1,2,2	ARCT	3
1	ARCT=.5*PI	ARCT	4
	GO TO 6	ARCT	5
2	IF (X+.99999) 3,4,4	ARCT	6
3	ARCT=PI	ARCT	7
	GO TO 6	ARCT	8
4	ARCT=ATAN(SQRT(1.-X*X)/X)	ARCT	9
	IF (ARCT) 5,6,6	ARCT	10
5	ARCT=ARCT+PI	ARCT	11
6	CONTINUE	ARCT	12
	RETURN	ARCT	13
	END	ARCT	14

FUNCTION GAM1(ACAP,DXI,PI)	GAM1	1
DIMENSION ACAP(30,3)	GAM1	2
GAM1=PI*(-1.5*ACAP(1,1)-.75*ACAP(2,1)+2.*ACAP(1,2)+ACAP(2,2)-.5*ACAP(1,3)-.25*ACAP(2,3))/DXI	GAM1	3
RETURN	GAM1	4
END	GAM1	5
	GAM1	6

	FUNCTION FB(X1,X2,X3,Y)	FB	1
	D1=1./((X2-X1)	FB	2
	D2=1./((X3-X2)	FB	3
	T1=ABS(Y-X1)	FB	4
	T2=ABS(Y-X2)	FB	5
	T3=ABS(Y-X3)	FB	6
	EPS=1.E-6	FB	7
	IF(T1-EPS) 2,3,3	FB	8
2	F1=0.	FB	9
	F2=ALOG(T2)	FB	10
	F3=ALOG(T3)	FB	11
	GO TO 10	FB	12
3	F1=ALOG(T1)	FB	13
	IF(T2-EPS) 4,5,5	FB	14
4	F2=0.	FB	15
	F3=ALOG(T3)	FB	16
	GO TO 10	FB	17
5	F2=ALOG(T2)	FB	18
	IF(T3-EPS) 6,7,7	FB	19
6	F3=0.	FB	20
	GO TO 10	FB	21
7	F3=ALOG(T3)	FB	22
10	FB=((Y-X1)*F1*D1+((D1+D2)*(X2-Y)*F2+(Y-X3)*F3*D2)/3.14159	FB	23
	RETURN	FB	24
	END	FB	25

	SUBROUTINE EGAMI (NU,NG,A,B,XSEP,XATT,GAMMA,Y,GI)	EGAMI 1
	DIMENSION A(30,3)	EGAMI 2
	SINT=SQRT(1.-Y*Y)	EGAMI 3
	THETA=ARCT(Y)	EGAMI 4
	SUM=0.	EGAMI 5
	CCUNT=1.	EGAMI 6
	DO 6 N=2,NG	EGAMI 7
	CCUNT=COUNT+1.	EGAMI 8
6	SUM=SUM+A(N+1,NU)*(SIN((COUNT+1.)*THETA)/(COUNT+1.)-SIN((COUNT-1.)*THETA)/(COUNT-1.))	EGAMI 9
	GI=(3.14159-THETA+SINT)*(A(1,NU)+.5*A(2,NU))+.5*SUM-.25*GAMMA*(1.+EGAMI 11	EGAMI 10
	1Y)*SINT*SINT	EGAMI 12
	IF(Y-XATT) 8,8,7	EGAMI 13
7	DIFF=1.-XATT	EGAMI 14
	IF(DIFF-1.E-6) 8,8,9	EGAMI 15
9	GI=GI+2.*B*DIFF**(-1.5)*SQRT((XATT-XSEP)*(1.-Y)*(Y-XATT))	EGAMI 16
8	CONTINUE	EGAMI 17
	RETURN	EGAMI 18
	END	EGAMI 19

	SUBROUTINE ESIGI (NU,AX,XS,B,Y,SI)	ESIGI	1
	DIMENSION XS(100),B(100,3)	ESIGI	2
	SUM=0.	ESIGI	3
	DC 10 I=2,NX	ESIGI	4
10	SUM=SUM+B(I,NU)*GA(XS(I-1),XS(I),XS(I+1),Y)	ESIGI	5
	SI=B(I,NU)*RINT(XS(1),XS(NX+1),Y)+SUM	ESIGI	6
	RETURN	ESIGI	7
	END	ESIGI	8



```
FUNCTION GB(X1,X2,X3,X)  
GB=ABINT(X1,X2,X)-ABINT(X3,X2,X)  
GB=GB/3.14159  
RETURN  
END
```

GB	1
GB	2
GB	3
GB	4
GB	5

	FUNCTION ABINT(A,B,X)	ABINT 1
	ARGA=ABS(X-A)	ABINT 2
	ARGB=ABS(X-B)	ABINT 3
	COEF=2.*(B-A)	ABINT 4
	AP1=A+1.	ABINT 5
	BP1=B+1.	ABINT 6
	IF (ARGA-1.E-6) 2,3,3	ABINT 7
2	CA=0.	ABINT 8
	GO TO 5	ABINT 9
3	CA=ALOG(ARGA)	ABINT 10
	IF (ARGB-1.E-6) 4,5,5	ABINT 11
4	CB=0.	ABINT 12
	GO TO 6	ABINT 13
5	CB=ALOG(ARGB)	ABINT 14
6	ABINT=(CA-.5)*ARGA**2-(CB-.5)*ARGB**2-(ALOG(AP1)-.5)*AP1**2+(ALOG(BP1)-.5)*BP1**2-COEF*((X-B)*(CB-1.)+BP1*(ALOG(BP1)-1.))	ABINT 15
	ABINT=ABINT/COEF	ABINT 16
	RETURN	ABINT 17
	END	ABINT 18
		ABINT 19

	FUNCTION BINT(XS,XZ,X)	BINT	1
	RTS=SQR(1.+XS)	BINT	2
	RTZ=SQR(1.+XZ)	BINT	3
	BINT=-1.-X+RTS*RTZ	BINT	4
	IF(XZ-X) 2,3,3	BINT	5
2	RTSX=SQR(X-XS)	BINT	6
	RTZX=SQR(X-XZ)	BINT	7
	BINT=BINT+(XZ-XS)*ALOG((RTSX+RTZX)/(RTS+RTZ))+RTSX*RTZX	BINT	8
	GO TO 50	BINT	9
3	IF(X-XS) 5,5,4	BINT	10
4	BINT=BINT+(XZ-XS)*ALOG(SQR(XZ-XS)/(RTS+RTZ))	BINT	11
	GO TO 50	BINT	12
5	RTSX=SQR(XS-X)	BINT	13
	RTZX=SQR(XZ-X)	BINT	14
	BINT=BINT+(XZ-XS)*ALOG((RTSX+RTZX)/(RTS+RTZ))-RTSX*RTZX	BINT	15
50	CONTINUE	BINT	16
	RETURN	BINT	17
	END	BINT	18

	SUBROUTINE SCAL(SBL, NSBL, FRZ, ARR, RDBR)	SCAL	1
	DIMENSION SBL(300)	SCAL	2
	DELZ=FRZ*RDBR	SCAL	3
	EN=ARR/FRZ	SCAL	4
	DO 5 N=1,300	SCAL	5
	IF(EN-N) 4,4,5	SCAL	6
4	NE=N	SCAL	7
	GO TO 6	SCAL	8
5	CONTINUE	SCAL	9
6	NG=NSBL-NE	SCAL	10
	EN=FLOAT(NG)	SCAL	11
	NGM1=NG-1	SCAL	12
	SBL(1)=0.	SCAL	13
	DO 7 N=2,NE	SCAL	14
7	SBL(N)=SBL(N-1)+CELZ	SCAL	15
	FRACT=2.2/DELZ	SCAL	16
	FRAC1=FRACT-1.	SCAL	17
	R=FRACT*(1./FLOAT(NGM1))	SCAL	18
8	SAVE=R	SCAL	19
	R=R-(R*NG-FRACT*R+FRAC1)/(EN*R*NGM1-FRACT)	SCAL	20
	IF(ABS(SAVE-R)-1.E-6) 9,9,8	SCAL	21
9	RPI=R+1.	SCAL	22
	DO 10 N=NE,NSBL	SCAL	23
10	SBL(N+1)=RPI*SBL(N)-R*SBL(N-1)	SCAL	24
	RETURN	SCAL	25
	END	SCAL	26

	SUBROUTINE TERPF(XI,J,TAB1,TAB2,TAB3,TAB4,XITAB,FP)	TERPF 1
	DIMENSION TAB1(24),TAB2(24),TAB3(24),TAB4(24),XITAB(24)	TERPF 2
	IF(XI-.0001) 2,2,10	TERPF 3
2	GO TO (3,4,5,6),J	TERPF 4
3	FP=2.53-2.439*ALOG(XI)	TERPF 5
	GO TO 99	TERPF 6
4	FP=3.54-1.725*ALOG(.7071*XI)	TERPF 7
	GO TO 99	TERPF 8
5	FP=4.58-1.2195*ALOG(.5*XI)	TERPF 9
	GO TO 99	TERPF 10
6	FP=10.12	TERPF 11
	GO TO 99	TERPF 12
10	DO 12 N=1,24	TERPF 13
	IF(XI-XITAB(N)) 11,11,12	TERPF 14
11	NX=N	TERPF 15
	GO TO 13	TERPF 16
12	CONTINUE	TERPF 17
13	TX=(XI-XITAB(NX-1))/(XITAB(NX)-XITAB(NX-1))	TERPF 18
	TX1=1.-TX	TERPF 19
	GO TO (14,15,16,17),J	TERPF 20
14	FP=TX1*TAB1(NX-1)+TX*TAB1(NX)	TERPF 21
	GO TO 99	TERPF 22
15	FP=TX1*TAB2(NX-1)+TX*TAB2(NX)	TERPF 23
	GO TO 99	TERPF 24
16	FP=TX1*TAB3(NX-1)+TX*TAB3(NX)	TERPF 25
	GO TO 99	TERPF 26
17	FP=TX1*TAB4(NX-1)+TX*TAB4(NX)	TERPF 27
99	CONTINUE	TERPF 28
	RETURN	TERPF 29
	END	TERPF 30

SUBROUTINE EVAL(NNF,XX,SSC,SST,CCR,TTB,CCM,TTM)	EVAL	1
DIMENSION SSC(50),SST(50)	EVAL	2
COST = 2.*XX - 1.	EVAL	3
COSTS = COST**2	EVAL	4
IF(COSTS-1.E-8) 303,304,304	EVAL	5
304 TANT = SQRT(1./COSTS - 1.)	EVAL	6
THE = ATAN(TANT)	EVAL	7
GO TO 305	EVAL	8
303 THE = 1.5708	EVAL	9
305 IF(COST) 403,404,404	EVAL	10
403 THE = 3.14159 - THE	EVAL	11
404 ARG = 0.	EVAL	12
SUM1 = 0.	EVAL	13
SUM2 = 0.	EVAL	14
DO 551 N=1,NNF	EVAL	15
ARG = ARG + THE	EVAL	16
SUM1 = SUM1 + SSC(N)*SIN(ARG)	EVAL	17
551 SUM2 = SUM2 + SST(N)*SIN(ARG)	EVAL	18
CCR = SUM1*SIN(THE)*CCM	EVAL	19
TTB = (1. - COS(THE))*SUM2*TTM	EVAL	20
RETURN	EVAL	21
END	EVAL	22

	SUBROUTINE SIMP(NS,DX,ORD,FIND)	SIMP	1
	DIMENSION ORD(50)	SIMP	2
C	INTEGRATION OF NS + 1 EQUALLY SPACED ORDINATE VALUES	SIMP	3
C	BY SIMPSON'S RULE. NS MUST BE EVEN	SIMP	4
	SUM = 0.	SIMP	5
	DC 88 I=2,NS,2	SIMP	6
88	SUM = SUM + 2.*ORD(I-1) + 4.*ORD(I)	SIMP	7
	FIND = DX*(SUM - ORD(1) + ORD(NS+1))/3.	SIMP	8
	RETURN	SIMP	9
	END	SIMP	10

SUBROUTINE SECT(XU,YU,XL,YL,NOFF,NF,RCDBC,TMAX,CMAX,ST,SC)	SECT	1
C PROGRAM TO COMPUTE COEFFICIENTS TN AND CN OF THE FOURIER SERIES	SECT	2
C REPRESENTATION OF SECTION THICKNESS AND CAMBER DISTRIBUTIONS	SECT	3
DIMENSION XU(30),YU(30),XL(30),YL(30),YUC(30),YLC(30),ST(24),SC(24)	SECT	4
1) ,DUM(50),TBAR(50),CBAR(50)	SECT	5
12 FORMAT(////47X,26HINPUT AND COMPUTED OFFSETS/)	SECT	6
13 FORMAT(19X,4HX1/C,12X,4HYU/C,11X,5HYUC/C,20X,4HX1/C,12X,4HYL/C,11X	SECT	7
1,5HYLC/C/)	SECT	8
14 FORMAT(9X,3F16.5,8X,3F16.5)	SECT	9
NA=6	SECT	10
RNA=6.	SECT	11
RNF=FLOAT(NF)	SECT	12
MCUT=6	SECT	13
PI = 3.14159	SECT	14
DELT = PI/(2.*RNF)	SECT	15
NTC = 2*NF - 1	SECT	16
NINT = NTC + 2	SECT	17
NSIMP = NTC + 1	SECT	18
RDRC=.5*RCDBC	SECT	19
VARY = 0.	SECT	20
CB = 0.	SECT	21
TB = 0.	SECT	22
THETA = 0.	SECT	23
DO 89 K=1,NTC	SECT	24
THETA = THETA + DELT	SECT	25
X1 = .5*(1. + COS(THETA))	SECT	26
DO 90 LAM=2,NOFF	SECT	27
IF(X1-XU(LAM)) 110,90,90	SECT	28
110 YUINT = YU(LAM-1) + (X1 - XU(LAM-1))*(YU(LAM) - YU(LAM-1))/(XU(LAM	SECT	29
1) - XU(LAM-1))	SECT	30
GO TO 111	SECT	31
90 CONTINUE	SECT	32
111 DO 80 LAM=2,NOFF	SECT	33
IF(X1-XL(LAM)) 210,80,80	SECT	34
210 YLINT = YL(LAM-1) + (X1 - XL(LAM-1))*(YL(LAM) - YL(LAM-1))/(XL(LAM	SECT	35
1) - XL(LAM-1))	SECT	36
GO TO 112	SECT	37
80 CONTINUE	SECT	38
112 TBAR(K+1) = .5*(YUINT - YLINT)	SECT	39
89 CBAR(K+1) = .5*(YUINT + YLINT)	SECT	40
TMAX = 0.	SECT	41
CMAX = 0.	SECT	42
DO 79 K = 2,NSIMP	SECT	43
IF(TBAR(K)-TMAX) 801,802,802	SECT	44
802 TMAX = TBAR(K)	SECT	45
801 IF(CBAR(K)-CMAX) 79,702,702	SECT	46
702 CMAX = CBAR(K)	SECT	47
79 CONTINUE	SECT	48
IF(CMAX-1.E-5) 1201,1202,1202	SECT	49
1201 CMAX=1.	SECT	50
1202 CONTINUE	SECT	51
IF(TMAX-1.E-5) 1140,1141,1141	SECT	52
1140 TMAX=1.	SECT	53
1141 DO 69 K=2,NSIMP	SECT	54
TBAR(K) = TBAR(K)/TMAX	SECT	55



69	CBAR(K) = CBAR(K)/CMAX	SECT 56
	TBAR(1) = 0.	SECT 57
	CBAR(1) = 0.	SECT 58
	TBAR(NINT) = 0.	SECT 59
	CBAR(NINT) = 0.	SECT 60
	TTA = TBAR(NA)	SECT 61
	TTB = TBAR(NA+1)	SECT 62
	TTC = TBAR(NA+2)	SECT 63
	TAA = DELT*(RNA-1.)	SECT 64
	TBB = TAA + DELT	SECT 65
	TCC = TBB + DELT	SECT 66
	XA = .5*COS(TAA)	SECT 67
	XB = .5*COS(TBB)	SECT 68
	XC = .5*COS(TCC)	SECT 69
	SLOPE = ((TTC-TTB)*(XB-XA)/(XC-XB) + (TTB-TTA)*(XC-XB)/(XB-XA))/(X	SECT 70
	1C-XA)	SECT 71
	THETA = 0.	SECT 72
	COSB = COS(TBB)	SECT 73
	DO 456 I=2,NA	SECT 74
	THETA = THETA + DELT	SECT 75
	COST = COS(THETA)	SECT 76
456	TBAR(I) = (SQRT(1.-COST)/(1.-COSB)**1.5)*(TTB*(1.+COST-2.*COSB)/(1	SECT 77
	1.-COSB) + .5*SLOPE*(COST-COSB))	SECT 78
	NLE = 2*NF + 1 - NA	SECT 79
	COSR1 = 1. + COS(PI-RNA*DELT)	SECT 80
	THETA = PI	SECT 81
	SINAS=SIN(RNA*DELT)**2	SECT 82
	COSAS=COS(RNA*DELT)	SECT 83
	ANG=0.	SECT 84
	DO 457 I=2,NA	SECT 85
	IND = 2*NF + 2 - I	SECT 86
	THETA = THETA - DELT	SECT 87
	COST1 = 1. + COS(THETA)	SECT 88
	ANG=ANG+DELT	SECT 89
	COEF=(SINAS-SIN(ANG)**2)/(COSR1*(COS(ANG)+COSAS))	SECT 90
457	TBAR(IND) = (SQRT(RDBC*COST1)*COEF/TMAX+TBAR(NLE)*(COST1/COSR1)**1	SECT 91
	1.5)/(2.-COST1)	SECT 92
	THETA = TAA	SECT 93
	NAPI = NA + 1	SECT 94
	DO 458 I = NAPI,NLE	SECT 95
	THETA = THETA + DELT	SECT 96
458	TBAR(I) = TBAR(I)/(1.-COS(THETA))	SECT 97
	THETA = 0.	SECT 98
	DO 459 I=2,NSIMP	SECT 99
	THETA = THETA + DELT	SECT 100
459	CBAR(I) = CBAR(I)/SIN(THETA)	SECT 101
	RKK = 0.	SECT 102
	DO 59 K=1,NF	SECT 103
	RKK = RKK + 1.	SECT 104
	THETA = 0.	SECT 105
	DO 777 I=1,NINT	SECT 106
	DUM(I) = TBAR(I)*SIN(THETA*RKK)	SECT 107
777	THETA = THETA + DELT	SECT 108
	CALL SIMP(NSIMP,DELT,DUM,VARY)	SECT 109
	SY(K) = 2.*VARY/PI	SECT 110

THETA = 0.	SECT 111
DO 888 I=1,NINT	SECT 112
DUM(I) = CBAR(I)*SIN(THETA*RKK)	SECT 113
888 THETA = THETA + DELT	SECT 114
CALL SIMP(NSIMP,DELT,DUM,VARY)	SECT 115
59 SC(K) = 2.*VARY/PI	SECT 116
DO 969 I=1,NOFF	SECT 117
X = XU(I)	SECT 118
CALL EVAL(NF,X,SC,ST,CB,TB,CMAX,TMAX)	SECT 119
569 YUC(I) = CB + TB	SECT 120
DO 869 I=1,NOFF	SECT 121
X = XL(I)	SECT 122
CALL EVAL(NF,X,SC,ST,CB,TB,CMAX,TMAX)	SECT 123
869 YLC(I) = CB - TB	SECT 124
SUM1 = 0.	SECT 125
COUNT = 0.	SECT 126
DO 699 I=1,NF	SECT 127
COUNT = COUNT + 1.	SECT 128
699 SUM1 = SUM1 - ST(I)*COUNT*(-1.)**I	SECT 129
RCDRC = 8.*(TMAX*SUM1)**2	SECT 130
RCDRC=2.*RCDRC	SECT 131
TMAX=2.*TMAX	SECT 132
CMAX=2.*CMAX	SECT 133
WRITE(MOUT,12)	SECT 134
WRITE(MOUT,13)	SECT 135
WRITE(MOUT,14) (XU(I),YU(I),YUC(I),XL(I),YL(I),YLC(I),I=1,NOFF)	SECT 136
RETURN	SECT 137
END	SECT 138

SUBROUTINE CORDX(NSBL,NZ,RDBB,SBL,X,XC)		CORDX 1
C		CORDX 2
C	BOUNDARY LAYER COORDINATES AND CORRESPONDING CHORDAL	CORDX 3
C	COORDINATES ARE COMPUTED HERE.	CORDX 4
C		CORDX 5
	DIMENSION SBL(300),X(300),XC(300)	CORDX 6
336	FORMAT(/10X,31HITERATION TO COMPUTE XC FOR M =15,32H DID NOT CONVCORDX 7	
	ERGE IN 1000 STEPS.)	CORDX 8
337	FORMAT(1H1,25X,1HM,20X,1HS,25X,1HX,24X,2HXC//)	CORDX 9
338	FORMAT(22X,I5,3E25.5)	CORDX 10
	MOUT=6	CORDX 11
	MX = NSBL + NZ - 1	CORDX 12
	RZERO = RDBB/2.	CORDX 13
	XC(NZ) = -1.	CORDX 14
	DO 255 M=1,NZ	CORDX 15
	MM = NZ + 1 - M	CORDX 16
255	X(M) = SBL(NZ) - SBL(MM)	CORDX 17
	DO 256 M=NZ,MX	CORDX 18
	MM = M + 1 - NZ	CORDX 19
256	X(M) = SBL(NZ) + SBL(MM)	CORDX 20
	DO 257 M=1,MX	CORDX 21
	IF(NZ-M) 333,257,335	CORDX 22
333	K = M + 1 - NZ	CORDX 23
	GO TO 334	CORDX 24
335	K = NZ - M + 1	CORDX 25
334	XC(M) = -1. + SBL(K)	CORDX 26
	IF(SBL(K)-RZERO) 341,341,342	CORDX 27
341	XC(M) = -1. + SBL(K)**2/(4.*RZERO)	CORDX 28
342	CONTINUE	CORDX 29
	DO 258 L=1,1000	CORDX 30
	SAVE = XC(M)	CORDX 31
	CALC1 = SQRT((1.+XC(M))/RZERO)	CORDX 32
	CALC2 = SQRT(1.+(1.+XC(M))/RZERO)	CORDX 33
	XC(M)=XC(M)+CALC1*(SBL(K) - RZERO*(CALC1*CALC2+ALOG(CALC1+CALC2))	CORDX 34
	1)/CALC2	CORDX 35
	IF(ABS(SAVE-XC(M))-1.E-6) 257,257,258	CORDX 36
258	CONTINUE	CORDX 37
	WRITE(MOUT,336) M	CORDX 38
257	CONTINUE	CORDX 39
	WRITE(MOUT,337)	CORDX 40
	DO 264 M=1,MX	CORDX 41
	IF(NZ-M) 261,261,262	CORDX 42
262	K=NZ-M+1	CORDX 43
	GO TO 263	CORDX 44
261	K=M+1-NZ	CORDX 45
263	WRITE(MOUT,338) M,SBL(K),X(M),XC(M)	CORDX 46
264	CONTINUE	CORDX 47
	RETURN	CORDX 48
	END	CORDX 49

	SUBROUTINE PGRAD(M,X,UE,DXI,PRESS,SA,SB,SC,SR,SS)	PGRAD 1
C		PGRAD 2
C	SUBROUTINE FOR CALCULATION OF PRESSURE GRADIENT AND	PGRAD 3
C	DERIVATIVE COEFFICIENTS.	PGRAD 4
C		PGRAD 5
	DIMENSION X(300),UE(300,3)	PGRAD 6
	D1Z=X(M+1)-X(M)	PGRAD 7
	D2Z=X(M+2)-X(M)	PGRAD 8
	D21=X(M+2)-X(M+1)	PGRAD 9
	D1M1=X(M+1)-X(M-1)	PGRAD 10
	DZM1=X(M)-X(M-1)	PGRAD 11
	XIM=D1Z/(D2Z*D21)	PGRAD 12
	ETAM=1./D1Z-1./D21	PGRAD 13
	ZETAM=D21/(D1Z*D2Z)	PGRAD 14
	PRESS = (3.*UE(M+1,1)-4.*UE(M+1,2)+UE(M+1,3))/(2.*DXI)+UE(M+1,1)*	PGRAD 15
	1XIM*UE(M+2,1)+ETAM*UE(M+1,1)-ZETAM*UE(M,1))	PGRAD 16
	SA=1./D1Z+1./D1M1	PGRAD 17
	SB=D1M1/(D1Z*DZM1)	PGRAD 18
	SC=D1Z/(D1M1*DZM1)	PGRAD 19
	SR=D1M1/DZM1	PGRAD 20
	SS=D1Z/DZM1	PGRAD 21
	RETURN	PGRAD 22
	END	PGRAD 23

	SUBROUTINE TRANS (UPRIM,PRESS,THETA,REB,UC,NY,FLAM,XFLAM,LAMQ)	TRANS 1
C		TRANS 2
C	SUBROUTINE TO TEST FOR TRANSITION IN A LAMINAR BOUNDARY LAYER.	TRANS 3
C		TRANS 4
	DIMENSION UC(100,3),FLAM(10),XFLAM(10)	TRANS 5
	F(X) = .11746 - 1.0582E-3*X - 1.1023E-4*X*X	TRANS 6
	TKAY = PRESS*REP*THETA**2/UC(NY,2)	TRANS 7
	IF(TKAY-.077) 2,2,99	TRANS 8
2	IF(ABS(TKAY)-.0701) 3,3,4	TRANS 9
3	ARG = TKAY*72.48	TRANS 10
	GO TO 5	TRANS 11
4	ARG = 0.	TRANS 12
	DO 6 N=1,1000	TRANS 13
	SAVE = ARG	TRANS 14
	ARG = ARG - (ARG*(F(ARG)**2-TKAY)/(F(ARG)*( .11746-ARG*3.1746E-3 - A	TRANS 15
	RG*ARG*5.5115E-4))	TRANS 16
	IF(ABS(1.-SAVE/ARG)-1.E-6) 7,7,6	TRANS 17
6	CONTINUE	TRANS 18
7	IF(ARG+11.) 8,8,5	TRANS 19
8	EF = 1.75	TRANS 20
	GO TO 10	TRANS 21
5	DO 15 N=1,10	TRANS 22
	IF(ARG-XFLAM(N)) 24,24,15	TRANS 23
24	NBAR = N	TRANS 24
	GO TO 16	TRANS 25
15	CONTINUE	TRANS 26
16	EF = FLAM(NBAR-1)+(ARG-XFLAM(NBAR-1))*(FLAM(NBAR)-FLAM(NBAR-1))/(X	TRANS 27
	FLAM(NBAR)-XFLAM(NBAR-1))	TRANS 28
10	B = .5*EF	TRANS 29
	A = 3.36*(UPRIM/UC(NY,2))**2	TRANS 30
	RTH = F(ARG)*(SQRT(B*B+9860.*A)-B)/A	TRANS 31
	IF(REB*THETA-RTH) 99,50,50	TRANS 32
50	LAMQ = 0	TRANS 33
99	CONTINUE	TRANS 34
	RETURN	TRANS 35
	END	TRANS 36

	SUBROUTINE CAPS(ITER,N,CAPG,CAPH,CAPJ,CAPK,SR,SS,SD,SE,SF,VISC,V,UCAPS	1
1C)		CAPS 2
	DIMENSION CAPG(100),CAPH(100),CAPJ(100),CAPK(100)	CAPS 3
	DIMENSION VISC(100,2),V(100,2),UC(100,3),SD(100),SE(100),SF(100)	CAPS 4
	IF(ITER) 4,2,4	CAPS 5
2	CAPG(N)= SR*V(N,1) - SS*V(N,2)	CAPS 6
	CAPH(N)=SR*VISC(N,1)-SS*VISC(N,2)	CAPS 7
	CAPJ(N)=SR*(SD(N)*VISC(N+1,1)+SE(N)*VISC(N,1)-SF(N)*VISC(N-1,1))-SS	CAPS 8
	1S*(SD(N)*VISC(N+1,2)+SE(N)*VISC(N,2)-SF(N)*VISC(N-1,2))	CAPS 9
	CAPK(N)= SR*UC(N,2)-SS*UC(N,3)	CAPS 10
	GO TO 6	CAPS 11
4	CAPG(N)=.5*(CAPG(N)+V(N,1))	CAPS 12
	CAPH(N)=.5*(CAPH(N)+VISC(N,1))	CAPS 13
	CAPJ(N)=.5*(CAPJ(N)+SD(N)*VISC(N+1,1)+SE(N)*VISC(N,1)-SF(N)*VISC(N	CAPS 14
	1-1,1))	CAPS 15
	CAPK(N)=.5*(CAPK(N)+UC(N,1))	CAPS 16
6	CONTINUE	CAPS 17
	RETURN	CAPS 18
	END	CAPS 19

	SUBROUTINE TERP(YIN,YBASE,VARY,NY,VALUE)	TERP	1
C		TERP	2
C	SUBROUTINE FOR DETERMINING INTERPOLATED VALUE OF THE	TERP	3
C	FUNCTION VARY AT Y = YIN.	TERP	4
C		TERP	5
	DIMENSION YBASE(100),VARY(100)	TERP	6
	IF(YIN-YBASE(NY-1)) 2,3,3	TERP	7
3	VALUE = VARY(NY)	TERP	8
	GO TO 10	TERP	9
2	DO 15 N=1,NY	TERP	10
	IF(YIN-YBASE(N)) 24,24,15	TERP	11
24	NBAR=N	TERP	12
	GO TO 16	TERP	13
15	CONTINUE	TERP	14
16	D21=YBASE(NBAR)-YBASE(NBAR-1)	TERP	15
	D31=YBASE(NBAR+1)-YBASE(NBAR-1)	TERP	16
	D32=D31-D21	TERP	17
	D3A=YBASE(NBAR+1)-YIN	TERP	18
	D2A=YBASE(NBAR)-YIN	TERP	19
	DA1=YIN-YBASE(NBAR-1)	TERP	20
	VALUE=D3A*D2A*VARY(NBAR-1)/(D21*D31)+D3A*DA1*VARY(NBAR)/(D21*D32)-	TERP	21
	1D2A*DA1*VARY(NBAR+1)/(D31*D32)	TERP	22
10	CONTINUE	TERP	23
	RETURN	TERP	24
	END	TERP	25

SUBROUTINE YDIFF(NY,ALPHA,BETA,GAMMA,DELTA,SD,SE,SF,C2,C3,C4,Y)	YDIFF	1
DIMENSION ALPHA(100),BETA(100),GAMMA(100),DELTA(100)	YDIFF	2
DIMENSION SD(100),SE(100),SF(100),Y(100)	YDIFF	3
NV=NY-2	YDIFF	4
NVPI=NV+1	YDIFF	5
DO 40 N=2,NV	YDIFF	6
ALPHA(N) = 2.*(2.*Y(N)-Y(N-1)-Y(N+1))/((Y(N+2)-Y(N-1))*(Y(N+2)-Y(N+1))	YDIFF	7
1+1))*(Y(N+2)-Y(N)))	YDIFF	8
DELTA(N) = 2.*(Y(N+2)+Y(N+1)-2.*Y(N))/((Y(N+2)-Y(N-1))*(Y(N+1)-Y(N+1))	YDIFF	9
1-1))*(Y(N)-Y(N-1)))	YDIFF	10
BETA(N) = (DELTA(N)*(Y(N)-Y(N-1))**3-ALPHA(N)*(Y(N+2)-Y(N))**3)/(Y(N+1)-Y(N))**3	YDIFF	11
GAMMA(N) = -ALPHA(N)-BETA(N)-DELTA(N)	YDIFF	12
40 CONTINUE	YDIFF	13
DO 39 N=2,NVPI	YDIFF	14
SD(N) = (Y(N)-Y(N-1))/((Y(N+1)-Y(N-1))*(Y(N+1)-Y(N)))	YDIFF	15
SE(N) = 1./(Y(N)-Y(N-1))-1./(Y(N+1)-Y(N))	YDIFF	16
SF(N) = (Y(N+1)-Y(N))/((Y(N)-Y(N-1))*(Y(N+1)-Y(N-1)))	YDIFF	17
39 CCNTINUE	YDIFF	18
C2 = Y(3)*Y(4)/(Y(2)*(Y(3)-Y(2))*(Y(4)-Y(2)))	YDIFF	19
C3 = -Y(2)*Y(4)/(Y(3)*(Y(4)-Y(3))*(Y(3)-Y(2)))	YDIFF	20
C4 = Y(2)*Y(3)/(Y(4)*(Y(4)-Y(3))*(Y(4)-Y(2)))	YDIFF	21
RETURN	YDIFF	22
END	YDIFF	23
	YDIFF	24



	SUBROUTINE ELDER(BCAP,XSIG,NSIG,UINF,ELD,Y,YMAX)	ELDER 1
	DIMENSION BCAP(100,3),XSIG(100)	ELDER 2
	BCAP(NSIG+1,1)=0.	ELDER 3
	XS=XSIG(1)	ELDER 4
	XZ=XSIG(NSIG+1)	ELDER 5
	IF(XZ-1.) 16,16,1	ELDER 6
1	DEADL=XZ-XS	ELDER 7
	YMAX=1.E-10	ELDER 8
	SUM=.5*(XSIG(2)-XS)*BCAP(2,1)	ELDER 9
	DO 10 N=2,NSIG	ELDER 10
	X=XSIG(N+1)	ELDER 11
	SUM=SUM+.5*(X-XSIG(N))*(BCAP(N+1,1)+BCAP(N,1))	ELDER 12
	IF(N-NSIG) 4,2,4	ELDER 13
2	ANGLE=1.5708	ELDER 14
	GO TO 6	ELDER 15
4	ANGLE=ATAN(SQRT((X-XS)/(XZ-X)))	ELDER 16
6	Y=SUM+BCAP(1,1)*(DEADL*ANGLE-SQRT((X-XS)*(XZ-X)))	ELDER 17
	IF(Y-YMAX) 10,10,8	ELDER 18
8	YMAX=Y	ELDER 19
10	CONTINUE	ELDER 20
	ELD=Y/YMAX	ELDER 21
	IF(ABS(ELD)-UINF) 20,20,12	ELDER 22
12	IF(ELD) 14,16,16	ELDER 23
14	ELD=-UINF	ELDER 24
	GO TO 20	ELDER 25
16	ELD=UINF	ELDER 26
20	CONTINUE	ELDER 27
	RETURN	ELDER 28
	END	ELDER 29

	SUBROUTINE REATT(UC,V,X,Y,MX,NY,RY,DRY,UE,X5,DEL5,MST,REB)	REATT 1
	DIMENSION UC(100,3),V(100,2),Y(100)	REATT 2
	DIMENSION X(300),UE(300,3)	REATT 3
	DIMENSION TAB1(24),TAB2(24),TAB3(24),TAB4(24),XITAB(24)	REATT 4
	DATA TAB1 /24.98,23.29,21.04,19.33,17.61,15.29,13.46,11.54,10.36,9.13,8.35,7.32,6.20,5.31,4.43,3.57,2.22,1.26,.66,.31,.14,.01,0.,0./	REATT 5
	DATA TAB2 /20.05,18.85,17.25,15.04,14.8,13.12,11.77,10.3,9.36,8.65,7.95,7.2,6.43,5.66,4.9,4.18,2.89,1.86,1.11,.62,.32,.04,0.,0./	REATT 6
	DATA TAB3 /16.65,15.8,14.67,13.8,12.91,11.66,10.65,9.48,8.71,8.11,7.59,7.01,6.41,5.77,5.13,4.5,3.31,2.28,1.48,.9,.51,.09,.01,0./	REATT 7
	DATA TAB4 /10.12,10.05,9.93,9.78,9.58,9.17,8.72,8.08,7.6,7.2,6.85,6.53,6.18,5.79,5.36,4.91,3.98,3.05,2.21,1.5,.95,.22,.03,0./	REATT 8
	DATA XITAB /.0001,.0002,.0005,.001,.002,.005,.01,.02,.03,.04,.05,.06,.07,.08,.09,.1,.12,.14,.16,.18,.2,.25,.3,.35/	REATT 9
3	FORMAT(///40X,23HATT REATTACHMENT, BETA =E13.5)	REATT 10
	MOUT=6	REATT 11
	RTR=SQRT(REB)	REATT 12
	UC(1,2)=0.	REATT 13
	UC(1,3)=0.	REATT 14
	V(1,1)=0.	REATT 15
	V(1,2)=0.	REATT 16
	DO 5 M=1,MX	REATT 17
	IF(X5-X(M)) 4,4,5	REATT 18
4	MST=M+2	REATT 19
	GO TO 6	REATT 20
5	CONTINUE	REATT 21
6	XA=X(MST-2)	REATT 22
	XB=X(MST-1)	REATT 23
	UA=UE(MST-2,1)	REATT 24
	UB=UE(MST-1,1)	REATT 25
	ZA=ALOG(UA*DEL5*REB)	REATT 26
	PGRAD=2.*(UA-UB)/((UA+UB)*(XB-XA))	REATT 27
	BETM2=(.0974-SQRT(DEL5*PGRAD))/(.0249+.004565*Z A)	REATT 28
	IF(BETM2-1.) 8,7,7	REATT 29
7	BETM2=1.	REATT 30
	GO TO 10	REATT 31
8	IF(BETM2-.3) 9,9,10	REATT 32
9	BETM2=.3	REATT 33
10	BETA=1.7(BETM2*BETM2)	REATT 34
	WRITE(MOUT,3) BETA	REATT 35
	AGAM=.0974*BETM2-.0249/BETA	REATT 36
	BGAM=.004565/BETA	REATT 37
	AH=1.-(5.3+3.9*BETM2)*(1.0974-.0249*BETM2)	REATT 38
	BH=BETM2*(5.3+3.9*BETM2)*.004565	REATT 39
	GAMA=AGAM-BGAM*ZA	REATT 40
	DERIV=UA*REB*EXP(-ZA)*GAMA*GAMA*(1.+BETA*(1.+AH+BH*ZA))/(AH+BH+BH*ZA)	REATT 41
	ZB=ZA+DERIV*(XB-XA)	REATT 42
	DELB=EXP(ZB)/(UB*REB)	REATT 43
	GAMB=AGAM-BGAM*ZB	REATT 44
	DELL=.35*DELB*RTR*BETM2/GAMB	REATT 45
11	IF(DELL-Y(NY-3)) 14,12,12	REATT 46
12	RY=RY+DRY	REATT 47
	CALL YSET(RY,Y(2),NY,Y)	REATT 48
	GO TO 11	REATT 49
		REATT 50
		REATT 51
		REATT 52
		REATT 53
		REATT 54
		REATT 55

14	IF(BETA-4.) 102,101,101	REATT 56
101	TERPB=1.-4./BETA	REATT 57
	INDEX=3	REATT 58
	GO TO 110	REATT 59
102	IF(BETA-2.) 104,103,103	REATT 60
103	TERPB=.5*BETA-1.	REATT 61
	INDEX=2	REATT 62
	GO TO 110	REATT 63
104	TERPB=BETA-1.	REATT 64
	INDEX=1	REATT 65
110	K=0	REATT 66
	TERP1=1.-TERPB	REATT 67
50	K=K+1	REATT 68
	GO TO (16,17,99),K	REATT 69
16	G=GAMA	REATT 70
	DELTA=DEL5	REATT 71
	UEDGE=UA	REATT 72
	L=3	REATT 73
	GO TO 18	REATT 74
17	G=GAMB	REATT 75
	DELTA=DEL8	REATT 76
	UEDGE=UB	REATT 77
	L=2	REATT 78
18	XICO=G/(DELTA*RTR*BETM2)	REATT 79
	UCOW=RTR*(UEDGE*G)**2	REATT 80
	EFCO=G/BETM2	REATT 81
	NLAM=NY	REATT 82
	DO 75 N=2,NY	REATT 83
	XI=Y(N)*XICO	REATT 84
	IF(XI-.35) 20,19,19	REATT 85
19	UC(N,L)=UEDGE	REATT 86
	GO TO 75	REATT 87
20	CALL TERPF(XI,INDEX,TAB1,TAB2,TAB3,TAB4,XITAB,FP1)	REATT 88
	INDP1=INDEX+1	REATT 89
	CALL TERPF(XI,INDP1,TAB1,TAB2,TAB3,TAB4,XITAB,FP2)	REATT 90
	FP=TERP1*FP1+TERPB*FP2	REATT 91
	UC(N,L)=UEDGE*(1.-EFCO*FP)	REATT 92
	IF(N-NLAM) 21,75,75	REATT 93
21	ALTER=UCOW*Y(N)	REATT 94
	IF(ALTER-UC(N,L)) 33,33,32	REATT 95
32	UC(N,L)=ALTER	REATT 96
	GO TO 75	REATT 97
33	NLAM=N	REATT 98
75	CONTINUE	REATT 99
	GO TO 50	REATT100
99	DO 60 K=2,3	REATT101
	SAVE2=0.	REATT102
	DO 60 N=3,NY	REATT103
	SAVE1=UC(N-1,K)	REATT104
	UC(N-1,K)=(SAVE2+SAVE1+UC(N,K))/3.	REATT105
60	SAVE2=SAVE1	REATT106
	DUDX=0.	REATT107
	COD=.5/(XB-XA)	REATT108
	DO 65 N=2,NY	REATT109
	DUDXP=COD*(UC(N,2)-UC(N,3))	REATT110

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        V(N,1)=V(N-1,1)-(Y(N)-Y(N-1))*(DUDXP+DUJDX)  
        V(N,2)=V(N,1)  
65      DUDX=DUDXP  
        RETURN  
      END
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REATT111  
REATT112  
REATT113  
REATT114  
REATT115
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SUBROUTINE ELPIT(ALPH1,ALPH2,EMI,TORF,THETZ,UINF,DXI,CMPA,CMPAS)	ELPIT 1
SAVET=ALPH1	ELPIT 2
STEP=TORF*DXI	ELPIT 3
SINS=SIN(STEP)	ELPIT 4
CGSS=COS(STEP)	ELPIT 5
CONST=2.*EMI*(UINF/TORF)**2	ELPIT 6
ALPH1=THETZ+(ALPH1-THETZ)*CGSS+ALPH2*SINS/TORF+CONST*(2.*CMPA-CMPA	ELPIT 7
1S)*(1.-CGSS)+CONST*(CMPAS-CMPA)*(SINS-STEP*CGSS)/(TORF*DXI)	ELPIT 8
ALPH2=ALPH2*CGSS-TORF*SINS*(SAVET-THETZ)+CONST*(CMPA-CMPAS)*(1.-CG	ELPIT 9
1SS)/DXI+CONST*CMPA*TORF*SINS	ELPIT 10
RETURN	ELPIT 11
END	ELPIT 12

	SUBROUTINE VWASH(BARG,H,S,NVOR,X1,UINF,VZIP,XGAM,NGPI,DXI)	VWASH 1
	DIMENSION VZIP(30),XGAM(30)	VWASH 2
	DO 10 N=1,NGPI	VWASH 3
	DIFF=XGAM(N)-X1	VWASH 4
	SUM=0.	VWASH 5
	DO 5 K=1,NVOR	VWASH 6
	SUM=SUM+DIFF/(DIFF*DIFF+H)	VWASH 7
5	DIFF=DIFF-S	VWASH 8
10	VZIP(N)=VZIP(N)+SUM*BARG	VWASH 9
	RETURN	VWASH 10
	END	VWASH 11

	SUBROUTINE WASH(XGAM,NGAM,TIME,ALPH1,ALPH2,HEAVE,AROT,FREQF,PHIH,UWASH	1
	LINE,CAMBR,NF,VZIP,MOTR,INDV)	2
	DIMENSION XGAM(30),VZIP(30),CAMBR(24)	3
	NGPI = NGAM+1	4
	ANGLE = FREQF*TIME	5
	GO TO (108,120), INDV	6
108	GO TO (110,120),MOTR	7
110	CONST = -ALPH2*COS(ANGLE)*UINF+HEAVE*COS(ANGLE+PHIH)+ALPH1*UINF	8
	FACT = -ALPH2*FREQF*SIN(ANGLE)*JINF	9
	GO TO 130	10
120	CONST=UINF*ALPH1+HEAVE	11
	FACT=-UINF*ALPH2	12
130	DO 10 M=1,NGPI	13
	X=XGAM(M)	14
	THETA = ARCT(X)	15
	SUM=0.	16
	CCUNT=0.	17
	DO 20 N=1,NF	18
	COUNT=COUNT+1.	19
20	SUM=SUM+COUNT*CAMBR(N)*CCS(COUNT*THETA)	20
	IF(M-1) 2,4,2	21
2	IF(NGPI-M) 3,4,3	22
4	SUM = SUM + SUM	23
	GO TO 50	24
3	COUNT = 0.	25
	COTT = X/SIN(THETA)	26
	DO 30 N=1,NF	27
	COUNT = COUNT+THETA	28
30	SUM=SUM+COTT*CAMBR(N)*SIN(COUNT)	29
50	VZIP(M) = UINF*SUM+CONST+FACT*(AROT-X)	30
10	CONTINUE	31
	RETURN	32
	END	33

APPENDIX B

DETERMINATION OF COUPLING PARAMETERS



# APPENDIX B

## DETERMINATION OF COUPLING PARAMETERS

The characteristic equation for the rotor blade is

$$\sum_{k=0}^3 B_{2k} \lambda^{2k} = 0$$

where

$$B_0 = f_0 - \frac{\bar{\omega}_{\beta\beta}^2 T_{\beta\theta}^2}{M_{\beta\beta} M_{\theta\theta}} - \frac{\bar{\omega}_{\beta\beta}^2 T_{\theta\theta}^2}{M_{\theta\theta} M_{\theta\theta}}$$

$$B_2 = f_2 + 2 \frac{\bar{\omega}_{\beta\beta}^2 M_{\beta\theta} T_{\beta\theta}}{M_{\beta\beta} M_{\theta\theta}} + 2 \frac{\bar{\omega}_{\beta\beta}^2 M_{\theta\theta} T_{\theta\theta}}{M_{\theta\theta} M_{\theta\theta}} - \frac{T_{\beta\theta}^2}{M_{\beta\beta} M_{\theta\theta}} - \frac{T_{\theta\theta}^2}{M_{\theta\theta} M_{\theta\theta}}$$

$$B_4 = f_4 - \frac{\bar{\omega}_{\beta\beta}^2 M_{\beta\theta}}{M_{\beta\beta} M_{\theta\theta}} - \frac{\bar{\omega}_{\beta\beta}^2 M_{\theta\theta}^2}{M_{\theta\theta} M_{\theta\theta}} + 2 \frac{M_{\beta\theta} T_{\beta\theta}}{M_{\beta\beta} M_{\theta\theta}} + 2 \frac{M_{\theta\theta} T_{\theta\theta}}{M_{\theta\theta} M_{\theta\theta}}$$

$$B_6 = 1 - \frac{M_{\beta\theta}^2}{M_{\beta\beta} M_{\theta\theta}} - \frac{M_{\theta\theta}^2}{M_{\theta\theta} M_{\theta\theta}}$$

in which

$$f_0 = \bar{\omega}_\beta^2 \bar{\omega}_\phi^2 \bar{\omega}_\theta^2$$

$$f_2 = \bar{\omega}_\beta^2 \bar{\omega}_\phi^2 + \bar{\omega}_\beta^2 \bar{\omega}_\theta^2 + \bar{\omega}_\phi^2 \bar{\omega}_\theta^2$$

$$f_4 = \bar{\omega}_\beta^2 + \bar{\omega}_\phi^2 + \bar{\omega}_\theta^2$$

The characteristic equation for the two-dimensional system is found to be

$$\sum_{k=0}^3 D_{2k} \lambda^{2k} = 0$$

where

$$D_0 = f_0 - \bar{\omega}_\phi^2 h_a a_1^2 - \bar{\omega}_\beta^2 h_b b_1^2$$

$$D_2 = f_2 - \bar{\omega}_\phi^2 g_a \bar{x} a_1 - \bar{\omega}_\beta^2 g_b \bar{x} b_1 \\ - h_a a_1^2 - h_b b_1^2$$

$$D_4 = f_4 - c_4 \bar{x}^2 - g_a \bar{x} a_1 - g_b \bar{x} b_1$$

$$D_6 = 1 - c_6 \bar{x}^2$$

in which

$$h_a = \frac{M_{\beta\beta}}{R^2 M_{\theta\theta}} \quad h_b = \frac{M_{\phi\phi}}{M_{\theta\theta}}$$

$$g_a = 2 h_a A_1$$

$$g_b = 2 h_b A_2$$

$$c_4 = \bar{\omega}_{\phi}^2 h_a A_1^2 + \bar{\omega}_{\beta}^2 h_b A_2^2$$

$$c_6 = h_a A_1^2 + h_b A_2^2$$

$$a_1 = A_1 ( \bar{\omega}_{\beta}^2 l_{s_1} + r_m \bar{\omega}_{\phi}^2 l_{s_2} ) - B \bar{\omega}_{\phi}^2 l_{s_2}$$

$$b_1 = A_2 ( \bar{\omega}_{\beta}^2 l_{s_1} + r_m \bar{\omega}_{\phi}^2 l_{s_2} ) + B \bar{\omega}_{\phi}^2 l_{s_2}$$

Equating  $D_0/D_6$  to  $B_0/B_6$ ,  $D_2/D_6$  to  $B_2/B_6$  and  $D_4/D_6$  to  $B_4/B_6$  provides three relations in the three unknowns  $\bar{x}$ ,  $l_{s_1}$ , and  $l_{s_2}$ . If  $a_1$  and  $b_1$  are eliminated, the following equation for  $\bar{x}$  is obtained:

$$(r_1 t_2 - r_2 t_1)^2 + (r_1 s_2 - r_2 s_1)(t_2 s_1 - t_1 s_2) = 0$$

where

$$r_1 = - \left[ h_a + \frac{h_b g_a^2}{g_b^2} \right] \quad r_2 = \left[ \frac{\bar{\omega}_{\phi}^2}{\bar{\omega}_{\beta}^2} - 1 \right] h_a$$

$$s_2 = ( \bar{\omega}_{\beta}^2 - \bar{\omega}_{\phi}^2 ) g_a \bar{x} , \quad s_1 = s_2 + \frac{2 h_b g_a F}{g_b^2 \bar{x}}$$

$$t_1 = (1 - c_6 \bar{x}^2) B_2/B_6 - f_2 + \bar{\omega}_{\beta}^2 F + \frac{h_b F^2}{g_b^2 \bar{x}^2}$$

$$t_2 = (1 - c_6 \bar{x}^2)(B_2 - B_0/\bar{\omega}_\beta^2)/B_6 - f_2 + \bar{\omega}_\beta^2 F + f_0/\bar{\omega}_\beta^2$$

in which

$$F = f_4 - B_4/B_6 + (B_4 c_6/B_6 - c_4) \bar{x}^2$$

With some algebraic manipulation, a polynomial of fourth degree in  $\bar{x}^2$  can be extracted from that equation. The value of  $\bar{x}$  is taken to be the square root of the smallest positive root of that polynomial. The original equations are then used to solve for  $a_1$  and  $b_1$ , from which  $l_{s1}$  and  $l_{s2}$  are readily obtained.

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